



**Synertek**  
**Systems Corporation**

**VIM  
REFERENCE  
MANUAL**



# **VIM REFERENCE MANUAL**

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SSC Pub MN-A-260006-A

First Printing: May, 1978



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# VIM-1 REFERENCE MANUAL

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\* KIM is a product of MOS Technology, Inc.



## CHAPTER 1

### INTRODUCTION TO THE VIM COMPUTER

Whether you're a teacher or a student of computer science, a systems engineer or a hobbyist, you now own one of the most versatile and sophisticated single-board computers available today. The Synertek Systems VIM-1 is an ideal introduction to the expanding world of microprocessor technology as well as a powerful development tool for design of microcomputer-based systems. Fully assembled and thoroughly tested, the VIM-1 comes equipped with a 28-key dual-function keyboard for input and a 6-digit light emitting diode (LED) display for output. All that's needed to make your computer operational is a single 5-volt power supply.

Based on the popular and reliable 6502 Central Processing Unit (CPU), the VIM-1 is designed to permit flexible solutions to a wide range of application problems. A system monitor (SUPERMON) is stored in 4K bytes of Read Only Memory (ROM) furnished with the VIM-1 so you're free to concentrate on the application itself. But should you require customized system software, sockets are provided on the board for three additional ROM or Erasable PROM (EPROM) packages that can expand total ROM to 24K bytes. And by changing connections on the jumpers that have been designed for this purpose, the VIM-1 can be set up to respond to your own system software as soon as the power is turned on.

For working with data and programs, VIM-1 comes equipped with 1K of Random Access Memory (RAM), and sockets are available on the board for plug-in expansion up to 4K. Should additional memory be required for your application, an expansion port is provided which will allow additional ROM, PROM, RAM or I/O to be attached to the system up to the 65,536 maximum addressable limit for an 8-bit microprocessor.

While the keyboard and LED display included on the VIM-1 board will be sufficient for most users, other users may require the additional storage capability of audio cassette tape or the hard copy output of an RS-232 or a teletype terminal. Not only the serial interface, but also the hardware and software necessary for control of these devices is included on the VIM-1. Adding them to your system is simply a matter of properly wiring the appropriate connectors. Similarly, VIM-1 allows an oscilloscope to be added to the system to provide a unique 32-character display under software control. (Or, with the addition of the VIM-2 KB/TV interface and a common and inexpensive Radio Frequency (RF) adapter, you can turn your television set into a video display terminal.)

And that's not all. A total of 51 active Input-Output (I/O) lines (expandable to 71 with the addition of a plug-in component) permit an almost endless variety of other peripheral devices to interface to the VIM-1, from floppy disk drives to full-ASCII keyboards and other computer systems.

Other key hardware and software features of VIM-1 include jumper-selectable and program-controlled write protection for selected areas of memory, four internal timers (expandable to six), four on-board buffers for direct control of high voltage or high current interfaces, and a debug facility that may be controlled either by a manual switch or by software. We could go on, but rather than merely list what the VIM-1 is capable of doing, let's move on to the rest of the manual and learn how to put it to work.



## CHAPTER 2

### HOW TO USE THE VIM REFERENCE MANUAL

This manual is designed both to help you get your VIM-1 running and to teach you to use it as fully as possible. Reading over the following chapter descriptions will give you an idea of how to proceed and where to look for help when you run into a problem. Although to get the most out of this manual you should read it thoroughly before attempting to operate your VIM-1, only Chapter 3 is essential before applying power and attempting simple operations.

**You should read Chapter 3 before you even unpack your VIM-1.** Following the handling instructions in that chapter will help insure that you do not inadvertently damage the microcomputer components. Chapter 3 also contains instructions for connecting the power supply, and a simple keyboard exercise to acquaint you with the VIM-1 and verify that the system is working properly. In addition, directions are provided for attaching an audio cassette recorder, teletype or any RS-232 compatible terminal to the system.

Chapter 4 provides you an overview of the hardware and software features of the VIM-1. The major Integrated Circuit (IC) devices are described, and the configuration of the various edge connectors is explained. Memory assignment is also discussed, as are the various hardware jumper options on VIM-1. A complete list of machine language and assembly language commands for the 6502 CPU is included in this chapter.

Chapter 5 provides complete operating instructions for the VIM-1. The color-coded keyboard layout is explained, the keys and their functions are defined, and you're shown how to form VIM monitor commands. Instructions for operating an audio cassette recorder, teletype terminal with paper tape unit, and RS-232 terminal are included with the appropriate monitor command descriptions. In addition, the features of the VIM-1 monitor are explained in detail and a flowchart of monitor logic is included.

Chapter 6 is where you'll learn to program the VIM-1 to handle your applications. We'll describe the program flow and assembly code for a small sample program and explain how to prepare it for entry to the VIM-1. Then we'll discuss how to execute it and how to find problems in it if it doesn't work the way you expected it to work. After you've completed this example program, you'll have a chance to try your hand at two more programs of increasing complexity.

Chapter 7 describes how to use an oscilloscope with your VIM-1 module to obtain a unique, 32-character display similar to that of a CRT. The hardware is present on your VIM-1 to allow this usage, and the software has been designed to allow you to write your own program to send characters to the oscilloscope. A sample program implementing this feature is discussed in the chapter.

Chapter 8 explains how to expand your VIM-1 system to include additional memory or peripheral devices. I/O techniques are also discussed, including how to configure an auxiliary expansion port.

Chapter 9 consists of a discussion of advanced monitor and programming techniques which will add flexibility and expandability to your VIM system. One of the unique things about the VIM-1 is its seemingly endless flexibility in software. For example,

you can create a sub-set of new monitor commands or an entirely new monitor by taking advantage of the way the system handles unrecognized commands. You can also make use of nearly all of the monitor as subroutines in your own programs, thus saving both programming time and memory space.

In addition to the chapters described above, several appendices located at the back of the manual include important service and other reference information. Appendix A explains what to do if your VIM-1 does not operate properly, becomes defective or requires service. Appendix B contains a complete parts list and a component layout diagram. Audio cassette tape formats are described in Appendix C, and the format for data stored on punched paper tape is outlined in Appendix D.

You will find that your VIM-1 will interface many devices designed to accompany the KIM computer. This compatibility with KIM-related products is described in Appendix E. Appendix F explains how to create and use a sync tape for audio cassette operation. Finally, Appendices G, H, I and J provide reference information on the SY6502, SY6522, SY6532 and SY2114 RAM IC devices.

The last item in the manual, which is not an appendix but an addendum, is a complete listing of the VIM-1 SUPERMON monitor program. Nothing is held back; you have the complete listing to allow you to modify it any way you wish. Once you understand how the monitor works and the essentials of 6502 assembly language programming, this listing becomes an invaluable tool for implementing your own applications.



## CHAPTER 3

### PREPARING TO USE YOUR VIM COMPUTER

This chapter will take you, step-by-step, through the process of unpacking the VIM-1 and making it operational. After applying power and checking to see that the keyboard and display function properly, you will learn how to attach an audio cassette recorder, TTY, or CRT to the system.

#### 3.1 PARTS CHECK

In addition to this manual, several other items are included with your microcomputer. Packed along with the VIM-1 microcomputer itself you should find a programming card containing a summary of 6502 instruction codes and VIM commands, a programming manual, a warranty card, which you should fill out and mail to Synertek Systems as soon as possible, an optional user club card and two edge connectors, one long and one short. Also included is a red plastic strip which serves as a faceplate over the lighted display. The terms of the warranty are explained on the warranty card. Also included with the computer is a packet of small rubber feet on which to mount your VIM-1 for table-top operation.

#### 3.2 CAUTION ON MOS PARTS

The integrated circuits on your VIM-1 are implemented with Metal Oxide Silicon (MOS) technology and may be damaged or destroyed if accidentally exposed to high voltage levels. By observing a few simple precautions you can avoid a costly and disappointing mishap.

Static electricity is perhaps the least obvious, and thus most dangerous, source of voltage potential that can damage computer components. The VIM-1 is wrapped in special conductive material to protect it in shipping, and you should be careful to discharge any possible build-up of static electricity on your body before unpacking or handling the circuit board. Walking on a carpeted floor is especially liable to produce static electricity. Always touch a ground connection such as a metal window frame or an appliance with a three-pronged plug before handling your VIM-1, and avoid touching the pin connections on the back of the circuit board. Ungrounded or poorly grounded test equipment and soldering irons are other sources of potentially dangerous voltage levels. Make sure that all test equipment and soldering irons are properly grounded.

#### 3.3 VISUAL CHECK

While observing the precautions described in section 3.2, take the VIM-1 from its box and remove the protective packing. Next, apply the small rubber mounting feet and place the VIM-1 on a flat surface with the keyboard facing you. Using Figure 3-1 you can identify the major system components and begin to familiarize yourself with the layout of the VIM-1 board. Chapter 4 describes the system in more detail, with appropriate schematics, but for now we're just concerned with powering-up and beginning operation.

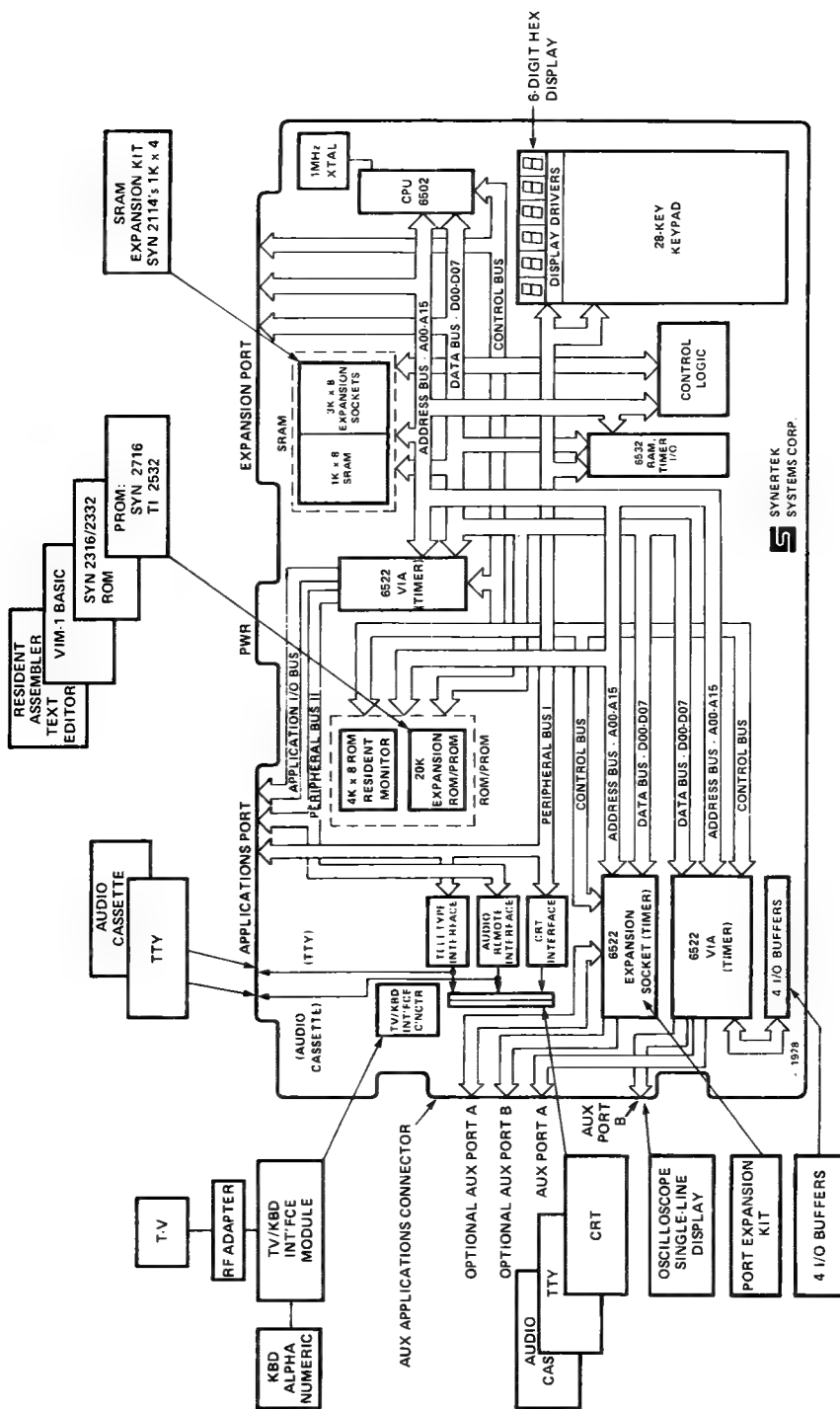


Figure 3-1. FUNCTIONAL BLOCK DIAGRAM

### 3.4 RECOMMENDED POWER SUPPLIES

The VIM-1 microcomputer requires only the addition of a power supply to become fully operational. Any unit that supplies +5 Volts DC @ 1.5 amps and has adequate overload protection is acceptable. Synertek Systems does not recommend any particular make or model. Rather than buy an assembled power supply, you may want to build your own from one of the many kits available from hobby stores and mail order houses.

### 3.5 POWER SUPPLY CONNECTION

Now that you've obtained a 5-volt power supply, you're almost ready to power-up the VIM-1. Find the power supply edge connector (the smaller of the two edge connectors packed along with the microcomputer), and wire it as shown in Figure 3-2. Next, slide the connector onto the power connector pins located in the middle of the top edge of the board. Check to make sure that the wiring is correct and that the connector is properly oriented before attaching it to the board.

### 3.6 POWER-ON CHECK

Turn on the power supply. The red light to the left of the power connection should glow to indicate that power is reaching the board. The LED display above the keyboard should be completely blank, and a tone should be heard. Press the Carriage Return (CR) key. You should again hear the audible tone that is emitted when power is turned on or a key depression is sensed, and the display should show "SY1.0 . .". Carriage Return (CR) is the key that "logs you on" to the computer when first powering up or after pressing Reset (RST). If your computer isn't responding properly, turn off the power supply. Remove the power connector from the board and make sure that all wires are connected to the proper locations and are securely attached, then repeat the power-up procedure.

If after you recheck and repeat the power-up procedure, your VIM-1 does not respond as described above, refer to Appendix A for information on returning the unit for service.

### 3.7 KEYBOARD EXERCISE

Now that your VIM-1 is operational, let's try a small program to verify that the system is functioning properly. The program will add together two 8-bit binary numbers and store the result. As you enter the program, addresses and data will appear on the LED display as hexadecimal digits. Addresses are 16 bits long and thus will be represented by four hexadecimal digits, while data bytes are 8 bits long and will appear as two hex digits. Before entering the program, you may want to review the following listing of assembler code for the test program. The process of converting assembler code to machine language will be explained in Chapter 6.

	MONITR	=	\$8000
	VALUE1	=	\$0200
	VALUE2	=	\$0201
	RESULT	=	\$0202
	*	=	\$0203
0203	18	START	CLC
0204	D8		CLD
0205	AD 00 02		LDA VALUE1
0208	6D 01 02		ADC VALUE2
020B	8D 02 02		STA RESULT
020E	4C 00 80		JMP MONITR
			END

# POWER SUPPLY CONNECTIONS

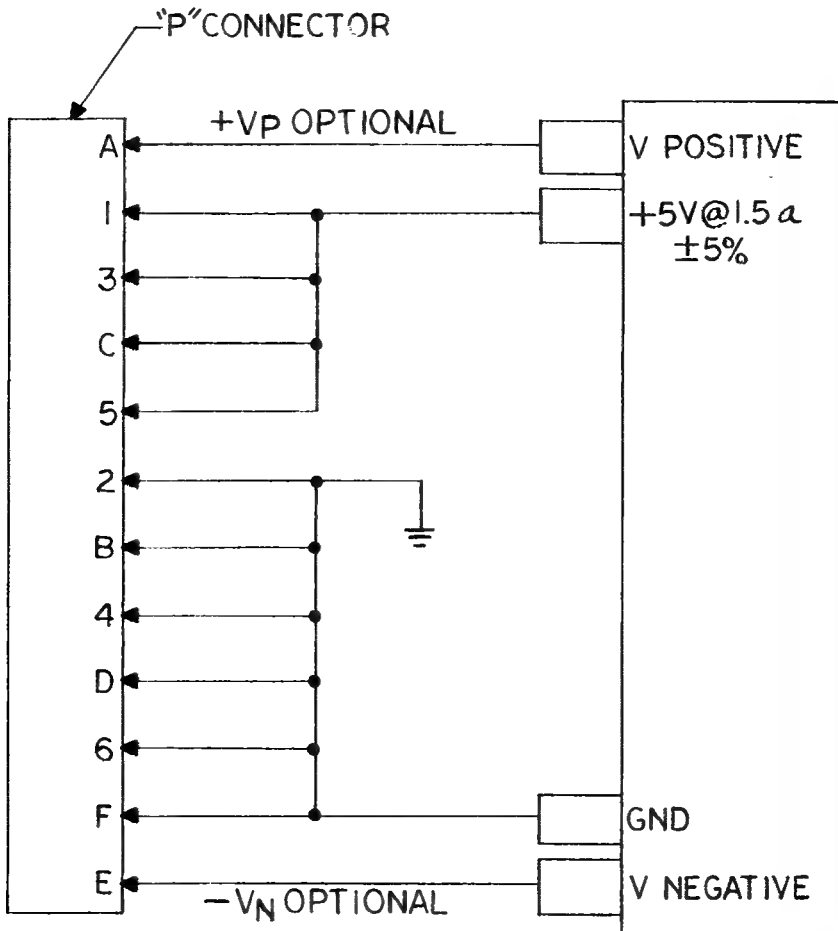


Figure 3-2. POWER SUPPLY CONNECTIONS

Now enter the program by following the steps listed below. Asterisks indicate the displayed data contained in the identified locations. Simulated key tops stand for function keys (e.g., (CR) for carriage return) The period displayed at the end of each entry sequence is SUPERMON's standard prompt character. As each data byte is entered, the address will automatically increment.

<u>YOU KEY IN</u>	<u>DISPLAY SHOWS</u>	<u>EXPLANATION</u>
(RESET)		
(CR)	SY1.0..	Keyboard log-on
(MEM) 200 (CR)	0200.**	Display contents of location 0200.
C1	0201.**	Store C1 (Hex) in 0200, display next location.
05	0202.**	Store 05 (Hex) in 0201, display contents of 0202.
00	0203.**	Store 00 (Hex) in 0202, display 0203
Enter Program:		
18	0204.**	Store 18 (Hex) in 0203, display 0204
D8	0205.**	Store D8 (Hex) in 0204, display 0205
AD	0206.**	.
00	0207.**	.
02	0208.**	.
6D	0209.**	.
01	020A.**	
02	020B.**	
8D	020C.**	
02	020D.**	
02	020E.**	
4C	020F.**	
00	0210.**	
80	0211.**	
(CR)	211.**.	
Check to see that program is entered correctly:		
(MEM) 200 (CR)	0200.C1.	VALUE1
(→)	0201.05.	VALUE2
(→)	0202.00.	RESULT
(→)	0203.18.	Clear carry flag
(→)	0204.D8.	Set status register for binary add
(→)	0205.AD.	Load VALUE1 into accumulator
(→)	0206.00.	Address of VALUE1, low order byte
(→)	0207.02.	Address of VALUE1, high order byte
(→)	0208.6D.	Add VALUE2 to accumulator
(→)	0209.01.	Address of VALUE2, low order byte
(→)	020A.02.	Address of VALUE2, high order byte
(→)	020B.8D.	Store accumulator
(→)	020C.02.	Address of RESULT, low order byte
(→)	020D.02.	Address of RESULT, high order byte
(→)	020E.4C.	JUMP to monitor
(→)	020F.00.	Address of monitor, low order byte
(→)	0210.80.	Address of monitor, high order byte
(CR)	210.80..	Exit from memory display and modify mode

Your program is now entered and ready to execute. The two numbers you will add together, C1 (Hex) and 05 (Hex), are stored in locations 0200 and 0201 respectively. The result will be stored in location 0202. The two digit hex codes you entered in

succeeding memory locations are the addresses, operands, and 6502 instruction codes necessary to add together two 8-bit binary numbers and return to the monitor program. To execute the program and display the result, perform the following steps:

<u>YOU KEY IN</u>	<u>DISPLAY SHOWS</u>	<u>EXPLANATION</u>
(GO) 203 (CR)	g 203 .	Execute program starting at location 0203
(MEM) 202 (CR)	0202.C6	Check result stored in location 0202
(CR)	202.C6. .	Exit from memory display and modify mode

Although this is a simple problem, it demonstrates the basic procedures for entering and executing a program on the VIM-1 as well as verifying that the system is operating properly.

### 3.8 ATTACHING AN AUDIO CASSETTE RECORDER

The program you entered in section 3.7 will remain stored in RAM memory only as long as the power remains on. As soon as the power is turned off, RAM data is lost, so to reuse the program you would have to enter it again from the keyboard. In order to provide you with a way to permanently store data and programs, VIM-1 is equipped with the hardware and software logic necessary to "talk to" an audio cassette recorder.

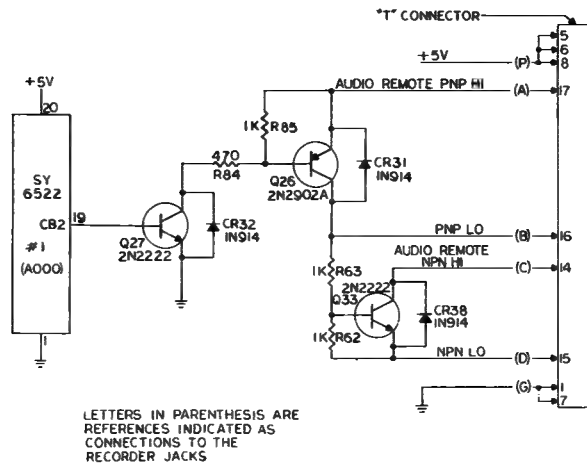
Since VIM-1 audio cassette operation involves high data transfer rates (185 bytes per second for HIGH-SPEED format), you should use a good quality recorder to ensure reliable performance. The unit should be equipped with an earphone jack for output, a microphone for input, a remote jack for remote control of the motor (optional), and standard controls for Play, Record, Rewind, and Stop. An additional feature that is useful but not essential is a tape counter. By keeping a record of counter values you can locate any program of data block manually without having to search the tape under program control at Play speed.

VIM-1 is designed to allow the cassette unit to be attached to either the Applications (A) or the Terminal (T) connector (requires a DB25 connector; see section 3.12). Refer to Figure 3-1 for the board location of these two connectors. Figure 4-3 shows how the Applications (A) edge connector should be wired for the cassette unit. The Terminal (T) connector should be wired as shown in Figure 4-3 if the unit is to be attached to the T connector. Keep the leads as short as possible and avoid running them near sources of electrical interference such as AC power cords. Always use the ground connection at the connector and do not ground directly to the power supply.

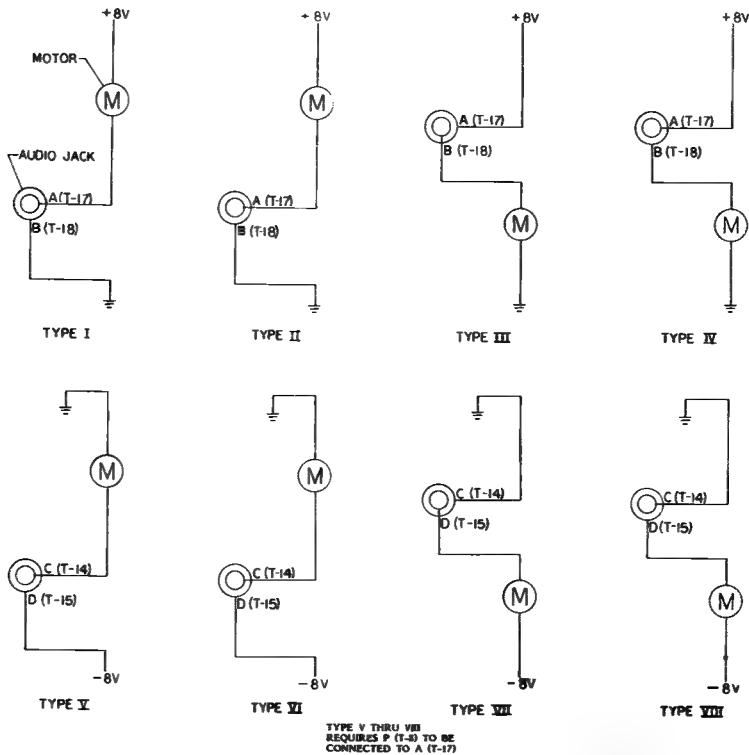
The remote control circuitry on the VIM-1 card allows a variety of cassette recorders to be used under software control. However, before you connect your remote control you must determine which type of connection is necessary for your particular recorder. Figure 3-3 illustrates the VIM-1 circuitry and eight different ways to hook it up. The following procedure can be used to determine which connection is necessary for your recorder:

1. Insert the remote control cable into your recorder. Install a tape in the unit.
2. Press play. The tape should not move. If it does, check the cable.
3. Measure the voltage at the center tip of the open end of the cable. (See Figure 3-4. Use ground reference from the MONITOR OUT plug.) Record

# AUDIO CASSETTE VIM REMOTE CONTROL CONNECTION



## AUDIO CASSETTE RECORDER JACKS REMOTE CONTROL CONNECTIONS



**Figure 3-3. REMOTE CONTROL TYPES AND CONNECTIONS**

# REMOTE CONTROL PLUG UNIT

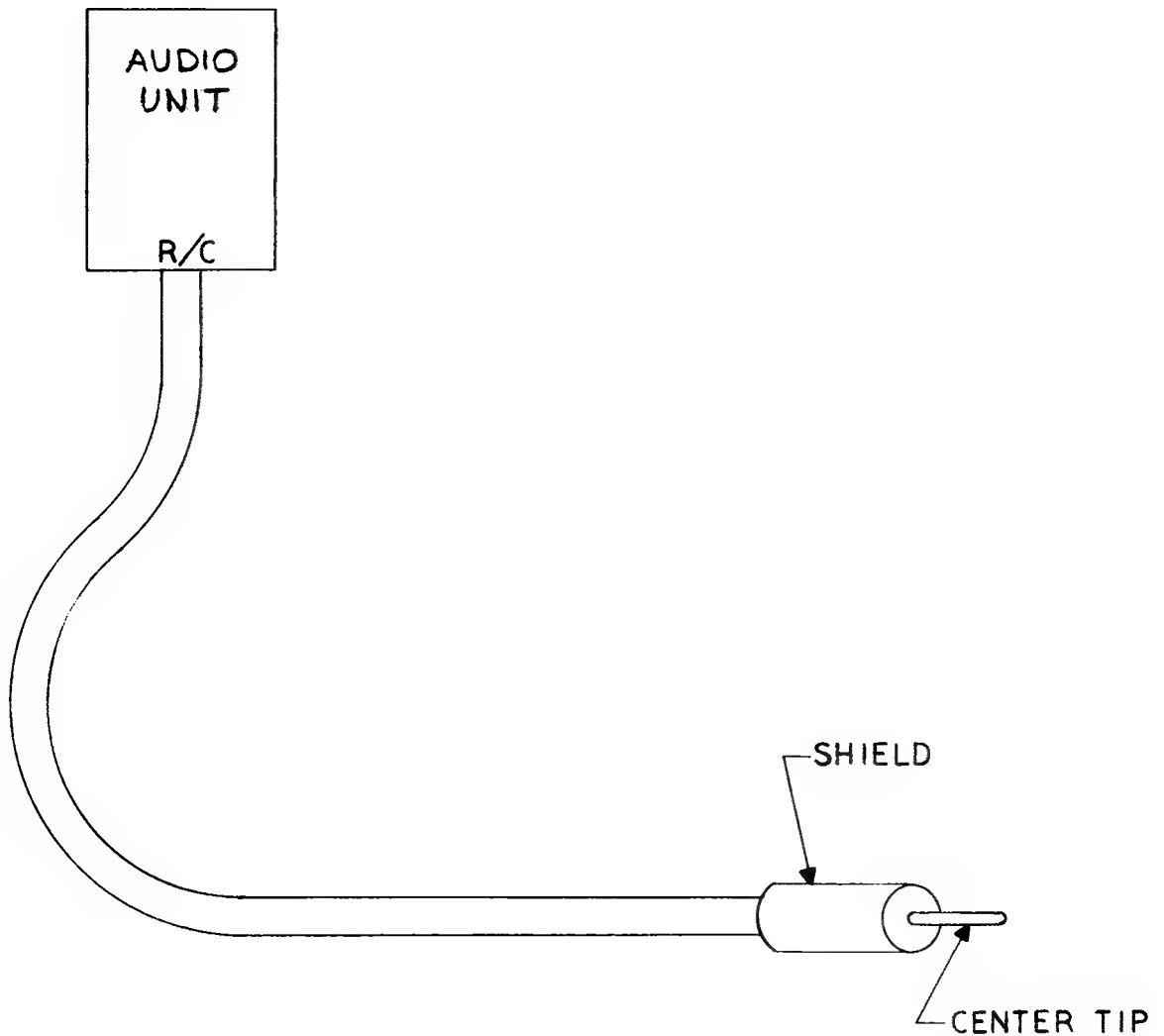


Figure 3-4. REMOTE CONTROL PLUG UNIT



- this as Reading A. Typically this will be either +6 to +8 volts, -6 to -8 volts, or ground.
4. Measure voltage at the shield of the open end of the cable. Record this as Reading B. The same typical values stated in step 3 will apply. Readings A and B should not be the same.
  5. Using a wire jumper, short the shield and center tip together. Your tape should now move. Measure the voltage at the center tip (do not remove the short). Record this as Reading C.
  6. If your tape moves in step 2 or your tape does not move in step 5, check your cable for opens or shorts.
  7. Use Table 3-1 to determine which type of connections to make for your recorder.
  8. After you have found the proper category for your recorder, Figure 3-3 illustrates which connections to make.

### 3.9 SAVE AND LOAD EXERCISE

To check cassette unit operation, we'll "Save" on tape the program presented in Section 3.7, then load the program back into RAM. But before beginning tape operations, we must set the volume and tone controls on the recorder to the correct position. This is accomplished by creating and using a "sync" tape as described in Appendix F. Follow those procedures now, keeping in mind that we will save the program, and thus will also load it back into RAM, in HIGH-SPEED format.

After adjusting your recorder, enter the program from the keyboard as you did before. Insert a tape into the recorder. If your unit is equipped with remote control, place it in Record mode. Since the motor for the cassette is under software control, the tape will not advance. If your unit does not have remote control, do not place the unit in Record mode until just before pressing (CR) while entering the save command shown below including the carriage return, before placing the unit in Play Mode.

<u>YOU KEY IN</u>	<u>DISPLAY SHOWS</u>	<u>EXPLANATION</u>
(SAV 2) 3 (-) 200 (-) 210 (CR)	0-210.	Save locations 0200 to 0210 in a record with ID=03, in HIGH-SPEED format.

When recording starts the display will go blank. When recording is completed the display will re-light. All this should take approximately eight seconds. If your unit does not have remote control, stop the tape manually after the display re-lights.

Now rewind the tape to the starting point. If your unit has remote control, you will have to pull out the Remote jack from the recorder or keep your finger on the RST key.

To destroy the program stored in RAM, turn off system power, then turn it on again.

Log back onto the computer by pressing (CR), then place the cassette unit in Play mode if it is equipped with remote control. If you are operating the controls manually, you should first enter the load command shown below.

<u>YOU KEY IN</u>	<u>DISPLAY SHOWS</u>	<u>EXPLANATION</u>
(LD 2) 3 (CR)	..L3	Load HIGH-SPEED tape record with ID=03 into memory.

This command directs the VIM-1 to search for the tape record with ID=03. While the VIM-1 is searching, an "S" will be displayed. When reading begins, the AUDIO indicator LED will glow and the display should go blank. When the specified record has been loaded into memory the display will re-light.

If you are operating the controls manually, turn the recorder OFF. Under remote control, the motor will stop automatically.

Now follow the instructions in Section 3.7 for executing the program. The result of the addition, C6 (Hex), should appear on the display. If the "S" did not disappear when reading in the program, or if the cassette otherwise did not respond as described above, check all wiring connections, verify the settings of the volume and tone controls and repeat the recording and playback procedures, making sure that each step is performed correctly. If after rechecking connections and repeating the procedure you are still unsuccessful, refer to Appendix A.

### 3.10 ATTACHING A TTY

To enable you to add a hard copy output device to your system, VIM-1 interfaces to a TTY terminal. Since the Teletype Model 33ASR is widely used and easily obtained, it will be used in the procedures and diagrams in this section. To interface other terminals, use the information given in this section as a general guide and consult the terminal instruction manual for different wiring and connection options.

Your TTY should be set for 20 mA current-loop operation. If it is not, follow the manufacturer's instructions for establishing this configuration. In addition, check to make sure that your TTY is set up to operate in full-duplex mode. You need not concern yourself with the TTY data transmission rate. VIM-1 assumes 110 bits-per-second (baud) for TTY terminals.

Just like an audio cassette recorder, a TTY may be attached to either the Applications (A) connector or using a DB25 (see section 3.12), to the Terminal (T) connector connection (See Figure 3-1). Figure 3-5A shows how the edge connector should be wired if the TTY will be attached to the "A" connector. Figure 3-5B shows the proper connections if it will be attached to the "T" connector. Wire the edge connector as appropriate for your application, then slide it into position. To "log on" to the terminal enter the following command at the on-board keyboard (not on the TTY keyboard).

<u>YOU KEY IN</u>	<u>DISPLAY SHOWS</u>	<u>EXPLANATION</u>
(RESET)		
(CR)	SY1.0 . .	Log-on to keyboard
(SHIFT) (JUMP) 1 (CR)	blank	Log-on to TTY

The TTY should respond with a carriage return and the TTY prompt character, a period. If it does not, turn off the power and re-check your connections, then power-up again.

### 3.11 TERMINAL EXERCISE

After the TTY prints the prompting character (".") as shown on the first line of the chart below, perform the rest of the steps listed to become acquainted with TTY operation. You will be entering a portion of the program presented in Section 3.7.

# TTY I/O CONNECTIONS

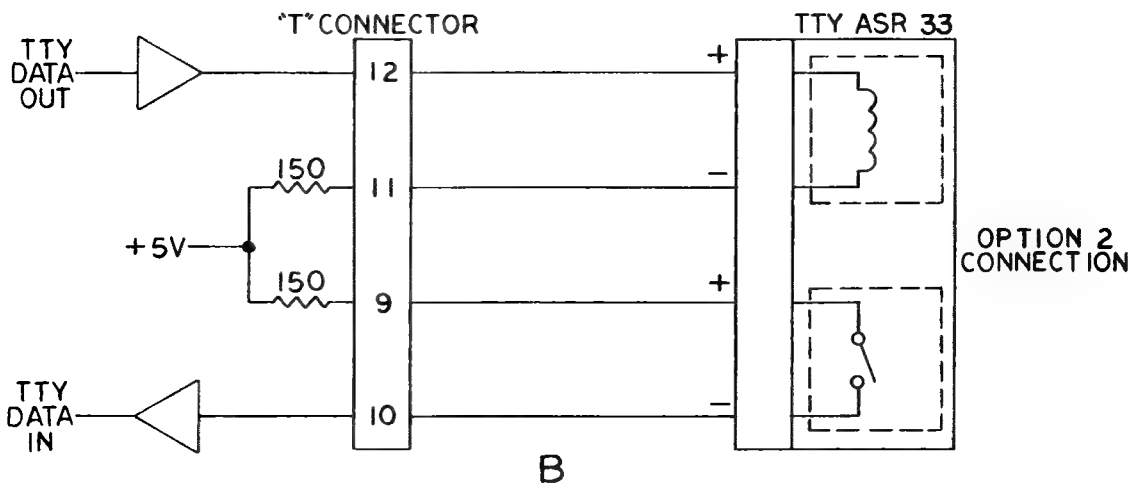
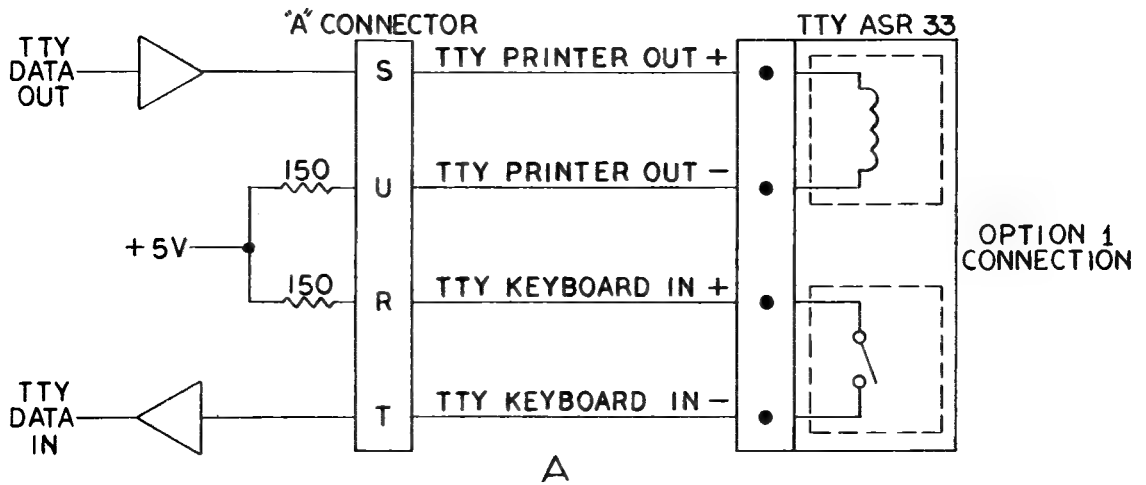


Figure 3-5. TTY I/O CONNECTIONS

<u>YOU KEY IN</u>	<u>TTY PRINTS</u>	<u>EXPLANATION</u>
	.	Prompt
M 200 (RETURN)	.M 200 0200,**,	Display contents of location 0200
C1	0200,**,C1 0201,**,	Store C1 (Hex) in 0200, display 0201
05	0201,**,05 0202,**,	Store 05 (Hex) in 0201, display 0202
(RETURN)	.	Return to monitor

### 3.12 ATTACHING A CRT

VIM-1 is equipped with an RS-232 interface to facilitate the use of such RS-232 devices as a full-ASCII keyboard and CRT display. Figure 3-6 shows how the proper DB25 connector, which may be easily obtained from an electronics supply house or computer hobby store, should be wired. The location of the interface on the VIM-1 board is shown in Figure 3-1. Some older units may need to be wired differently. Refer to the section on jumper options in Chapter 4.

### 3.13 CRT EXERCISE

Operating a CRT terminal is very similar to operating a TTY. Names of keys and their functions may vary slightly depending on the device, so you should consult your CRT operating manual to find which keys correspond to the TTY keys used in the exercise in section 3.11. VIM-1 automatically adjusts to data transmission rates of 300, 600, 1200, 2400, or 4800 baud for CRT operation. To set the baud rate, enter a "Q" on the CRT keyboard after powering-up (do not press any on-board keys). The CRT should respond with a ".", the terminal prompt character. Now repeat the exercise in Section 3.11 using the CRT keyboard.

In this chapter you have made your VIM-1 operational and learned how to attach several peripheral devices to the system. Let's move on to Chapter 4 and examine in detail the various features of VIM-1 hardware and software.

# CRT I/O CONNECTIONS

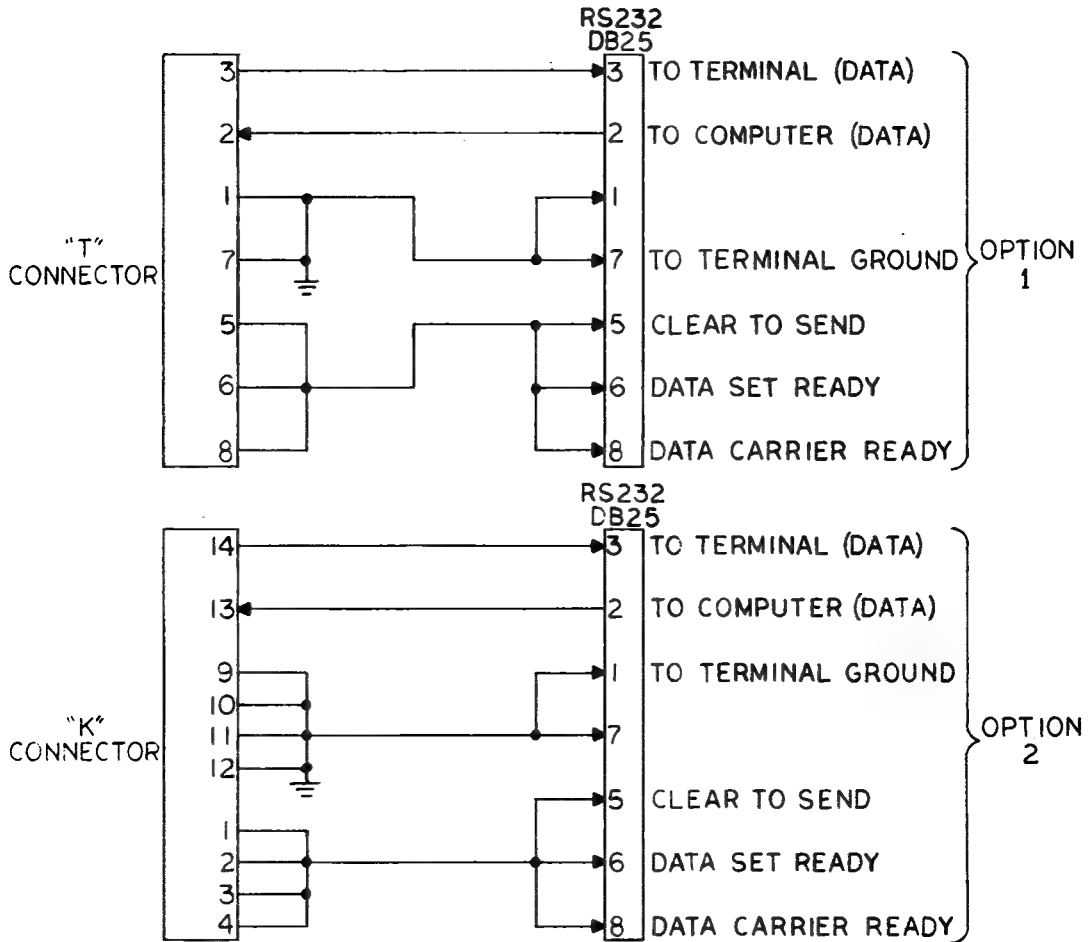


Figure 3-6. CRT I/O CONNECTIONS



## CHAPTER 4

### VIM-1 SYSTEM OVERVIEW

This chapter will describe your VIM-1 microcomputer system's hardware and software in sufficient detail to allow you to understand its theory of operation. Each Integrated Circuit (IC) component on the VIM-1 board is discussed and related to a functional block diagram. Each functional module is then discussed schematically and the I/O connectors are described. The system memory is then covered and the software is discussed briefly. Detailed data on the software itself is found in Chapter 5 of this manual.

#### 4.1 HARDWARE DESCRIPTION

The VIM-1 microcomputer consists primarily of a 6502 CPU, one or more 6522 Variable Interface Adapters (VIA), a 6532 Memory and I/O Controller and two types of memory involving any combination of several different components. Because of the flexibility of the memory structure, it is discussed in a separate section (4.2, below).

In any microcomputer system, all the components work together functionally as well as being physically interconnected. These connections are illustrated in Figure 4-1, a block diagram of the VIM-1 microcomputer system.

##### 4.1.1 6502 CPU Description

The Central Processing Unit (CPU) of the VIM-1 microcomputer system is the 6502 microprocessor which is designed around a basic two-bus architecture—one full 16-bit address bus and an eight-bit data bus. Two types of interrupts are also available on the processor. Packaged in a 40-pin dual-in-line package, the 6502 offers a built-in oscillator and clock drivers. Additionally, the 6502 provides a synchronization signal which indicates when the processor is fetching an instruction (operation code) from program memory.

During the following discussion of the 6502, you should refer to the Data Sheets in this manual, which describe the pin connections for all three of the major types of devices present on the VIM-1 microprocessor system.

**4.1.1.1 Bus Structure.** The 6502 CPU is organized around two main busses, each of which consists of a separate set of parallel paths which can be used to transfer binary information between the components and devices in the VIM-1 system. The address bus transfers the address generated by the processor to the address inputs of the peripheral interface and memory devices (i.e., the 6522 and 6532 components). Note that in the Data Sheet for the 6502, the address lines originate at pins 9-20 and 22-25 of the 6502 CPU. These address lines go to pins 2-17 on the 6522 and/or to pins 2, 5-8, 10-15 and 34-40 on the 6532. Since the processor is almost always the only source of address generation in a system, an address bus is generally referred to as "unidirectional." That is the case with the VIM-1 microcomputer system. Since the address bus consists of 16 lines, the processor may read and write to a total of 65,536 bytes of storage (i.e., program memory words, RAM words, stack, I/O devices and other information), a condition which is normally referred to as a "64K memory capacity."

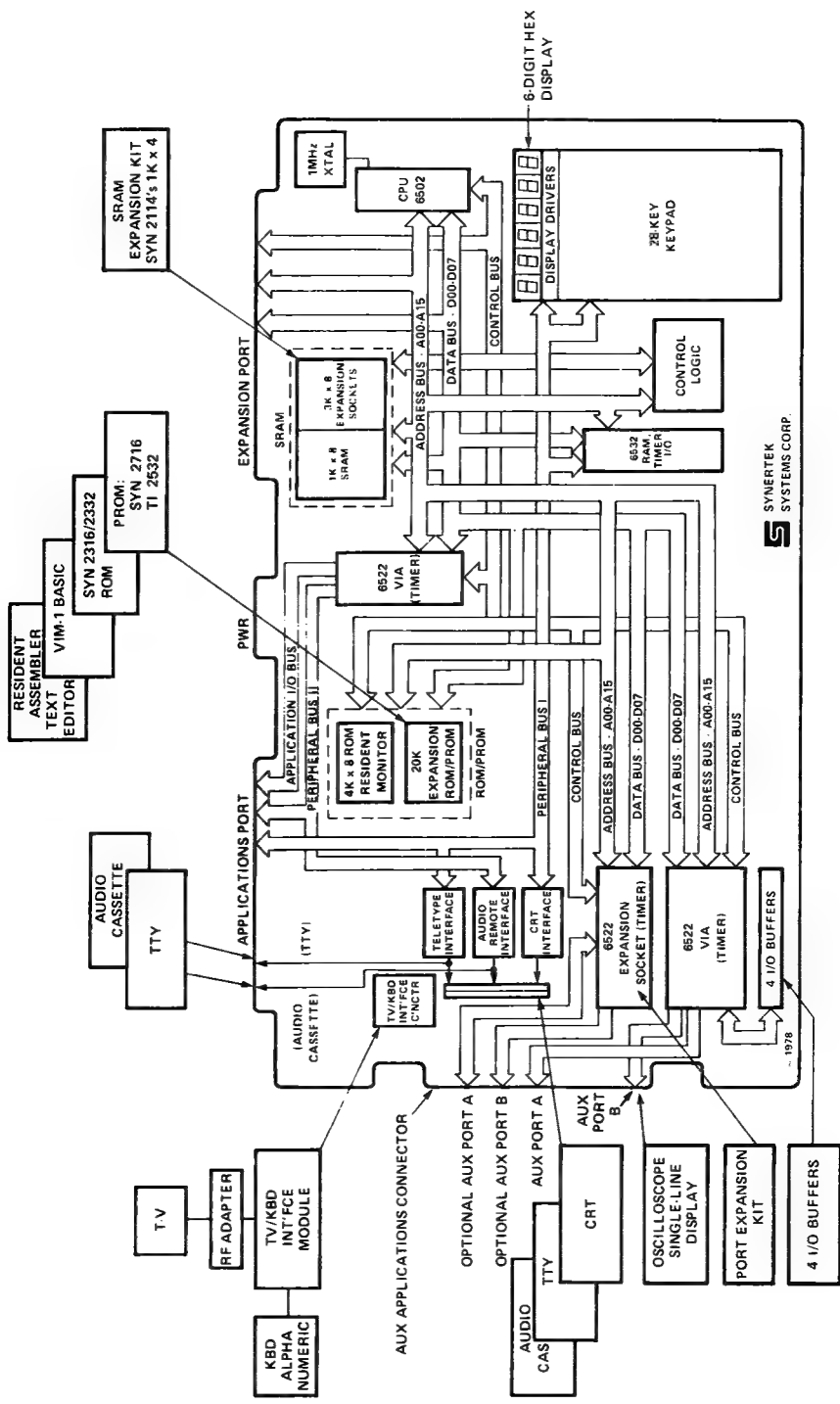


Figure 4-1. FUNCTIONAL BLOCK DIAGRAM



The other bus in the 6502 processor is called the data bus. It is an eight-bit bidirectional data path between the processor and the memory and interface devices. When data is moved from the processor to a memory location, the system performs a write; when the data is traveling from memory to the CPU, a read is being performed. Pins 26-33 on the 6502, 6522 and 6532 devices are all data lines connected to the data bus. The direction of the transfer of data between these pin connectors is determined by the output of the Read/Write (R/W, Pin 34) of the 6502. This line enables a write memory when it is "low" (when its voltage is below 0.4 VDC). Write is disabled and all data transfers will take place from memory to the CPU if the level is high (greater than 2.4 VDC).

One of the important aspects of the 6502 CPU is that it has two interrupt input lines available, Interrupt Request (labeled  $\overline{IRQ}$  in the Data Sheet) and a Non-Maskable Interrupt (labelled  $\overline{NMI}$ ).

Interrupt handling is one of the key aspects of microprocessor system design. Although the idea of interrupt handling is fairly simple, a complicating factor is the necessity for the processor to be able to handle multiple interrupts in order of priority (usually determined by the programmer) and not "losing track" of any of them in the process. These are concepts which you as a programmer-user of the VIM-1 will be concerned with only in advanced applications. The handling of user-generated interrupts is discussed elsewhere in this manual. If you do have occasion to alter pre-determined interrupt handling, it will be helpful for you to understand how the process works for the two types of interrupts in the 6502.

There are two main differences between the  $\overline{IRQ}$  and  $\overline{NMI}$  signals and their handling. First,  $\overline{IRQ}$  will interrupt the CPU only if a specific flag--the Interrupt Disable Flag (I)--in the system's Processor Status Register is cleared, i.e., zero. If this flag is "set"--i.e., one--the  $\overline{IRQ}$  is disabled until the flag is cleared. But an  $\overline{NMI}$  request (as its name implies) always causes an interrupt, regardless of the status of the I-flag. The other main difference between the two types of interrupts is that the  $\overline{IRQ}$  interrupt is "level sensitive." Any time the signal is less than 0.4 VDC and the Interrupt Disable flag is cleared, an interrupt will take place. In the case of  $\overline{NMI}$ , the interrupt is said to be "edge-sensitive" because it is dependent on a sequence of timing events. This interrupt will occur only if the signal goes "high" (i.e., exceeds 2.4 VDC) and then goes back to ground (less than 0.4 VDC). The interrupt occurs on the negative-going transition past 0.4 V.

The Data Sheet contains a summary of the 40 pins on the 6502 CPU and their function. Note that three of the pins--5, 35 and 36--are not connected on the 6502.

**4.1.1.2 Summary.** The 6502 CPU is a versatile processor. It was selected for your VIM-1 microprocessor system because of its overall functional characteristics, which facilitate its use in a wide variety of applications. Its role in the VIM-1 system will become clearer when we discuss programming and software in Section 4.3 and in Chapters 5 and 6.

#### **4.1.2 6522 Description**

The SY6522 Versatile Interface Adapter (VIA) is a highly flexible component used on the VIM-1 module to handle peripheral interfaces. Two of these devices are standard components on your VIM-1; a third may be added merely by plugging it into the socket (U28) provided. Control of the peripheral devices is handled primarily through the two eight-bit bi-directional ports. Each line of these ports can be programmed to act as

either an input or an output. Also, several of the peripheral I/O lines can be controlled directly from the two very powerful interval timers integrated into the chip. This results in the capability to 1) generate programmable frequencies, 2) count externally generated pulses, and 3) to time and monitor real time events.

A description of the pin designations on the SY6522 is contained in the Data Sheet enclosed with your VIM-1. It should be used in following the discussion of the operation of the component in the VIM-1 module which follows. The Memory Map of the VIM-1 module (Figure 4-10) will also be helpful during this discussion.

**4.1.2.1 Processor Interface.** Data transfers between the SY6522 and the CPU (6502) take place over the eight-bit data bus (DB0-DB7) only while the Phase Two Clock ( $\phi_2$ ) is high and the chip is selected (i.e., when CS1 is high and CS2 is low). The direction of these data transfers is controlled by the Read/Write line (R/W). When this line is low, data will be transferred out of the processor into the selected 6522 register; when R/W is high and the chip is selected, data will be transferred out of the SY6522. The former operation is described as the write operation, the latter the read operation.

Four Register Select lines (RS0-RS3) are connected to the processor's address bus to allow the processor to select the internal SY6522 register which is to be accessed. There are 16 possible combinations of these four bits and each combination accesses a specific register. Because of the fact that the SY6522 is a programmable-addressable device, these RS line settings, in combination with the basic device address, form the specific register address shown in the 6522 Data Sheet.

Two other lines are used in the SY6522 interface to the 6502 processor. The Reset line ( $\overline{RES}$ ) clears all internal registers to a logical zero state (except T1, T2 and SR), placing all peripheral lines in the input state. It also disables the timers, shift register and other on-chip functions and disables interrupting from the chip. The Interrupt Request line ( $\overline{IRQ}$ ) generates a potential interrupt to the CPU when an internal interrupt flag is set and a corresponding interrupt enable bit is set to a logical "1." The resulting output signal is then "wire or'ed" with other similar signals in the system to determine when and whether to interrupt the processor.

**4.1.2.2 Peripheral Interface.** As we mentioned earlier, peripheral interface is handled largely over two eight-bit ports, with each of the 16 lines individually programmable to act as an input or output line. Port A consists of lines PA0-PA7 and Port B of lines PB0-PB7.

Three registers are used to access each of the eight-bit peripheral ports. Each port has a Data Direction Register (DDRA and DDRB), which is used in specifying whether the pins are to act as inputs or outputs. If a particular bit in the Data Direction Register is set to zero, the corresponding peripheral pin is acting as an input; if it is set to "1," the pin acts as an output point.

Each of the 16 peripheral pins is also controlled by a bit in the output register (ORA and ORB) and a similar bit in the Input Register (IRA and IRB). When the pin is programmed to act as an output, the voltage on the pin is controlled by the corresponding bit in the Output Register. A "1" in the appropriate Output Register causes the pin to go "high" (2.4 VDC or higher), and a zero causes it to go "low (0.4 VDC or lower).

Functionally, reading a peripheral port causes the contents of the appropriate Input Register to be transferred to the Data Bus.

The SY6522 has a number of sophisticated features which allow very positive control of data transfers between the processor and peripheral devices through the operation of "handshake" lines which involve the use of Peripheral Control Lines (CA1-CA2 and CB1-CB2). These operations are beyond the scope of this manual; if you are interested in further information, you should consult the data sheet enclosed.

#### **4.1.3 6532 Description**

Like the SY6522 described above, the SY6532 is used on the VIM-1 module to control peripheral interface. Only one SY6532 is furnished with your VIM-1 and no others are provided for.

From an operational standpoint, the SY6532 is quite similar to the SY6522. One key difference, particularly on your VIM-1 module, is the presence of a 128-byte x 8-bit RAM within the SY6522. This is the location referred to as "System RAM" in discussions of the software operation and in the Memory Map (Figure 4-10).

A description of the pin designations on the SY6532 is included in the enclosed Data Sheet. You will notice that, like the SY6522, the SY6532 contains 16 peripheral I/O pins divided into two eight-bit ports (lines PA0-PA7 and PB0-PB7). Each of these pins can be individually programmed to function in input or output mode.  $\overline{IRQ}$  on the VIM-1 SY6532 is not connected.

The Address lines (A0-A6) are used with the RAM Select ( $\overline{RS}$ ) line and the Chip Select lines (CS1 and  $\overline{CS2}$ ) to address the SY6532. It is in this addressing that the SY6532 differs somewhat from the SY6522's on your VIM-1 module. To address the 128-byte RAM on the SY6532, CS1 must be high and  $\overline{CS2}$  and  $\overline{RS}$  must both be low. To address the I/O lines and the self-contained interval timer, CS1 and  $\overline{RS}$  must be high and  $\overline{CS2}$  must be low. In other words, CS1 is high and  $\overline{CS2}$  is low to address the chip;  $\overline{RS}$  is used to differentiate between addressing RAM and the I/O Interval Timer functions. Distinguishing between I/O lines and the Interval Timer is the function of Address Line 2 (A2), which is high to address the timer and low to address the I/O section. Again, the Memory Map in Figure 4-10 clarifies these operations since they are largely software-directed and address-dependent.

#### **4.1.4 Functional Schematics**

Understanding the electrical interfaces among the various components may be of some interest to you as you use and expand your VIM-1 microcomputer. The figures on the following pages include segmented schematics, where each figure provides an electronic overview of the interface between the CPU and its related component devices and peripherals.

Table 4-1 describes the contents of each figure in this group of schematic segments.

**Table 4-1. INDEX OF SCHEMATIC SEGMENTS FIGURES 4-2 TO 4-9**

<u>Figure</u>	<u>Function/Segment Diagrammed</u>
4-2	TTY and CRT Interface
4-3	Audio Cassette Interface
4-4	Audio Cassette Remote Control
4-5	I/O Buffer
4-6	Keyboard/Display
4-7	Control Section
4-8	Memory Section
4-9	Oscilloscope Output Driver

Table 4-2 provides, in summary form, a list of the connector points on the four VIM-1 connectors. This allows you to determine pin and connector configurations for various application options.

Key: 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 Component Side  
A B C D E F G H J K L M N P R S T U V W X Y Z Solder Side

EXPANSION (E)		APPLICATION (A)		AUXILIARY APPLICATION (AA)	
1	SYNC	A	AB0	1	GND A
2	RDY	B	AB1	2	-VN B
3	<del>01</del>	C	AB2	3	2 PA 1
4	IRQ	D	AB3	4	2 PA 2
5	RO	E	AB4	5	2 CA 0
6	NMI	F	AB5	6	2 EB 2
7	RES	H	AB6	7	2 PB 7
8	DB7	J	AB7	8	2 PB 5
9	DB6	K	AB8	9	2 PB 3
10	DB5	L	AB9	10	2 PB 1
11	DB4	M	AB10	11	2 PA 7
12	DB3	N	AB11	12	2 PA 5
13	DB2	P	AB12	13	2 PA 3
14	DB1	R	AB13	14	RES
15	DB0	S	AB14	15	3 CB 1
16	30	T	AB15	16	3 PB 2
17	DBOUT (1)	U	<del>02</del>	17	3 PB 0
18	POR	V	R/W	18	3 PA 6
19	Unused	W	R/W	19	3 PA 3
20	Unused	X	AUD TEST	20	3 PA 4
21	+5V	Y	<del>02</del>	21	3 PA 5
22	GND	Z	Ram-R/W	22	3 PB 5
				23	3 PB 7
				24	AUD OUT LO
				25	AUD GND

(1) Jumper option

Table 4-2. CONNECTOR POINTS AND THEIR FUNCTIONS IN VIM-1

CRT/TTY

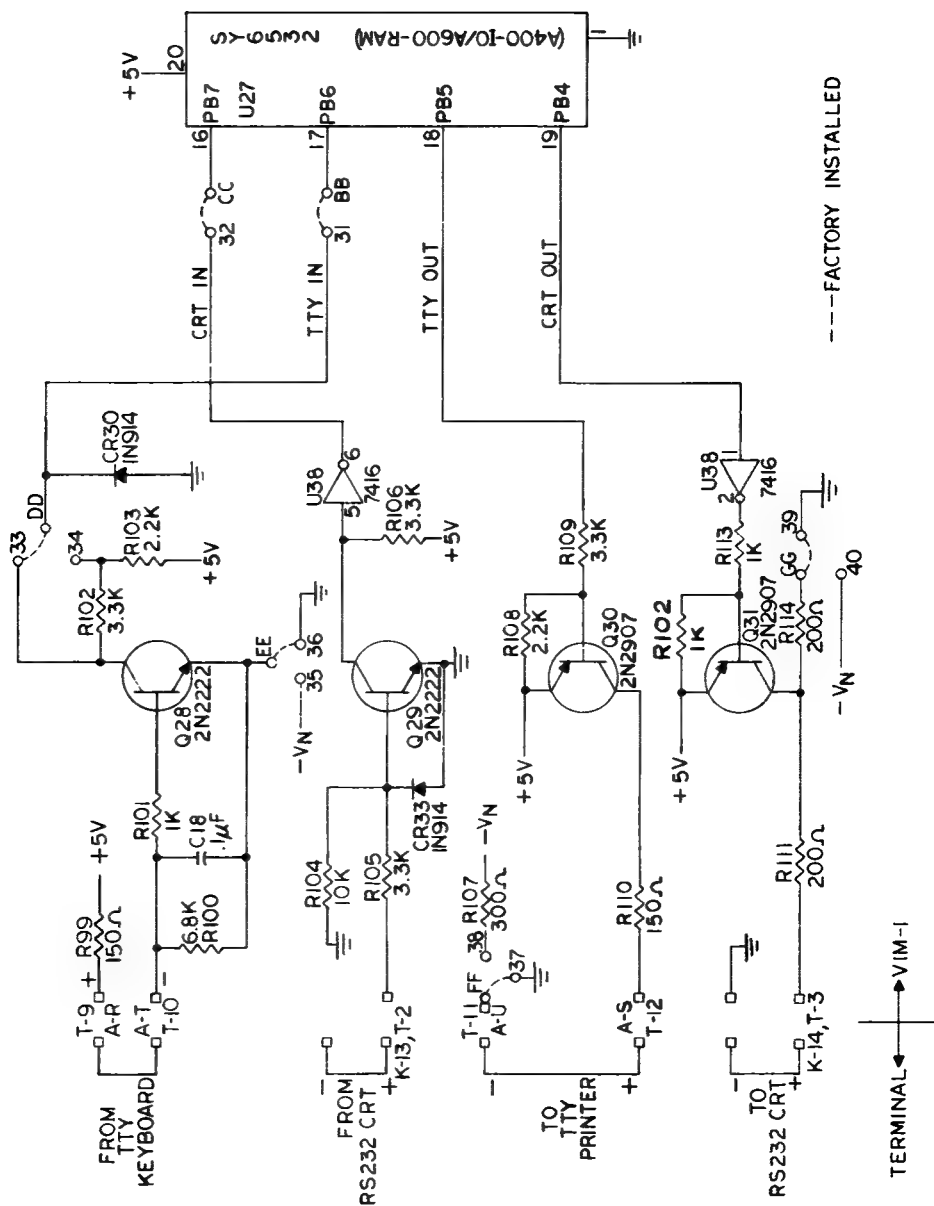


Figure 4-2. TTY/CRT INTERFACE SCHEMATIC

# AUDIO CASSETTE SCHEMATIC

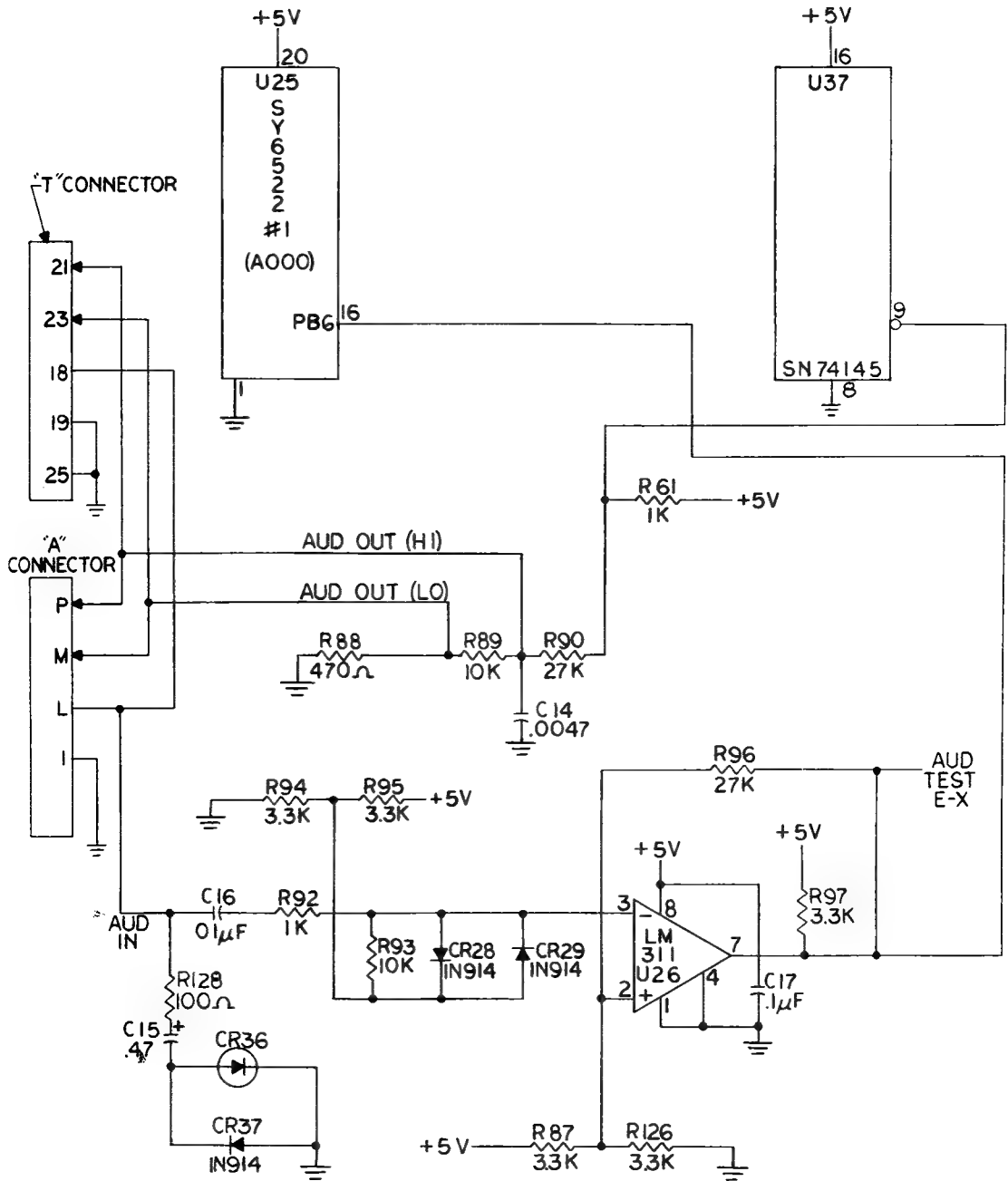
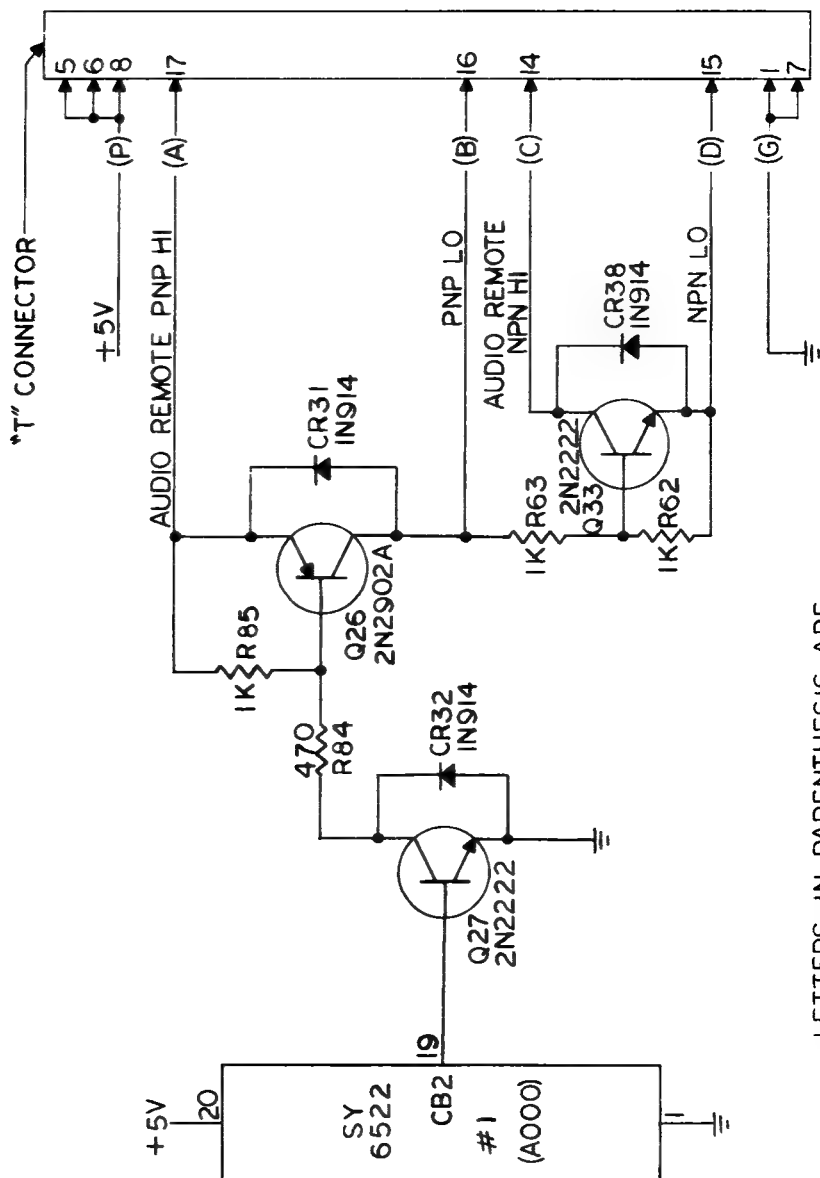


Figure 4-3. AUDIO CASSETTE INTERFACE SCHEMATIC

# AUDIO CASSETTE VIM REMOTE CONTROL CONNECTION



LETTERS IN PARENTHESIS ARE REFERENCES INDICATED AS CONNECTIONS TO THE RECORDER JACKS

Figure 4-4. AUDIO CASSETTE REMOTE CONTROL



# I/O BUFFERS

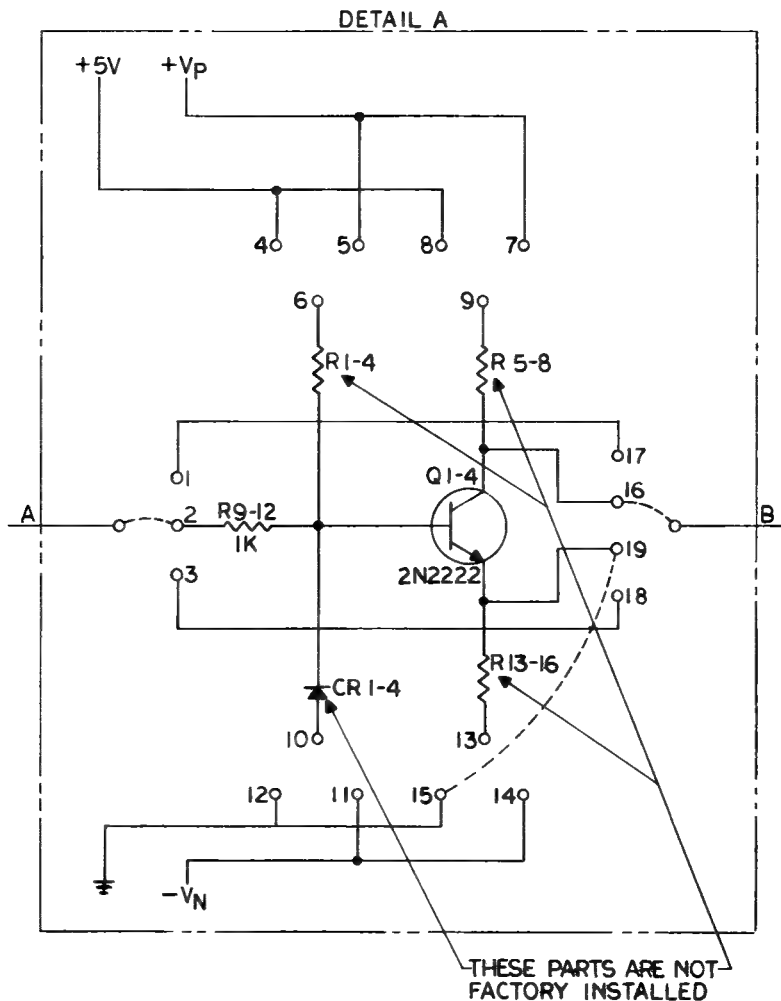
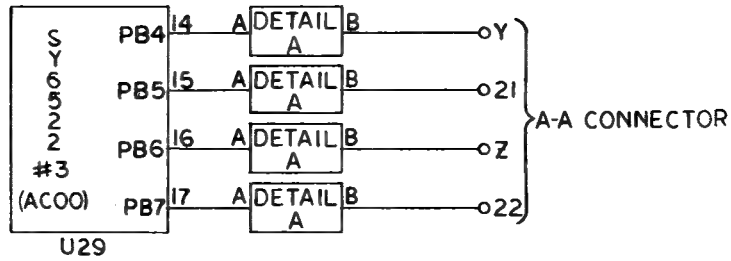


Figure 4-5. I/O BUFFERS SCHEMATIC

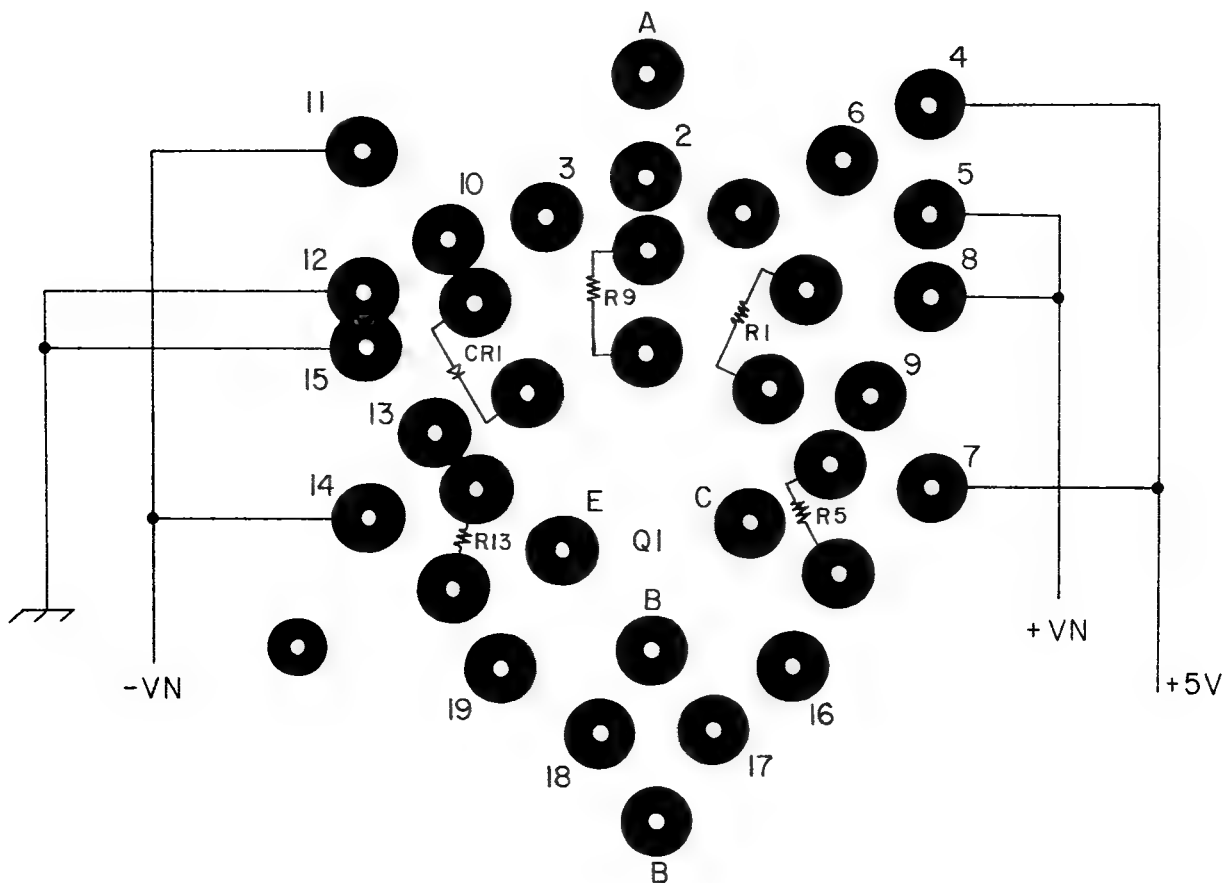


Figure 4-5a. I/O BUFFERS, PC SEGMENT BLOW-UP

# KEYBOARD/DISPLAY

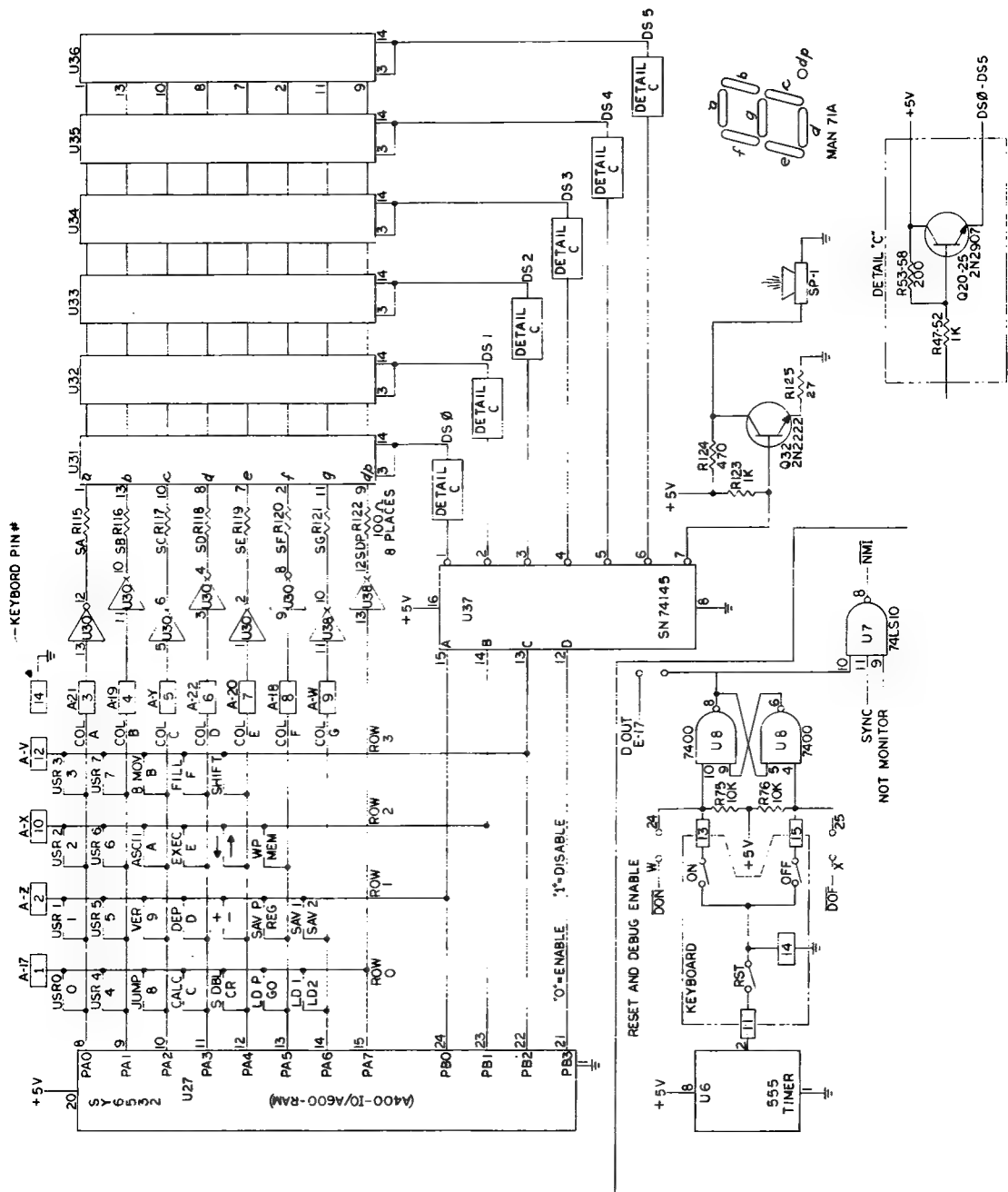


Figure 4-6. KEYBOARD/DISPLAY SCHEMATIC

# CONTROL

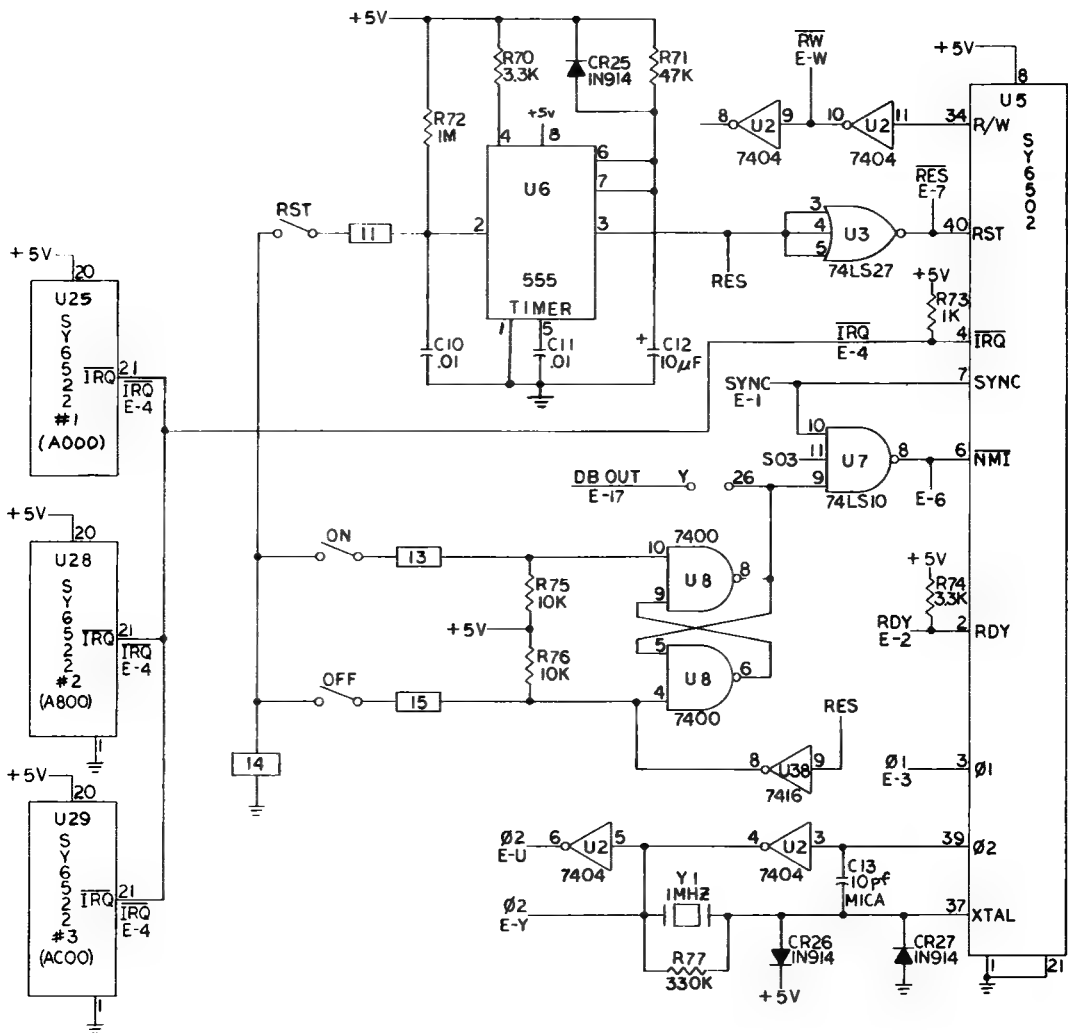


Figure 4-7. CONTROL SECTION SCHEMATIC

# MEMORY

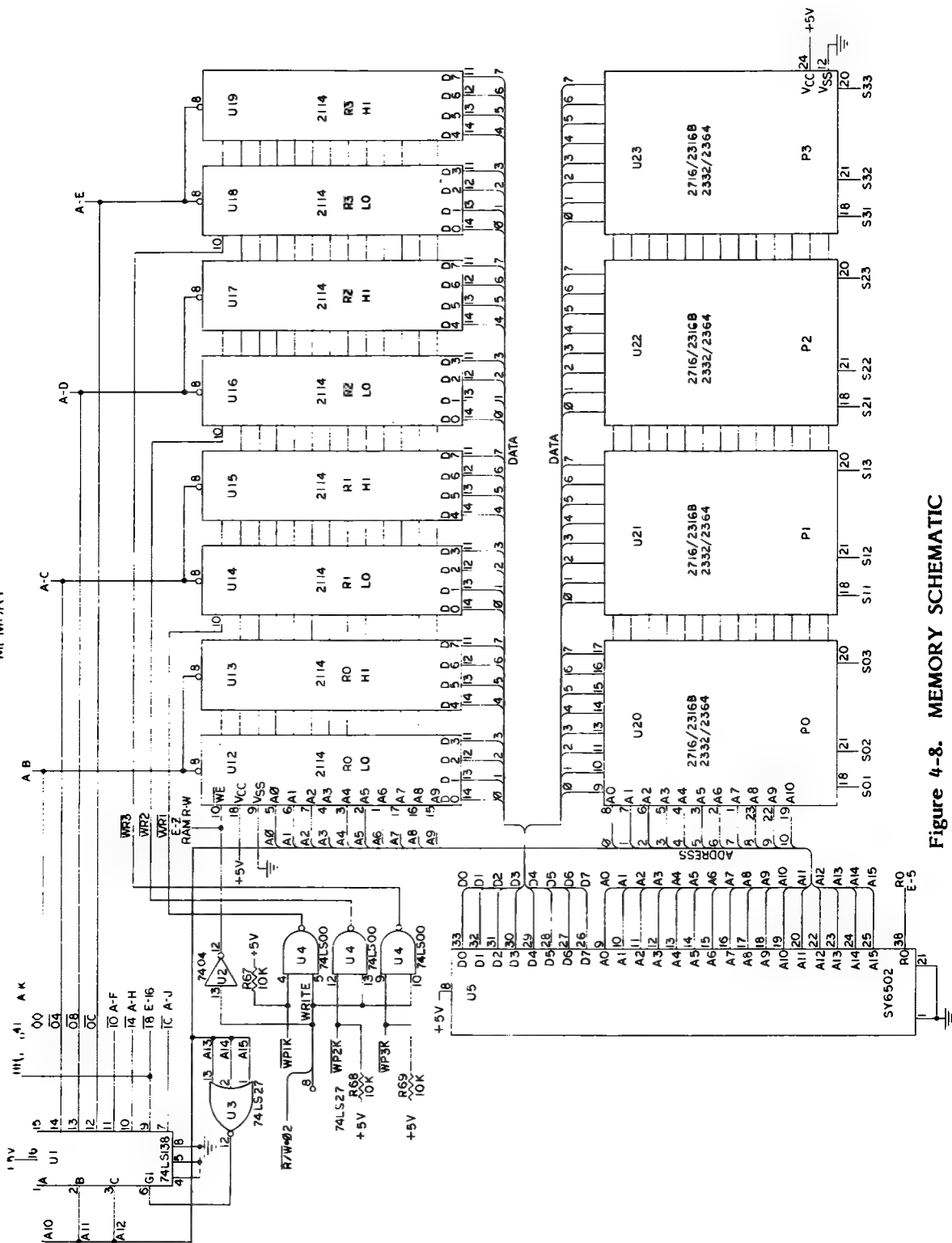


Figure 4-8. MEMORY SCHEMATIC

# OSCILLOSCOPE OUTPUT DRIVER

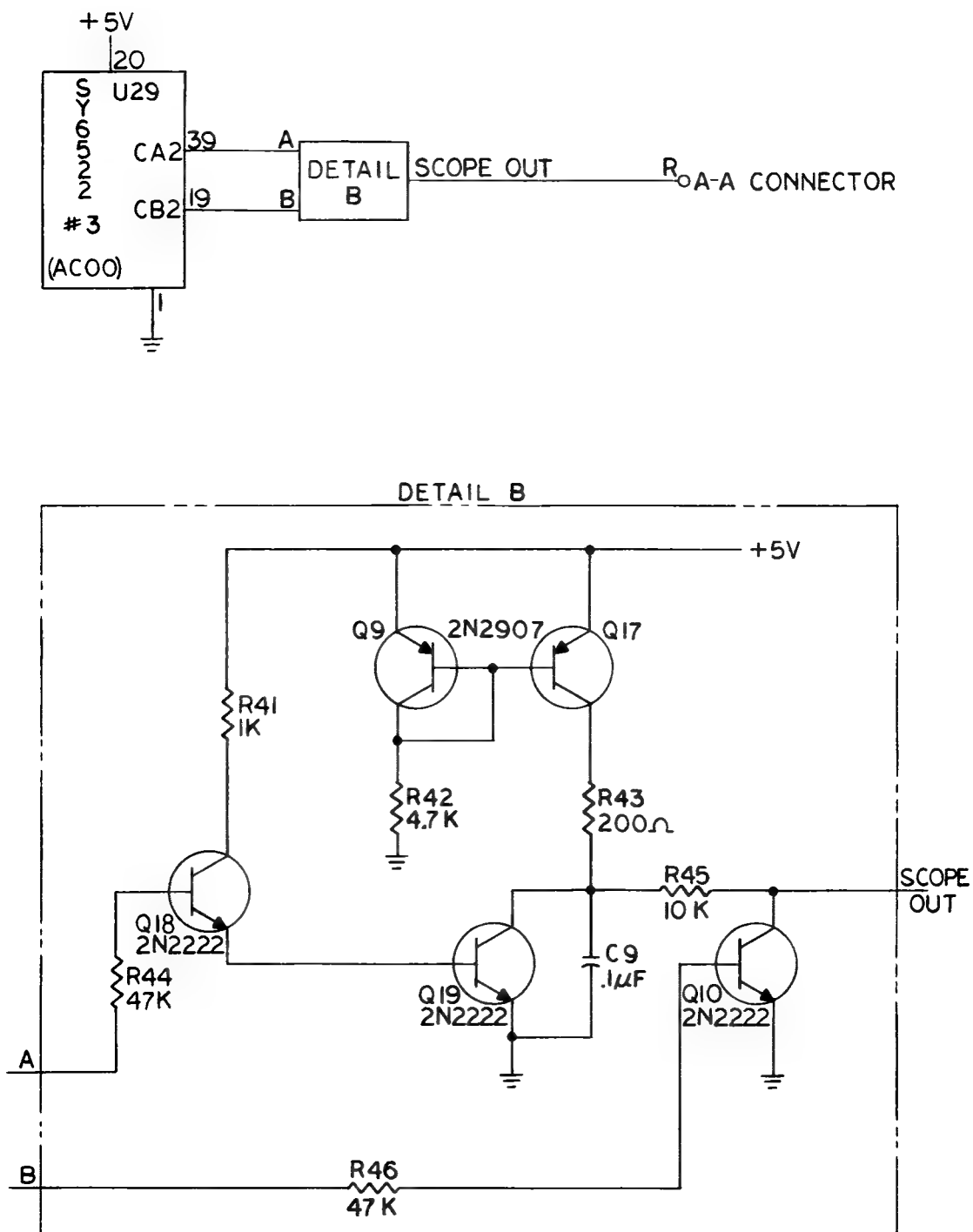


Figure 4-9. OSCILLOSCOPE OUTPUT DRIVER SCHEMATIC

## 4.2 MEMORY ALLOCATION

This section describes the standard memory allocation in your VIM-1 microcomputer system. It makes extensive use of the detailed Memory Map contained in Figure 4-10. Also described in this section is the technique by which ROM and RAM addressing and usage may be altered by using an array of on-board jumpers which allow you to modify and expand your VIM-1 memory. Expanding RAM memory using off-board components is taken up briefly in Section 4.2.3, although a detailed discussion of this is reserved for Chapter 8, "System Expansion".

### 4.2.1 Standard Memory Allocation

Figure 4-10 is a map of the standard memory allocation in your VIM-1 microcomputer. Provided with your system are 1K of on-board RAM, extending from location 0000 to 03FF in the Memory Map. Note that the top-most eight bytes (locations 00F8 to 00FF) in Page Zero of this 1K block are reserved for use by the system and should not be used by your programs. The remainder of Page Zero is largely similar to the rest of the RAM provided, but it also has some special significance for addressing which will become clearer in Section 4.3. Locations 0100-01FF in the 1K memory block furnished with your system are reserved for stack usage. Your programs may use this area, but you should use it for normal stack operations incidental to operating your programs. Locations 01FF-03FF are general-use RAM for your program and data storage.

In addition to the 1K of on-board RAM furnished with your system, sockets are provided for 3K of plug-in RAM, allowing you to have 4K of on-board RAM memory. These sockets occupy memory locations 0400-0FFF.

The SUPERMON monitor resides in ROM at memory locations 8000-8FFF. (As you know, the SY6502 CPU addresses all memory and I/O identically, so that it is immaterial whether a specific address location is occupied by RAM, ROM or I/O devices.) The next 4K block, from 9000-9FFF, is reserved for future expansion of SUPERMON, although you may use those locations if you wish to do so, provided you remember that if you should obtain an expanded SUPERMON system in the future these addresses may be used.

Extending from A000-AFFF are the I/O devices on your VIM-1 module. As we have previously said, each port on the SY6522/SY6532 devices in VIM-1 is an addressable location. Sheets 2-6 of Figure 4-10 provide you with a detailed Memory Map breakdown of how these devices are addressed. Note that within the SY6532 is a 128 byte segment (locations A600-A7FF). This is the RAM which is resident on the SY6532 used by VIM-1 as System RAM. Sheet 4 of Figure 4-10 describes each memory location within System RAM in detail; you will need this data if you wish to make use of the capability of the system for modifications to SUPERMON. These modifications may include creating your own commands (as described in Chapter 5) which may be entered as if they were Monitor commands. Other such modifications making use of System RAM locations are described in Chapter 9 of this manual.

Memory locations B000-FF80 may be used by your programs, provided of course you have expanded memory to fill those address locations (see Chapter 8). Note, however, that if you plan to obtain the Synertek Systems 8K BASIC module at some later date, that module will occupy locations C000-DFFF. You should plan your applications programs accordingly. Locations FF80-FFFF are reserved for special use by the system, and should not be used in any of your applications code.

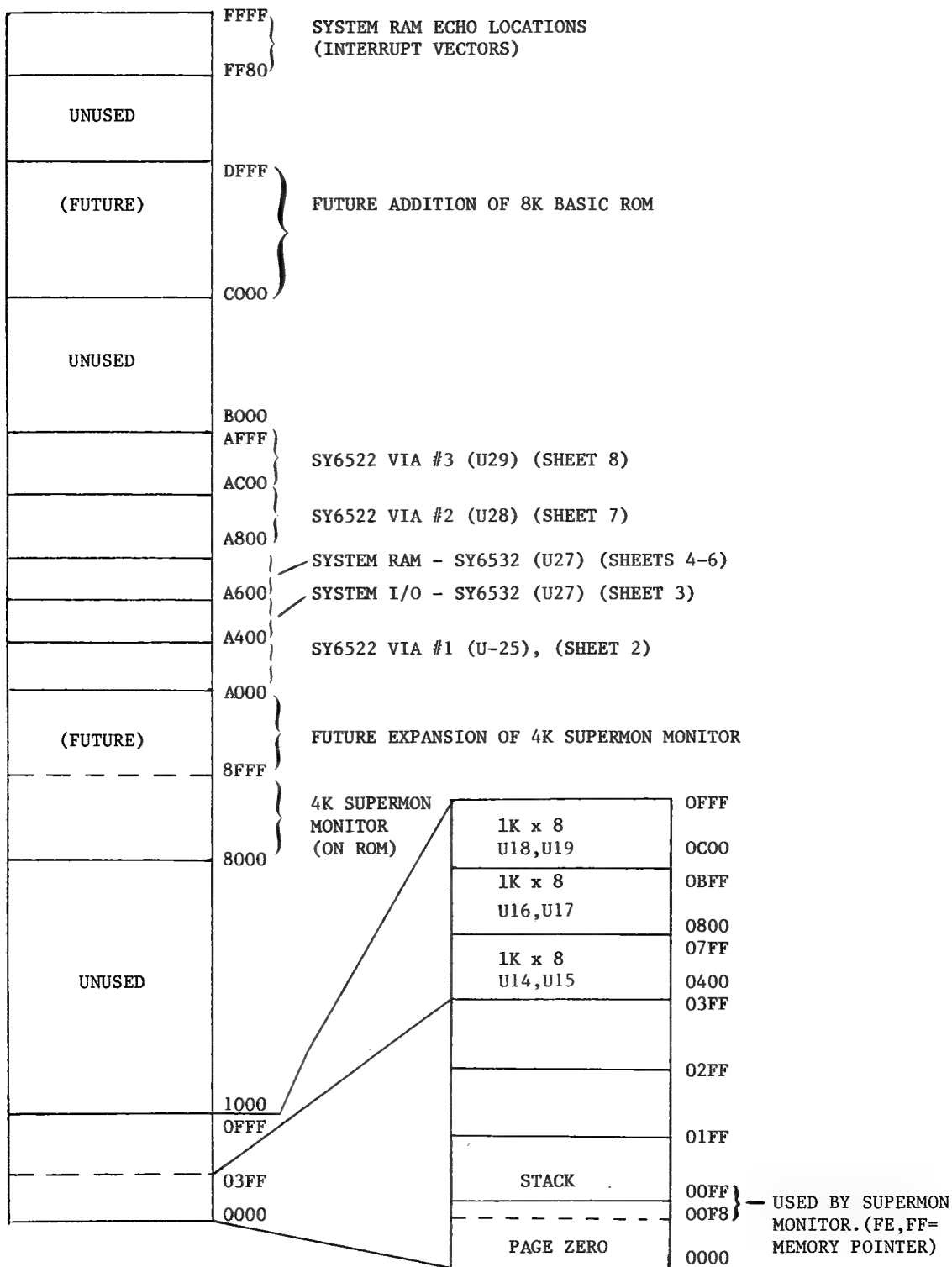


FIGURE 4-10. STANDARD MEMORY MAP, VIM-1



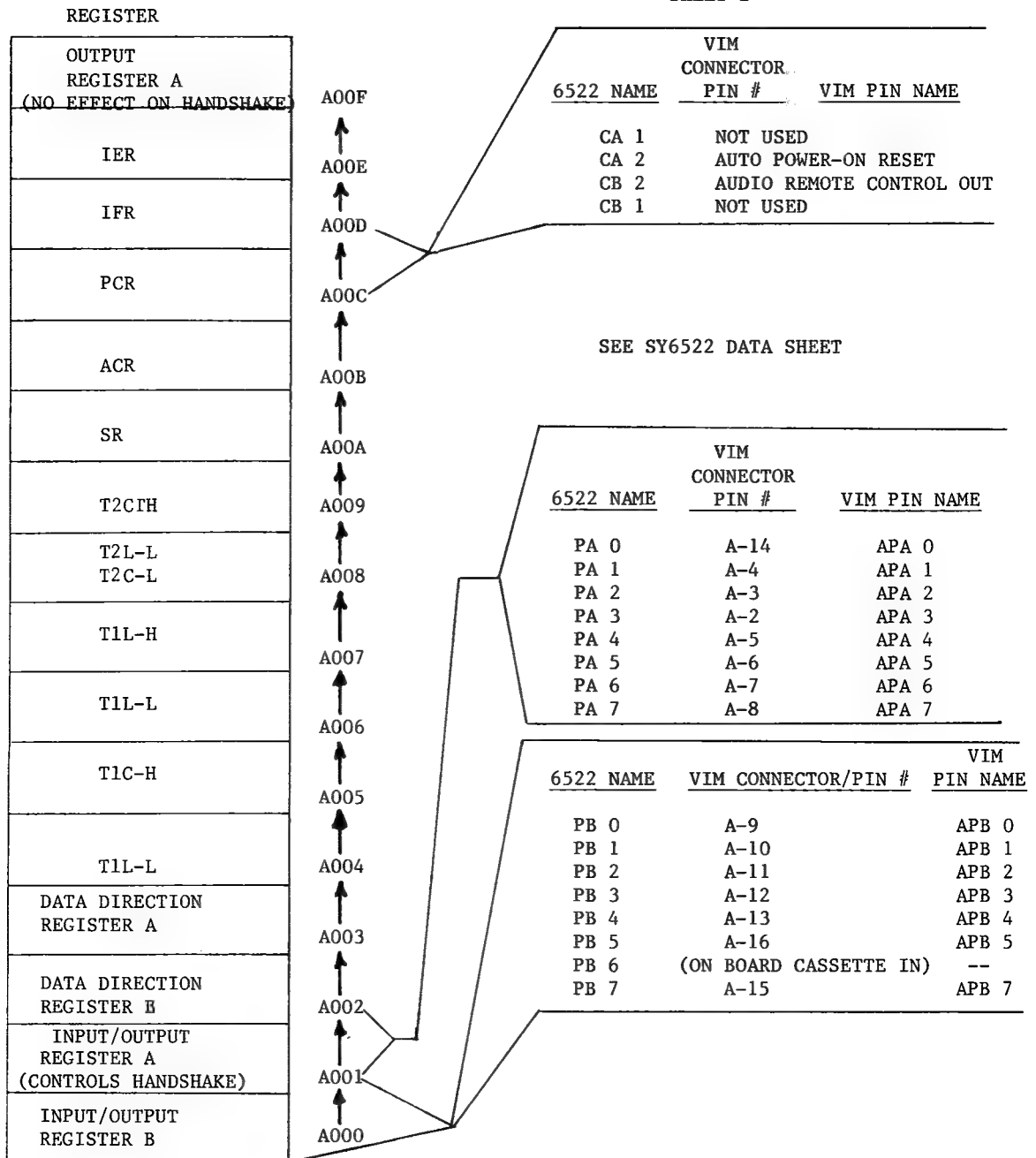


FIGURE 4-10 (CONT'D). MEMORY MAP FOR SY6522 VIA #1 (DEVICE U25)

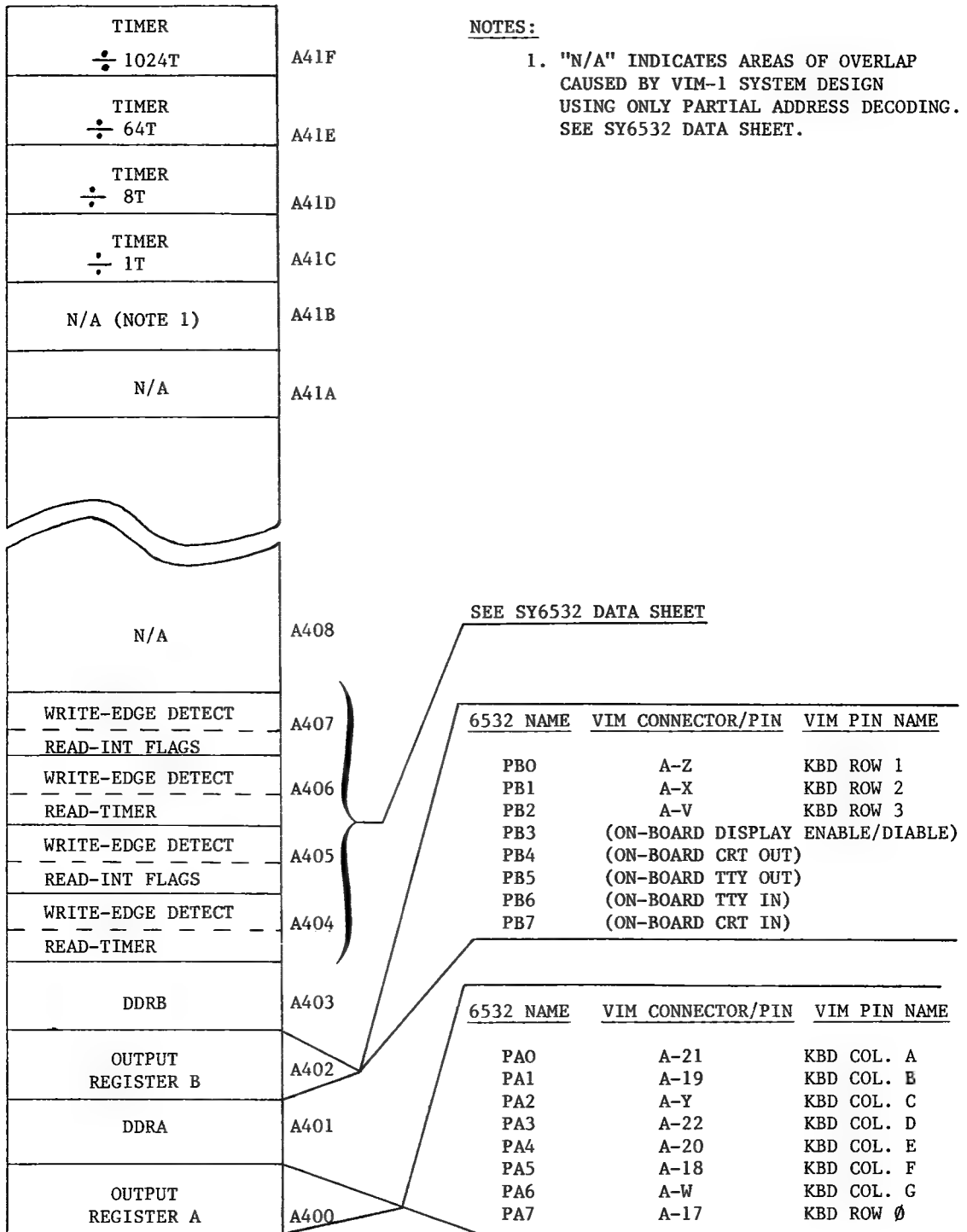


FIGURE 4-10 (CONT'D). MEMORY MAP FOR SY6532(DEVICE U27)

SYMBOL	ADDRESS	DEFAULT VALUE	COMMENTS
IRQVEC	A67F	80	IRQ Vector
	A67E	0F	
RSTVEC	A67D	8B	RESET Vector
	A67C	4A	
NMIVEC	A67B	80	NMI Vector
	A67A	9B	
UIRQVC	A679	80	User IRQ Vector
	A678	29	
UBRKVC	A677	80	User Break Vector
	A676	4A	
TRCVEC	A675	80	Trace Vector
	A674	C0	
EXEVEC	A673	88	'Execute' Vector
	A672	7E	
SCNVEC	A671	89	Display Scan Vector
	A670	06	
	A66F	4C	
URCVEC	A66E	81	Unrecognized Command Vector
	A66D	D1	
	A66C	4C	
	A66B	00	Not Used
	A66A	00	
INSVEC	A669	00	In Status Vector
	A668	89	
	A667	6A	
OUTVEC	A666	4C	Output Vector
	A665	89	
	A664	00	
INVEC	A663	4C	Input Vector
	A662	89	
	A661	BE	
YR	A660	4C	User Registers
XR	A65F	00	
AR	A65E	00	
FR	A65D	00	
SR	A65C	00	
PCHR	A65B	FF	
PCLR	A65A	8B	
MAXRC	A659	4A	
LSTCOM	A658	10	Max. No. Bytes/Record, Paper Tape (Note 6)
TV	A657	00	Last Monitor Command
KSHFL	A656	00	Trace Velocity (Note 5)
TOUTFL	A655	00	Hex Keyboard Shift Flag
	A654	B0	In/Out Enable (Note 4)

Figure 4-10. SYSTEM RAM MEMORY MAP, SY6532

SYMBOL	ADDRESS	DEFAULT VALUE	COMMENTS
TECHO	A653	80	Terminal Echo (Note 3)
ERCNT	A652	00	Error Count (Note 2)
SDBYT	A651	4C	Baud Rate (Note 1)
PADBIT	A650	01	Number of Padbits on Carriage Return
PIH	A64F	00	16-Bit Parameters
P1L	A64E	00	
P2H	A64D	00	
P2L	A64C	00	
P3H	A64B	00	
P3L	A64A	00	No. of Parameters Entered
PARNR	A649	00	
	A648	00	
	A647	00	
	A646	00	Not Used
RDIG	A645	3F	
DISBUF	A644	86	Right-most Digit
	A643	6E	
	A642	6D	
	A641	00	
	A640	00	
SCRF	A63F	00	Monitor Scratch Locations SCR0-SCRF
SCR0	A630	00	User Socket P3 (Jump Entry No. 7)
JTABLE	A62F	D0	
	A62E	00	User Socket P2 (Jump Entry No. 6)
	A62D	C8	
	A62C	00	0300 (Jump Entry 5)
	A62B	03	
	A62A	00	0200 (Jump Entry 4)
	A629	02	
	A628	00	0000 (Jump Entry 3)
	A627	00	
	A626	00	NEWDEV (Jump Entry 2)
	A625	8B	
	A624	64	TTY (Jump Entry 1)
	A623	8B	
	A622	A7	BASIC (Jump Entry 0)
	A621	C0	
	A620	00	Scope Buffer, No Defaults (32 locations)
SCPBUF	A61F	--	
	A600	--	

Figure 4-10. SYSTEM RAM MEMORY MAP, SY6532 (Continued)

## NOTES - SYSTEM RAM

- |    |             |            |    |
|----|-------------|------------|----|
| 1. | BAUD RATE - | BAUD SDBYT |    |
|    |             | 110        | D5 |
|    |             | 300        | 4C |
|    |             | 600        | 24 |
|    |             | 1200       | 10 |
|    |             | 2400       | 06 |
|    |             | 4800       | 01 |
- 
- |    |       |   |  |
|----|-------|---|--|
| 2. | ERCNT | - | Used by LD P, FILL, B MOV  |
|    |       |   | Count of bytes which failed to write correctly<br>And invalid checksums up to \$FF |
- 
- |    |       |   |   |
|----|-------|---|---|
| 3. | TECHO | - | bit 7 - ECHO/NO ECHO  |
|    |       |   | bit 6 - OUTPUT/NO OUTPUT    This bit is toggled everytime<br>a control O (ASCII 0F) is<br>encountered in the input<br>stream. |
- 
- |    |        |   |                        |
|----|--------|---|------------------------|
| 4. | TOUTFL | - | bit 7 = enable CRT IN  |
|    |        |   | bit 6 = enable TTY IN  |
|    |        |   | bit 5 = enable TTY OUT |
|    |        |   | bit 4 = enable CRT OUT |
- 
- |    |                     |  |   |
|----|---------------------|--|---|
| 5. | TV - TRACE VELOCITY |  |   |
|    |                     |  | 00 = SINGLE STEP                                |
|    |                     |  | non-zero - PRINT PC, A<br>THEN PAUSE AND RESUME |
|    |                     |  | PAUSE DEPENDS ON TV<br>(TRY TV = 09)            |
- 
- |    |                                  |  |  |
|----|----------------------------------|--|--|
| 6. | USER PC - DEFAULT = 8B4A = RESET |  |  |
|----|----------------------------------|--|--|

Figure 4-10. SYSTEM RAM MEMORY MAP, SY6532 (Continued)

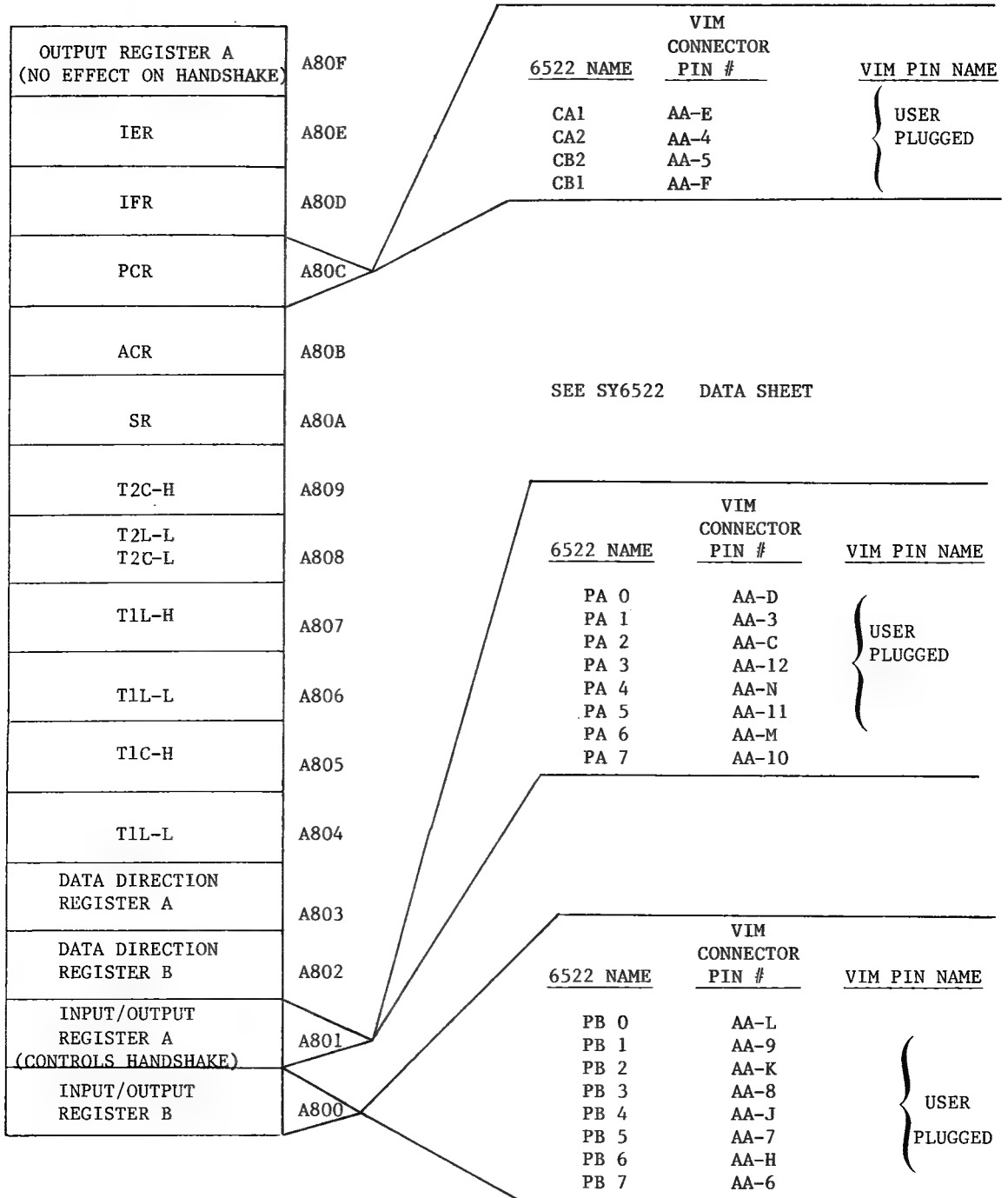


FIGURE 4-10 (CONT'D). MEMORY MAP FOR SY6532 VIA #2 (DEVICE U28)

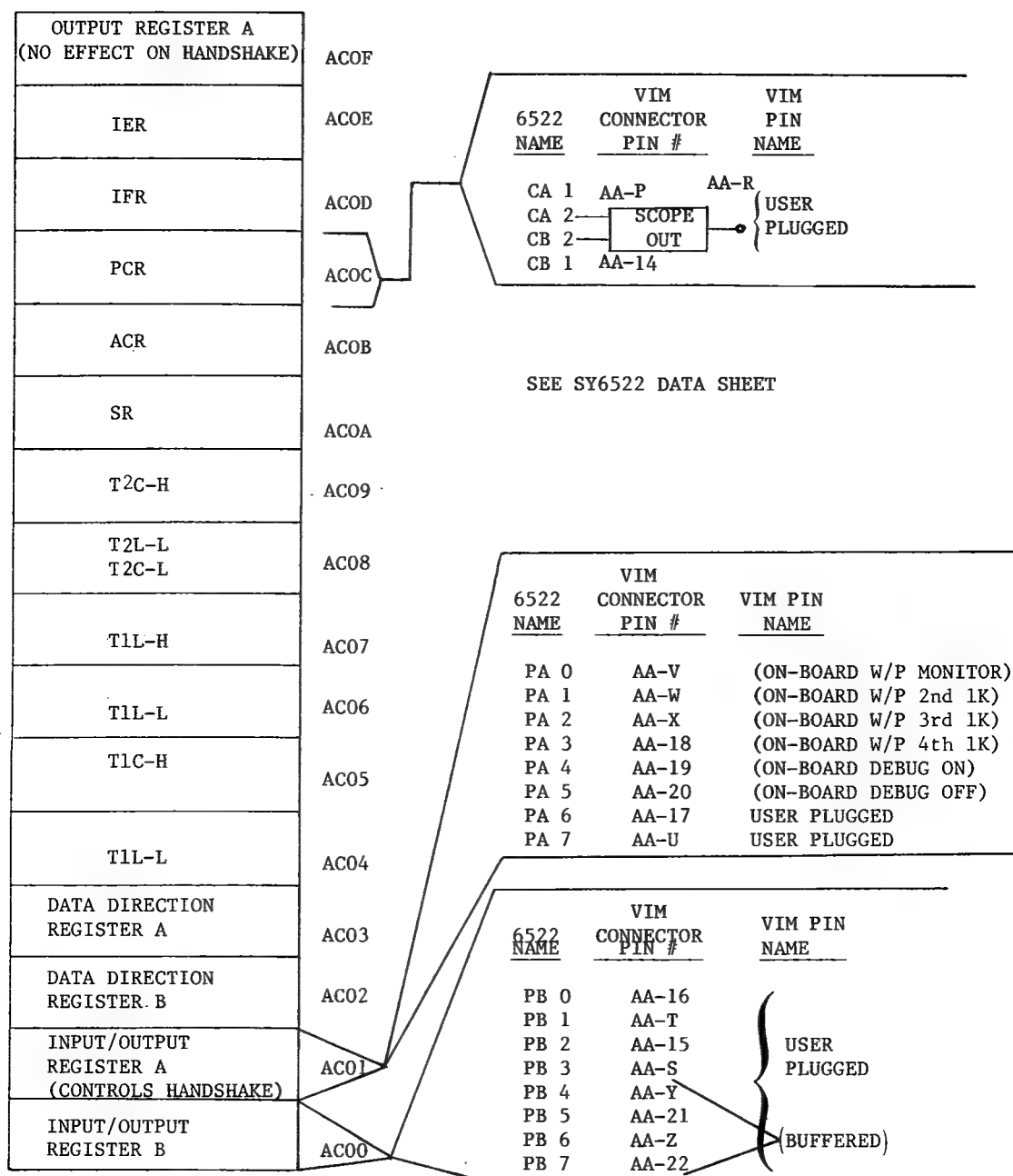


FIGURE 4-10 (CONT'D). MEMORY MAP FOR SY6522 VIA #3 (DEVICE U29)

#### **4.2.2 Address Decoding Jumper Options**

Four sockets (labeled P0-P3 on the board) for ROM PROM or EPROM are provided with your VIM-1. Each socket may contain any of four different types of Read-Only Memory devices, up to a total of 24K. The four acceptable devices are the SY2716, the SY2316B, the SY2332 and the SY2364. Each device is slightly different, but they are all read-only memories. They may appear in any combination on a VIM-1 microcomputer system, provided their total capacity does not exceed 24K. But since the devices have different memory capacities, it is necessary to alter normal addressing to accomodate the specific devices selected.

To serve this purpose, we have provided a set of jumpers, located just to the left of the center of the board and directly under the two 74LS145's. The schematic in Figure 4-11 illustrates each useful jumper combination and Table 4-3 outlines them in greater detail. (Note that Table 4-3 contains other jumpers available on the VIM-1, not all of which pertain to memory use.) The broken lines in Figure 4-11 indicate the jumpers installed at the factory. Note, for example, that the first PROM socket, labeled P0 (device U20) is associated with the address group beginning with 8000. If it were necessary to change this configuration, you would remove the connection from Pin 1 of the lower address decoder (74LS145) to jumper connection 7-J so that it becomes associated with a jumper combination which addresses the device you wish to address. Table 4-3a will assist you in configuring your selection of ROM correctly.

Near the bottom of the board below the speaker unit are four jumpers labeled JJ, KK, LL and MM. These enable Write Protection on the RAM in the four 1K blocks available on the board. Jumper 45-MM is factory-installed, enabling Write Protection on System RAM (the 128-byte block in the SY6532). As you add RAM later, or to Write Protect any of the on-board RAM aside from System RAM, you must connect the appropriate jumpers to enable the Write Protect function on the desired memory locations. RAM may be enabled for Write Protect in 1K blocks.

These jumpers offer you flexibility to adapt the VIM-1 board to your particular application. The jumpers will give you the ability to do the following:

- Use 2K, 4K, or 8K byte ROM or PROM in each 24 pin socket.
- Complete flexibility in selecting user PROM addressing.
- Ability to auto power-on to any of the ROM/PROM sockets.
- Write protect expansion RAM.

#### **4.2.3 Off-Board Expandability**

VIM-1 is expandable, on-board, up to 24K bytes of program memory and 4K bytes of RAM, with 8K bytes of address space allocated to the on-board I/O devices. Further expansion of any combination of ROM, PROM, RAM or I/O can be implemented by using VIM's "E" (Expansion) connector to attach an auxiliary board containing the additional devices. Total expandability is limited only by the amount of addressing capability of the SY6502 CPU, i.e., 64K bytes.

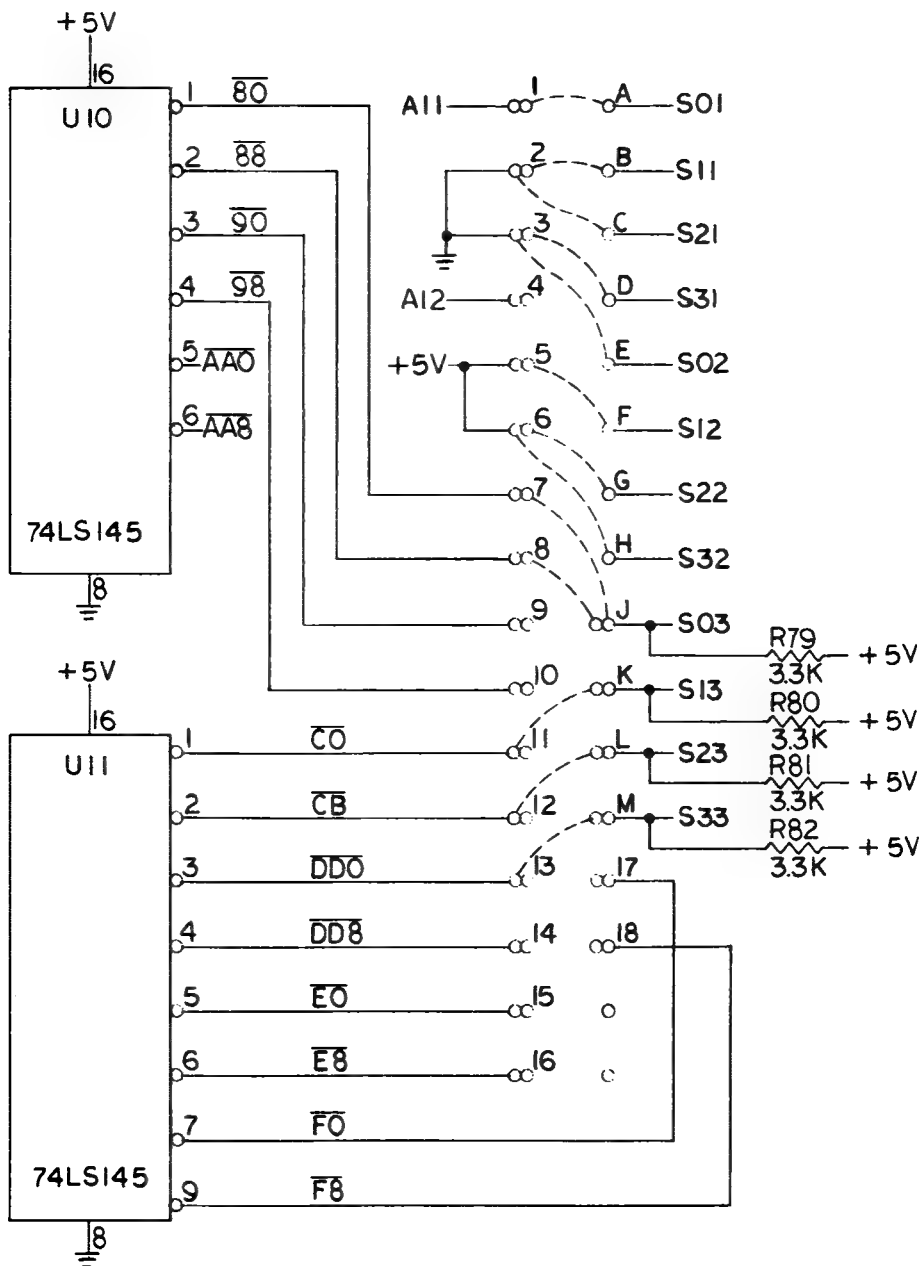
Detailed instructions for implementing off-board expansion are contained in Chapter 8, "System Expansion."

#### **4.2.4 I/O Buffers**

Your VIM-1 board comes to you equipped with four specially configured I/O buffer circuits. (See Figure 4-5.) The circuit configuration and PC Board layout allow the user to configure these buffers in many ways.



# EPROM/ROM JUMPER LOCATIONS AND USAGES



-----CONFIGURATION OF DELIVERED VERSION

Figure 4-11. MEMORY ADDRESS DECODING JUMPER OPTIONS

**Table 4-3. VIM-1 JUMPERS**

<b>JUMPER LETTER</b>	<b>POSITION NUMBER</b>	<b>DESCRIPTION</b>
A,B,C,D E,F,G,H	1,2,3 4,5,6	PROM/ROM Device Select (See Table 4-3a)
J,K,L,M	7,8,9,10,11,12 13,14,15,16,17,18	ADDRESS SELECT (See Table 4-3b)
N	19 (1) 20	Auto Power-On to U20 (2) Disable Auto Power-On to U20
P	19 (1) 20	Auto Power-On to U21 (2) Disable Auto Power-On to U21
R	19 (1) 20	Auto Power-On to U22 (2) Disable Auto Power-On to U22
S	19 (1) 20	Auto Power-On to U23 (2) Disable Auto Power-On to U23
T	21	Enables Monitor RAM at A0xx (3)
U	22	Enables Monitor RAM at F8xx (3)
V	23	RCN-1 to connector A-N
W	24	Enables Software Debug ON
X	25	Enables Software Debug OFF
Y	26	DBOUT to connector E-17
BB	31	Connects TTY IN to PB6 @A402
CC	32	Connects CRT IN to PB7 @A402
DD	33 34	To run TTY @ +5V and GND To run TTY @ +5V and -Vn (4)
EE	35 36	To run TTY @ +5V and GND To run TTY @ +5V and -Vn (4)
FF	37 38	To run TTY @ +5V and GND To run TTY @ +5V and -Vn (4)
GG	39 40	To run RS232 @+5V and GND To run RS232 @+5V and -Vn (5)
HH	41	Decode line T <sub>8</sub> to connector A-K
JJ	42	Enable software write protect 3K block
KK	43	Enable software write protect 2K block
LL	44	Enable software write protect 1K block
MM	45	Enable software write protect monitor RAM

**Table 4-3. VIM-1 JUMPERS (Continued)**

**NOTES**

- 1 Only one socket (U20, U21, U22, U23) should be jumpered to position 19 at one time. The remaining three sockets should be jumpered to position 20.
- 2 See software consideration of auto power-on in Chapter 9.
- 3 One or both can be connected at the same time.
- 4 These positions require a recommended -9V to -15V supply applied to the power connector pin E. R107 should be adjusted (removed and replaced) for your proper current loop requirements.

Example: (for 60ma current loops and  $V_n = -10V$ )

- a. Connect      DD to 33  
                         EE to 35  
                         FF to 38

$$b. \quad R_{107} = \frac{V_n - 5V}{I} = \frac{(10 - 5)}{60 \text{ ma}} \cong 100 \Omega$$

$R_{107} = 300 \Omega$  (as installed) for 20 ma current loop and  $V_n = -10V$

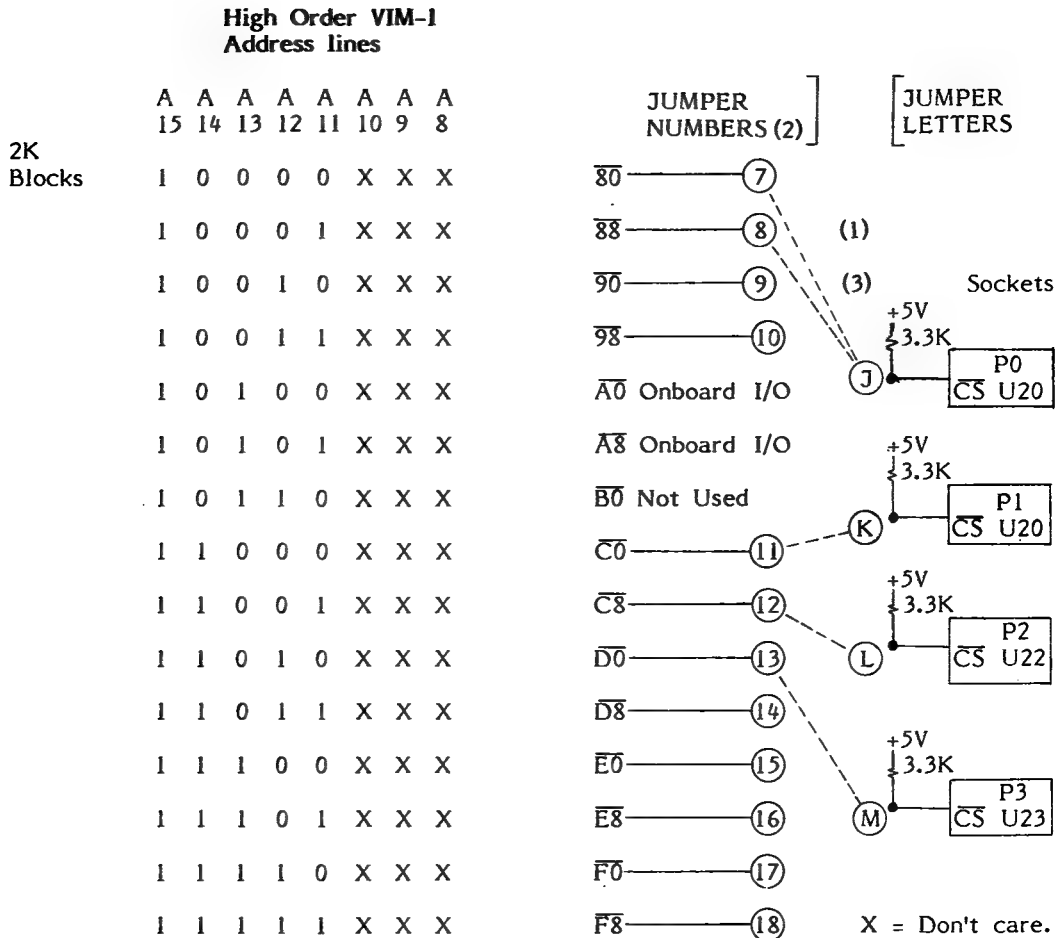
- 5 For RS232 devices using other than LM1489 or equivalent input receivers (i.e., probably terminals older than ten years) then GG should be strapped to 40 and a -9V to -15V supply applied to the power connector pin E.

**Table 4-3a. VIM-1 PROM/ROM DEVICE SELECT**

<b>SOCKET LOCATION</b>	<b>SOCKET NAME</b>	<b>MEMORY DEVICE</b>	<b>JUMPER LETTER</b>	<b>POSITION NUMBER</b>
U20	P0	2716	A E	2 or 3 5 or 6
U20	PO	2316	A E	2 or 3 2 or 3
U20	PO	2332	A E	1 2 or 3
U20	PO	2364	A E	1 4
U21	P1	2716	B F	2 or 3 5 or 6
U21	P1	2316	B F	2 or 3 2 or 3
U21	P1	2332	B F	1 2 or 3
U21	P1	2364	B F	1 4
U22	P2	2716	C G	2 or 3 5 or 6
U22	P2	2316	C G	2 or 3 5 or 6
U22	P2	2332	C G	1 2 or 3
U22	P2	2364	C G	1 4
U23	P3	2716	D H	2 or 3 5 or 6
U23	P3	2316	D H	2 or 3 2 or 3
U23	P3	2332	D H	1 2 or 3
U23	P3	2364	D H	1 4

**NOTE:** 2716 devices assumes Synertek, Intel or equivalent pin outs.

Table 4-3b. VIM-1 ADDRESS SELECT



- NOTES:**
- (1) Broken lines indicate delivered version of jumpers.
  - (2) Each jumper number represents a 2K address space decode.
  - (3) Jumper numbers can be wire or'ed to increase the address space of the CS on any socket (i.e., decoder is open collector.)

The single-stage circuit consists of a transistor and "circuit positions" for the user to add resistors, capacitors and diodes in any of many positions. This flexibility allows inverting and noninverting stages, input-resistive or capacitive coupling and much more. The user should refer to the schematic and P.C. layout in Figure 4-5a in order to completely understand this circuit.

### **4.3 SOFTWARE DESCRIPTION**

Software on your VIM-1 microcomputer must be discussed from two perspectives. First, the VIM SUPERMON Monitor software which handles keyboard display, interrupts and other requirements for system operation must be understood. We will discuss this subject in succeeding sections. The second aspect of software is the microprocessor assembly language with which you will write your applications programs. A brief introduction to the 6502 instruction set is included later in this chapter.

In this chapter, we discuss the VIM-1 command language syntax only briefly; Chapter 5 contains a detailed discussion of each of the instructions in the set. Chapter 6 will help you through the process of using these and the 6502 language in applications programming by describing three selected sample programs.

#### **4.3.1 Monitor Description - General**

Figure 9-1 illustrates the general system flow of the VIM-1 SUPERMON Monitor software. As you can tell, the main program is simple and straightforward. Its purpose is to direct processing to the appropriate I/O or command routine, and for this reason it is thought of as a "driver"--it "drives" or directs the software.

The means by which the Monitor handles the direction of software flow is one of the unique features of the VIM-1 system and is worth a brief explanation at this point. We will discuss the subject in greater detail in Chapters 5 and 8.

When the SUPERMON Monitor receives a one- or two-character command from the on-board keyboard, TTY or CRT terminal, it then accepts 0-3 parameters associated with the command. The string of command and parameters (if any) is terminated by the use of a carriage return. It is noteworthy that each instruction which may be entered by use of a single key on the on-board keyboard may also be entered with a similar command from a terminal.

Upon receiving a command and up to three parameters, SUPERMON checks to determine whether the command and its associated number of parameters is a defined combination. If so, the command is executed. Otherwise, an error message is printed or displayed showing the ASCII representation of the command which was not recognized.

For example, a "GO" with one parameter causes the program to pass control to the program stored at the memory location indicated by the parameter. Thus, a "GO" followed by "0200" instructs the system to begin executing the instructions stored starting at memory location 0200. A "GO" with no parameters (i.e., "GO" followed by a Carriage Return) will cause program execution to resume at the address stored in the "pseudo Program Counter" (memory locations 00FE and 00FF).

However, a "GO" command with two or three parameters is not a defined command in SUPERMON, and will result in a display or message of "Er 47". The "47" is the ASCII representation for a "G" and is designed to help you define the instruction or command which was not recognized.

The monitor is designed so that you can extend the range of defined command-parameter combinations by "intercepting" the error routine before it executes and designing your own series of pointers to memory locations to be associated with specific commands. Thus, you might wish to define a "GET" routine which could be entered at the keyboard with a "GO" and two parameters. You will learn how to do this in Chapter 9.

#### **4.3.2 Software Interfacing**

The VIM-1 Monitor is structured to be device-independent. Special requirements for device handling are "outside" the Monitor's central control routines, which isolate them from the Monitor's standard functions. Also, as we have indicated, VIM-1 commands may be entered from any device. It is not necessary to use the on-board keyboard to do so. This means you need not concern yourself with the details of I/O; they are handled internally. Your only task is developing the software to handle the command structure itself, as we described briefly above.

#### **4.3.3 6502 Microprocessor Assembly Language Syntax**

The SY6502 microprocessor used on your VIM-1 is an eight-bit CPU, which means that eight bits of data are transferred or operated upon at a time. It has a usable set of 56 instructions used with 13 addressing modes. Instructions are divided into three groups.

Group One instructions, of which there are eight, are those which have the greatest addressing flexibility and are therefore the most general-purpose. These include Add With Carry (ADC), the logical AND (AND), Compare (CMP), the logical Exclusive OR (EOR), Load A (LDA), logical OR with register A (ORA), Subtract With Carry (SBC) and Store Register A (STA).

Group Two instructions include those which are used to read and write data or to modify the contents of registers and memory locations.

The remaining 39 instructions in the SY6502 instruction set are Group Three instructions which operate with the X and Y registers and control branching within the program. You'll learn more about these instructions in the next section. More detailed information can be found in the Synertek Programming Manual for the SY6500 family.

An assembly language instruction consists of the following possible parts:

<b>Label</b>	-	Optional. Used to allow branching to the line containing the label and for certain addressing situations.
<b>Mnemonic</b>	-	Required. The mnemonic is a three-character abbreviation which represents the instruction to be carried out. Thus the mnemonic to store the contents of the accumulator in a specific memory location is "STA" ( <u>ST</u> ore <u>Accumulator</u> ).
<b>Operand(s)</b>	-	Some may be required, or none may be allowed. This depends entirely upon the instruction itself and may be determined from the later discussion.
<b>Comment</b>	-	Optional. Separated from last operand (or from the command mnemonic where no operand is used) by at least one blank. These words, are ignored by the assembler program but are included only to allow the programmer and others to understand the program.

The SY6502 allows 13 modes of addressing, which makes it one of the most flexible CPUs on the market. Table 4-4 describes these addressing modes briefly. Details may be found in the Synertek Programming Manual for the SY6502 family.

You will note that some of the addressing modes make use of Page Zero, a concept introduced briefly earlier in this chapter. Page Zero addressing modes are designed to reduce memory requirements and provide faster execution. When the SY6502 processor encounters an instruction using Page Zero addressing, it assumes the high-order byte of the address to be 00, which means you need not define that byte in your program. This technique is particularly useful in dealing with working registers and intermediate values. As the Memory Map (Figure 4-10, Sheet 1) shows, memory locations 0000-00FF make up Page Zero.

#### **4.3.4 SY6502 Instruction Set**

Table 4-5 provides you with a summary of the SY6502 instruction set. Each instruction is shown with its mnemonic, a brief description of the function(s) it carries out, and the corresponding "op code" for each of its valid addressing modes. The "op code" is the hexadecimal representation of the instruction and is what will appear when the instruction byte is displayed by SUPERMON.

When creating applications programs for your VIM-1, you will typically write them in the SY6502 assembly language mnemonic structure shown in Table 4-5, then perform a "hand assembly" to generate the "op codes" and operands. The process of hand assembling code is explained in greater detail in Section 6.2.2. You will be referring to this table—or to your VIM Reference Card—quite frequently during programming.

To understand some of the instructions, you should be aware of six "status register" flags which are set and reset by the results of program execution. Generally, these flags and their functions are:

<b>N</b>	-	Set to "1" by CPU when the result of the previous instruction is negative
<b>Z</b>	-	Set to "1" by CPU when the result of the previous instruction is zero
<b>C</b>	-	Set to "1" by CPU when the previous instruction results in an arithmetic "carry"
		Set to "0" by CPU when the previous instruction results in "borrow" (subtract)
<b>I</b>	-	When "1," this means IRQ to the CPU is disabled
<b>D</b>	-	When "1," this means that CPU arithmetic is operating in decimal mode
<b>V</b>	-	Set to "1" by CPU when the result of the previous instruction causes an arithmetic overflow

No further detail on these status register flags is provided here. The Synertek Programming Manual discusses this subject in greater detail.



Table 4-4. SUMMARY OF SY6502 CPU ADDRESSING MODES

MCS 6502 INSTRUCTION SET SUMMARY

Addressing Modes

Mode	Description	# Bytes	Example
IMPLIED	The operation performed is implied by the instruction.	1* TAX	AA Code for transfer A to X
ACCUMULATOR	The operation is performed upon the A register.	1 ROL A	2A Code for rotate left A
IMMEDIATE	The data accessed is in the second byte of the instruction.	2 LDA #3	A9 Code for load A immediate 03 Constant to use
ZERO PAGE	The address within page zero of the data accessed is in the second byte of the instruction.	2 LDA Z	A5 Code for load A zero page 75 Low part of address on page zero
ZERO PAGE INDEXED BY X	The second byte of the instruction plus the contents of the X register (without carry) is the address on page zero of the data accessed.	2 LDA Z,X	B5 Code for zero page indexed by X 75 Base address on page zero
ZERO PAGE INDEXED BY Y	The second byte of the instruction plus the contents of the Y register (without carry) is the address on page zero of the data accessed.	2 LDX Z,Y	B6 Code for zero page indexed by Y 75 Base address on page zero
ABSOLUTE	The address of the data accessed is in the second and third bytes of the instruction.	3 LDA L	AD Code for load A absolute 47 Low part of address 02 High part of address

\*Except BRK which is two bytes when not using DEMON.

Table 4-4. SUMMARY OF SY6502 CPU ADDRESSING MODES (Continued)

Mode	Description	# Bytes	Example
INDEXED BY X	The address in the second and third bytes of the instruction, plus the contents of the X register is the address of the data accessed.	3	LDA L,X BD 47 02 Code for load A indexed by X Low part of base address High part of base address
INDEXED BY Y	The address in the second and third bytes of the instruction, plus the contents of the Y register is the address of the data accessed.	3	LDA L,Y B9 47 02 Code for load A indexed by Y Low part of base address High part of base address
INDIRECT PRE-INDEXED BY X	The second byte of the instruction plus the contents of the X register (without carry) is the address on page zero of the two-byte address of the data accessed.	2	LDA (Z,X) A1 75 Code for load A, indirect pre-indexed by X Base address on page zero
INDIRECT POST-INDEXED BY Y	The contents of the page zero two-byte address specified by the second byte in the instruction, plus the contents of the Y register is the address of the data accessed.	2	LDA (Z),Y B1 75 Code for load A, indirect post-indexed by Y Base address of page zero
RELATIVE BRANCH	The second byte of the instruction contains the offset (in bytes) to branch address.	2	BEQ LOC F0 07 Code for branch if equal Seven bytes ahead
INDIRECT JUMP	The address in the second and third bytes of the instruction is the address of the address to which the jump is made.	3	JMP (LOC) 6C 47 02 Code for jump indirect Low part of indirect address High part of indirect address

Table 4-5. SY6502 CPU Instruction Set Summary

6502 INSTRUCTION SET SUMMARY																													
Instr	Description	Mode											Condition Codes																
		IMP	ACC	IMM	N	Z, X	Z, Y	ABS	L, X	L, Y	(X, Y)	RET	INH	N	Z	C	I	D	V	B									
ADC	A + M + C → A, C Add memory to accumulator with carry			69	65	75		6D	7D	79	61	71		*	*	*	-	-	*	-									
AND	A ∧ M → A "AND" memory with accumulator			29	25	35		2D	3D	39	21	31		*	*	-	-	-	-	-									
ASL	<table border="1"><tr><td>C</td><td>←</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr></table> Shift left one bit (memory or accumulator)	C	←	7	6	5	4	3	2	1	0		0A		06	16		0E	1E					*	*	*	-	-	-
C	←	7	6	5	4	3	2	1	0																				
BCC	Branch on C = 0 Branch on carry clear												90		-	-	-	-	-	-									
BCS	Branch on C = 1 Branch on carry set												B0		-	-	-	-	-	-									
BEQ	Branch on Z = 1 Branch on result zero												F0		-	-	-	-	-	-									
BIT	A ∧ M, M7 → N, M6 → V Test bits in memory with accumulator				24			2C						M7	*	-	-	-	-	M6									
BMI	Branch on N = 1 Branch on result minus												30		-	-	-	-	-	-									
BNE	Branch on Z = 0 Branch on result not zero												D0		-	-	-	-	-	-									
BPL	Branch on N = 0 Branch on result plus												10		-	-	-	-	-	-									
BRK	Forced interrupt PC ← P + Force break	00													-	-	-	1	-	-	1								

Table 4-5. SY6502 CPU Instruction Set Summary (Continued)

6502 INSTRUCTION SET SUMMARY		Mode										Condition Codes									
Instr	Description	IMP	ACC	IMM	Z	Z,X	Z,Y	ABS	L,X	L,Y	(Z,X)	(Z,Y)	REL	IND	N	Z	C	I	D	V	B
BVC	Branch on V = 0 Branch on overflow clear												50		-	-	-	-	-	-	-
BVS	Branch on V = 1 Branch on overflow set												70		-	-	-	-	-	-	-
CLC	0 → C Clear carry flag	18													-	-	0	-	-	-	-
CLD	0 → D Clear decimal mode flag	D8													-	-	-	-	0	-	-
CLI	0 → I Clear interrupt disable flag	58													-	-	-	0	-	-	-
CLV	0 → V Clear overflow flag	B8													-	-	-	-	-	0	-
CMP	A - M Compare memory and accumulator			C9	C5	D5		CD	DD	D9	CL	D1			*	*	*	-	-	-	-
CPX	X - M Compare memory and index X			E0	E4			EC							*	*	*	-	-	-	-
CPY	Y - M Compare memory and index Y			C0	C4			CC							*	*	*	-	-	-	-
DEC	M - 1 → M Decrement memory by one					D6		CE	DE						*	*	-	-	-	-	-
DEX	X - 1 → X Decrement index X by one	CA													*	*	-	-	-	-	-

Table 4-3. 5Y6502 CPU Instruction Set Summary (Continued)

6502 INSTRUCTION SET SUMMARY		Mode										Condition Codes									
Instr	Description	IMP	ACC	IMM	Z	Z'X	Z,Y	ABS	L,X	L,Y	(Z,X)	(Z,Y)	REL	INT	N	Z	C	I	D	V	B
DEY	Y - 1 → Y Decrement index Y by one	88													*	*	-	-	-	-	-
EOR	A ⊕ M → A "Exclusive-Or" memory with accumulator			49	45 55			4D 5D	59 41 51						*	*	-	-	-	-	-
INC	M + 1 → M Increment memory by one				E6 F6			EE FE							*	*	-	-	-	-	-
INX	X + 1 → X Increment Index X by one	E8													*	*	-	-	-	-	-
INY	Y + 1 → Y Increment index Y by one	C8													*	*	-	-	-	-	-
JMP	(PC + 1) → PCL (PC + 2) → PCH Jump to new location							4C						6C	-	-	-	-	-	-	-
JSR	PC + 2 → , (PC + 1) → PCL (PC + 2) → PCH Jump to new location saving return address							20							-	-	-	-	-	-	-
LDA	M → A Load accumulator with memory			A9	A5 B5			AD BD	B9 A1 B1						*	*	-	-	-	-	-
LDX	M → X Load index X with memory			A2	A6			B6 AE	BE						*	*	-	-	-	-	-
LDY	M → Y Load index Y with memory			A0	A4 B4			AC BC							*	*	-	-	-	-	-

Table 4-5. SY6502 CPU Instruction Set Summary (Continued)

6502 INSTRUCTION SET SUMMARY

6502 INSTRUCTION SET SUMMARY																													
Instr	Description	Mode											Condition Codes																
		IMP	ACC	IMM	Z	Z,X	Z,Y	ABS	L,X	L,Y	(Z,X)	REL	INI	N	Z	C	I	D	V	B									
LSR	0 → <table><tr><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr></table> → <table><tr><td>C</td></tr></table> Shift right one bit (memory or accumulator)	7	6	5	4	3	2	1	0	C	4A	46	56		4E	5E							0	*	*	-	-	-	-
7	6	5	4	3	2	1	0																						
C																													
NOP	No Operation	EA												-	-	-	-	-	-	-									
ORA	A V M → A "OR" memory with accumulator		09	05	15		0D	1D	19	01	11			*	*	-	-	-	-	-									
PHA	A → Push accumulator on stack	48												-	-	-	-	-	-	-									
PHP	P → Push processor status on stack	08												-	-	-	-	-	-	1									
PLA	A ← Pull accumulator from stack	68												*	*	-	-	-	-	-									
PLP	P ← Pull processor status from stack	28																											
ROL	<table><tr><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr></table> ← <table><tr><td>C</td></tr></table> ← M or A Rotate one bit left (memory or accumulator)	7	6	5	4	3	2	1	0	C	2A	26	36		2E	3E							*	*	*	-	-	-	-
7	6	5	4	3	2	1	0																						
C																													
ROR	Rotate One Bit Right (Memory or Accumulator)	6A	66	76		6E	7E						*	*	*	-	-	-	-	-									
RTI	P ← PC ↑ Return from interrupt	40																											
RTS	PC ↑, PC + 1 → PC Return from subroutine	60												-	-	-	-	-	-	-									

**Table 4-5. SY6502 CPU Instruction Set Summary (Continued)**

6502 INSTRUCTION SET SUMMARY												Mode								Condition Codes					
Instr	Description	IMP	ACC	IMM	Z	Z', X	Z, Y	ABS	L, X	L, Y	(X, Z)	(Y, Z)	RET	IND	N	Z	C	I	D	V	B				
SBC	A ← M - $\overline{C}$ → A Note: $\overline{C}$ = Borrow Subtract memory from accumulator with borrow			E9	E5	F5		ED	FD	F9	E1	F1			*	*	-	-	-	*	-				
SEC	1 → C Set carry flag	38													-	-	1	-	-	-	-				
SED	1 → D Set decimal mode flag	F8													-	-	-	-	1	-	-				
SEI	1 → I Set interrupt disable flag	78													-	-	-	1	-	-	-				
STA	A → M Store accumulator in memory				85	95		8D	9D	99	81	91			-	-	-	-	-	-	-				
STX	X → M Store index X in memory				86		96	8E							-	-	-	-	-	-	-				
STY	Y → M Store index Y in memory				84	94		8C							-	-	-	-	-	-	-				
TAX	A → X Transfer accumulator to index X	AA													*	*	-	-	-	-	-				
TAY	A → Y Transfer accumulator to index Y	A8													*	*	-	-	-	-	-				
TSX	S → X Transfer stack pointer to index X	BA													*	*	-	-	-	-	-				

Table 4-5. SY6502 CPU Instruction Set Summary (Continued)

6502 INSTRUCTION SET SUMMARY		Mode											Condition Codes								
Instr	Description	IMP	ACC	IMI	Z	Z,X	Z,Y	ABS	L,X	L,Y	(Z,X)	(Z,Y)	REL	IND	N	Z	C	I	D	V	B
TXA	X → A Transfer index X to accumulator	8A													*	*	-	-	-	-	-
TXS	X → S Transfer index X to stack pointer	9A													-	-	-	-	-	-	-
TYA	Y → A Transfer index Y to accumulator	98													*	*	-	-	-	-	-



## CHAPTER 5

### OPERATING THE VIM

In this chapter you will learn how to operate your VIM-1. The keyboard functions are described, formation of monitor commands is discussed, and procedures for using an audio cassette, TTY or CRT are explained.

As you operate your VIM-1, you will be dealing with the system monitor, SUPERMON, which is a tool for entering, debugging and controlling your 6502 programs. The monitor also provides a wealth of software resources (notably subroutines and tables) which are available to your applications programs as they run on the VIM-1 system.

SUPERMON is a 4K-byte program which is stored on a single ROM chip located at addresses 8000-8FFF, as you learned in Chapter 4. It also uses locations 00F8-00FF for special purposes and a special location called "System RAM" located at addresses A600-A7FF. These usages were outlined in detail in Chapter 4 and in the Memory Map.

Operationally, SUPERMON gets commands, parameters and data from its input channels (the HEX Keyboard, HKB; a teletype, TTY; a CRT terminal or RAM memory and others) and, based on this input, performs internal manipulations and various outputs (to the on-board LED display, TTY or CRT terminal screen or other peripheral devices).

#### 5.1 KEYBOARD LAYOUT

The VIM-1 keyboard (see Figure 5-1) consists of 28 color-coded dual-function keys. The characters and functions on the lower half of the keys are entered by pressing the keys directly. To enter the functions shown in the upper halves of the keys, press SHIFT before you press the key you wish to enter. Remove your finger from SHIFT before pressing the second key. Very little pressure is necessary to actuate a key, and except for DEBUG, you will hear an audible tone when the computer senses that a key has been pressed. RST will cause a beep after a short delay.

The functions included on the VIM-1 provide you with a formidable array of programming tools. You can examine and modify the contents of memory locations and CPU registers, deposit binary or ASCII data in memory, move blocks of data from one area of memory to another, search memory for a specific byte, and fill selected memory locations with a specified data byte. You can also store a double byte of data with a single command, display the two's complement of a number, or compute an address displacement.

The RST, DEBUG ON and DEBUG OFF keys do not transmit any characters to the monitor, but perform the functions indicated by their names directly using hardware logic.

#### 5.2 VIM COMMAND SYNTAX

As we have indicated earlier, each VIM-1 command entered from the on-board keyboard or other device may have from 0-3 parameters associated with it. Each command, with its string of parameters, is terminated by a "CR" (on the HKB) or a carriage return on a terminal device.

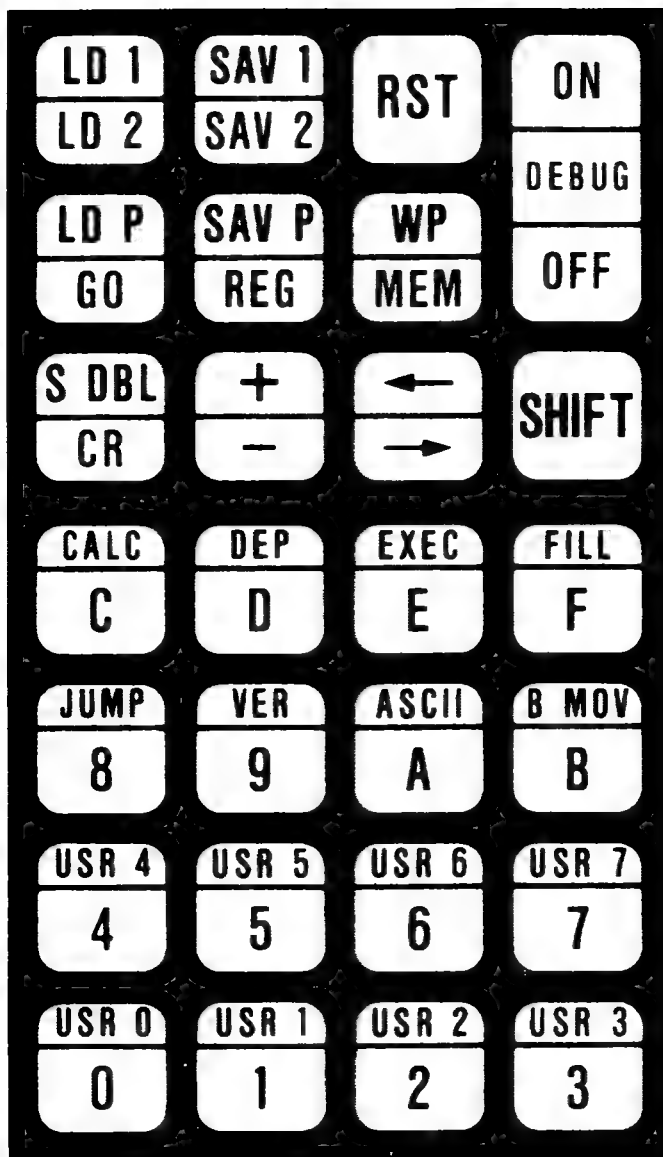


Figure 5-1. VIM-1 KEYBOARD

Table 5-1 summarizes the VIM-1 command set. The first column indicates the command, in both HKB and terminal format. The values (1), (2), and (3) refer to the values of the first, second, and third parameters entered. The term "old" is used to mean the memory location most recently referenced by any of the following commands: M, D, V, B, F, SD, S1, S2, SP, L1, L2, LP. All of these commands use locations 00FE and 00FF as an indirect pointer to memory; where a reference to "old" (or OLD) in some cases) occurs, the former value remains in the memory pointer locations 00FE-00FF.

Note that in the second column of Table 5-1 we have provided you with the ASCII code for each instruction. Several of the commands do not have associated ASCII codes and use instead a computed "hash code." Hash codes are marked with an asterisk. You need not concern yourself with the means by which the hash code is determined, but you should note that VIM will display these values when the commands are entered with an incorrect syntax, i.e., if you make an error when entering these commands.

Table 5-2 provides you with a brief summary of the additional keys found on the on-board keyboard of the VIM-1. These are operational and special keys which do not generally have parameters associated with them, with the exception of the special user-function keys.

In the discussion of each monitor command which follows, the same basic format is followed. First, the appropriate segment of Table 5-1 is reproduced, for easy reference. Next, the command is described in some detail. Examples are used where they will make understanding the monitor command easier.

Because it is believed that most users of the VIM-1 will ultimately use a TTY to enter and obtain printouts of instruction strings, the remainder of Chapter 5 is designed to use the TTY keyboard function designations rather than those of the on-board keyboard. Remember, though, that both keyboards are functionally the same as far as SUPERMON is concerned. For this reason, we are also using a comma as a delimiter in the command string; the minus sign on the on-board keyboard (or, for that matter, on the TTY or CRT keyboard) may also be used for this purpose.

**Table 5-1. VIM-1 COMMAND SUMMARY**

Command	Code	Number of Associated Parameters			
		0	1	2	3
MEM M	4D	Memory Exam- ine and mod- ify, begin at (OLD)	Memory Exam- ine and mod- ify, begin at (1)	Memory Search for byte (1), in locations (OLD) - (2)	Memory Search for byte (1), in locations (2) - (3)
REG R	52	Examine and modify user registers PC, S,F,A,X,Y			
GO G	47	Restore all user registers and resume execution at PC	Restore user registers ex- cept PC = (1) S = FD, mon- itor return address is on stack		
VER V	56	Display 8 bytes with checksum be- ginning at (OLD)	Display 8 bytes with checksum be- ginning at (1)	Display (1)-(2), 8 bytes per line, with addresses and cumulative checksums	
DEP D	44	Deposit to memory, be- ginning at (OLD). CRLF/ address after 8 bytes, auto spacing	Deposit to memory, be- ginning at (1)		
CALC C	43		Calculate 0-(1) or two's com- plement of (1)	Calculate (1)-(2) or displacement	Calculate (1)+(2)-(3) or displacement with offset
BMOV B	42				Move all of (2) thru (3) to (1) thru (1)+(3)-(2)

Table 5-1. VIM-1 COMMAND SUMMARY (Continued)

Command	Code	Number of Associated Parameters			
		0	1	2	3
JUMP J	4A		Restore user registers except PC= entry (1) of JUMP TABLE, S=FD, monitor return on stack		
SDBL SD	*10			Store high byte of (1) in (2) + 1 then lo byte of (1) in (2), good for changing vectors	
FILL F	46				Fill all of (2) - (3) with data byte (1)
WP W	57		Write protect user RAM according to lo 3 digits of (1)		
LD1 L1	*12	Load first KIM format record found into locations from which it was saved	Load KIM record (1) must = FF with ID = (1) into locations from which it was saved	load first KIM record found, but start at location (2)	
LD2 L2	*13	Load first hi speed record found into locations from which it was saved	load hi speed record with ID = (1)		(1) must = FF load first hi speed record found into (2) - (3)
LDP LP	*11	Load paper tape in demon format. To signal end of file for tape without EOF record, type ;00 CR in on-line mode.			

Table 5-1. VIM-1 COMMAND SUMMARY (Continued)

Command	Code	Number of Associated Parameters			
		0	1	2	3
SAVP SP	*IC			Save paper tape locations (1) - (2) in demon format. To create end of file record, unlock punch, switch to local mode, lock punch, type ;00 <b>CR</b>	
SAV1 S1	*ID				Save cassette tape locations (2) - (3) with ID = (1) KIM format
SAV2 S2	*IE				Save cassette tape locations (2) - (3) with ID = (1) hi speed format
EXEC E	45		Get monitor input from RAM, starting (1)	Get monitor input from RAM, starting (2) and store (1) for later use	Get monitor input from RAM, starting (3) and store (1) and (2) for later use.

**Table 5-2. OPERATIONAL AND SPECIAL KEY DEFINITION  
(ON-BOARD KEYBOARD ONLY)**

Command	ASCII or *Hash Code	Description/Use
CR	OD	Carriage Return (terminates all command strings)
+	2B	Advance eight bytes
-	2D	Retreat eight bytes; also used to delimit parameters
→	3E	Advance one byte or register
←	3C	Retreat one byte
USRO USR1 USR2 USR3 USR4 USR5 USR6 USR7	*14 *15 *16 *17 *18 *19 *1A *1B	All USR keys transmit the indicated Hash Code when entered as a command. The same hash codes can be sent from another terminal by entering UO (two characters, no spaces) through U7 as commands. These functions are not defined in SUPERMON and will cause the monitor to vector through the unrecognized command vector. See Chapter 9 for instructions on using this SUPERMON command feature to program your own special functions.
SHIFT	None	
RST	None	
DEBUG ON	None	
DEBUG OFF	None	
ASCII	None	

### 5.3 VIM-1 MONITOR COMMANDS

#### 5.3.1 M (Display and/or Modify Memory)

Number of Associated Parameters			
0	1	2	3
Memory Examine and modify, begin at (OLD)	Memory Examine and modify, begin at (1)	Memory Search for for byte (1), in locations (OLD)-(2)	Memory Search for byte (1), in locations (2)-(3)

- The standard form for this command uses one parameter and is shown below.

#### M addr CR

SUPERMON will then display the address and the byte contained in the location "addr." The following options are then available:

1. Enter 2 Hex digits: bb is replaced and the next address and byte are displayed.
2. Enter single quote (from terminal) and any character: bb is replaced with the ASCII code for the entered character.
3. Enter > or < (> or < from terminal): bb is left unchanged and addr+1 or addr-1, with its contents, is displayed.
4. Enter + or - : bb is left unchanged and addr+8 or addr-8 with its contents, is displayed.
5. Enter CR : Return to monitor command mode; bb unchanged.

- Another form of the display memory command uses no parameter as shown below:

#### M CR

This will cause VIM-1 to resume memory examine and modify at (OLD).

- The same memory (M) key may be used to search for a particular byte in memory, using three parameters in this form:

#### M bb,addr1,addr2 CR

This instructs the system to search for byte bb from addr1 to addr2. When an occurrence of bb is found, the location and contents are displayed, and all of the standard M options described above become available. In addition, a "G" entered following any halt will continue the search.



- Similarly, the two parameter sequence:

**M bb,addr CR**

will resume memory search for byte bb from (OLD) to addr.

The following examples demonstrate the various uses of memory display/modify commands. Characters entered by the user are underlined.

### One Parameter

<pre> .M <u>1</u> 0215, BB, <u>1</u> </pre>	<p>Display memory location (OLD); return to Monitor</p>
<pre> .M <u>A656</u> A656, 00, <u>0A</u> A657, 40, <u>1</u> </pre>	<p>Display memory location A656 Put some data there; return to Monitor</p>
<pre> .M <u>200</u> 0200, 20, <u>'A</u> 0201, 86, <u>'B</u> 0202, 88, <u>'C</u> 0203, 20, <u>1</u> </pre>	<p>Display memory location 200 Replace data with ASCII code for A Next location displayed; replace data with ASCII B Next location displayed; replace data with ASCII C Return to Monitor</p>
<pre> .M <u>0200</u> 0200, 41, <u>&gt;</u> 0201, 42, <u>&gt;</u> 0202, 43, <u>_</u> 0203, 20, <u>_</u> 0204, AF, <u>1</u> </pre>	<p>Display memory location 200 Display next location; data unchanged Display next location; data unchanged Use space bar for same purpose as arrow  Return to Monitor</p>
<pre> .M <u>0300</u> 0300, B4, <u>&lt;</u> 02FF, BB, <u>&lt;</u> 02FE, 44, <u>&lt;</u> 02FD, BB, <u>1</u> </pre>	<p>Display memory location 300 Display previous location; data unchanged   Return to Monitor</p>
<pre> .M <u>0200</u> 0200, 41, <u>+</u> 0208, F0, <u>_</u> 0209, 06, <u>_</u> 020A, 20, <u>_</u> 0202, 43, <u>1</u> </pre>	<p>Display memory location 200 Advance 8 bytes and display memory Space used to advance one location; data unchanged  Reverse 8 bytes and display memory Return to Monitor</p>
<pre> .M <u>0200</u> 0200, 41, <u>1</u> .M <u>1</u> 0200, 41, <u>1</u> </pre>	<p>Display memory location 200 Return to Monitor Display (OLD) which is still 200 Return to Monitor</p>

## Two and Three Parameters

<u>.M 6C,8000,8400</u>	Search for 6C in range 8000-8400
801F,6C, _	
8017,29, <u>↓</u>	
<u>.U</u>	
8017 29 10 F0 07 6B AA 6B 28,D2	
02D2	
<u>.M 6C,8400</u>	Continue search
801F,6C, _	
8020,F6, _	
8021,FF, <u>G</u>	Continue search
8026,6C, _	
8027,F8, _	
8028,FF, <u>↓</u>	Halt search
.	

### 5.3.2 R (Display and/or Modify User Registers)

Number of Associated Parameters			
0	1	2	3
Examine and modify user registers PC,S,F,A,X,Y			

- The only pre-defined form of this command is with no parameters, i.e.:

#### R CR

As soon as the command is entered, the contents of the PC are displayed as follows:

P 8B4A,

Using a forward arrow (→ or >), you may examine the next register. Registers are displayed in the order PC, S, F, A, X, Y, with wrap-around (i.e., PC is displayed after Y). Each register except PC carries a Register Number on the display or TTY printout; S is R1, F is R2, A is R3, X is R4, and Y is R5 (see example below).

To modify the displayed register, enter two or four digits (four only in the case of the PC). The register will be automatically modified and the next will be displayed. A CR will cause control to return to the monitor for another command.

In the following example, we have modified the contents of the PC register to become 0200, and the A register to be set to 16. The other registers are not modified and at the conclusion of the complete register cycle and redisplay of PC, a CR is used to return to monitor command mode.

•R↓	Display registers
P 8B4A, _	PC; space is used to advance
R1 FF, _	S
R2 00, _	F
R3 00, _	A
R4 00, _	X
R5 00, _	Y
P 8B4A, ↓	PC re-displayed; return to Monitor
•	
•R↓	
P 8B4A, 0200	
R1 FF, >	
R2 00, _	
R3 00, 16	Alter PC = 200, A = 16
R4 00, ↓	
•	

### 5.3.3 G (GO)

Number of Associated Parameters			
0	1	2	3
Restore all user registers and re-suspend execution at PC	Restore user registers except PC = (1) S = FD; monitor return address is pushed onto stack		

- The GO command may be used with no parameters to restore all user registers and begin execution at PC:

#### G CR

- With one parameter, the command will restore user registers except that PC is set to addr, S is set to FD and SUPERMON's return address is pushed onto the stack. Thus, if a subroutine return is executed, it will result in a return to monitor command mode (with the user's stack not saved). Its format is as follows:

G addr CR

### 5.3.4 V (VERIFY)

Number of Associated Parameters			
0	1	2	3
Display 8 bytes with checksum beginning at (OLD)	Display 8 bytes with checksum beginning at (1)	Display (1)-(2), 8 bytes per line, with addresses and cumulative checksums	

- With **one parameter**, this command will result in the display of 8 bytes beginning at addr, with checksum. The format is as follows:

#### V addr CR

In this example, bytes stored in locations 200-207 are displayed, along with their checksum:

```
.V 200↓
0200 41 42 43 20 AF 88 C9 0D,F3
02F3
.
```

Note that on the on-board display, only the two-byte checksum will be visible.

The checksum is a 16-bit arithmetic sum of all of the data bytes displayed. The low byte is displayed on the data line, and the full checksum on the next. The address is not included in the checksum.

- With **no parameters**, the command will display 8 bytes beginning at (OLD).

#### V CR

```
.V↓
0200 41 42 43 20 AF 88 C9 0D,F3
02F3
.
```

- With **two parameters**, the "V" command will display memory from addr1 through addr2. 19 bytes per line are displayed, with cumulative checksums. A single byte checksum is included on each data line, and a final two-byte checksum is printed on a new line.

#### V addr1,addr2 CR

```
.V 8000,8015↓
8000 4C 7C 8B 20 FF 80 20 4A,5C
8008 81 20 71 81 4C 03 80 08,C6
8010 48 8A 48 BA BD 04,5B
085B
.
```

### 5.3.5 D (Deposit)

Number of Associated Parameters			
0	1	2	3
Deposit to memory, beginning at (OLD), CRLF/address after 8 bytes, auto spacing	Deposit to memory, beginning at (1)		

- This command is used for entering data to memory from a terminal. With one parameter, this command instructs the system to output a **CR** and line feed and print addr. As each two-digit byte is entered, a space is output. If you enter a space (instead of a two-digit byte), you will cause two more spaces to be output, and that memory location will remain unchanged.

#### D addr **CR**

```
.D 200↓
0200 A9 3A 85 46 20 13 08 20
0208 EE 08 85 44 84 45 C6 46
0210 D0 F2 60 ↓
.
```

- As with other commands, the "D" with no parameters will deposit beginning at (OLD).

#### D **CR**

Notice that V and D line up, so that a line displayed with V may be altered with D, as shown below:

```
.V 200↓
0200 A9 3A 85 46 20 13 08 20,09
0209
.D ↓
0200 _ 0D _ 45 _ 80 03 ↓
.V 200↓
0200 A9 0D 85 45 20 80 03 20,43
0243
.
```

Verify contents of 0200-0207  
Checksum  
Deposit memory from 0200; space to advance  
Re-verify contents of 0200-0207  
New checksum

### 5.3.6 C (Calculate)

Number of Associated Parameters			
0	1	2	3
	Calculate 0-(1), the two's complement of (1)	Calculate (1)-(2) or displacement	Calculate (1)+(2)-(3) or displacement with offset

This command is used to do Hexadecimal arithmetic. It is very useful in programming to compute operands required for SY6502 instructions.

- With one parameter, it calculates 0 minus addr (i.e., the two's complement).

#### C addr CR

- With two parameters, the "C" command will calculate addr1 minus addr2 (i.e., displacement).

#### C addr1, addr2 CR

- With three parameters, the "C" command will calculate addr1 minus addr2 plus addr3 (i.e., displacement with offset).

#### C addr1,addr2,addr3 CR

### 5.3.7 B (Block Move in Memory)

Number of Associated Parameters			
0	1	2	3
			Move all of (2) thru (3) to (1) thru (1)+(3)-(2)

- This command is only defined for three parameters and is demonstrated by the following examples:

.B 200,300,320  
.

Move 300 thru 320 to 200 thru 220.

.B 200,220,250  
.

Move 220 thru 250 to 200 thru 230. (The direction of the move is such that no data is lost, even though the regions overlap.)

.B 220,200,230  
.

Move 230 thru 200 to 250 thru 220. (Note that this move occurs in the opposite direction. No data is lost.)



### 5.3.8 J (JUMP)

Number of Associated Parameters			
0	1	2	3
	Restore user registers except PC=entry (1) of JUMP TABLE, S=FD, monitor return pushed on stack		

- This command is only defined for one parameter.

#### J n CR

The parameter, n, must be in the range 0-7. All user registers are restored, except PC is taken from the JUMP TABLE in System RAM, and S=FD. The monitor return address is pushed onto the stack.

(Because the monitor return is on the stack, a JUMP to a subroutine is allowable.)

Note also that certain useful default addresses are inserted in the JUMP TABLE at Reset. (See Memory Map.)

### 5.3.9 SD (Store Double Byte

Number of Associated Parameters			
0	1	2	3
		Store high byte of (1) in (2)+1 then low byte of (1) in (2). Good for changing vectors	

- This command is defined only for two parameters and is most useful for changing vectors.

#### SD addr1,addr2 CR

The example below was used to enter the address of the Hex keyboard input routine into INVEC, in correct order (low byte-high byte). Note that this vector could not have been altered with M, because after one byte had been altered, the vector would have pointed to an invalid address.

```
.SD 89BE,A661
```

```
.
```

### 5.3.10 F (Fill)

Number of Associated Parameters			
0	1	2	3
			Fill all of (2)-(3) with data byte (1)

- Defined only for **three parameters**, this command will fill the defined region of memory (addr1-addr2) with a specified byte (bb).

**F bb,addr1,addr2 CR**

For example:

**F EA,200,300**

Fill the region 200 thru 300 with the byte EA, which is a NOP instruction.

### 5.3.11 **W (Write Protect)**

Number of Associated Parameters			
0	1	2	3
	Write protect user RAM according to 3 digits of (1)		

- This command is defined for only one parameter. To unprotect all of user RAM, the command is:

#### **W 0 CR**

Its general form is:

#### **W d<sub>1</sub>d<sub>2</sub>d<sub>3</sub> CR**

Where each of d<sub>1</sub>, d<sub>2</sub>, d<sub>3</sub> are the digits 0 (unprotect) or 1 (protect).

d <sub>1</sub> = 400-7FF	1K above first K of RAM
d <sub>2</sub> = 800-BFF	2K above first K of RAM
d <sub>3</sub> = C00-FFF	3K above first K of RAM

For example

• W 101

1	protect 400-7FF
0	unprotect 800-BFF
1	protect C00-FFF

Note that write protect applies to extended user RAM on-board, and also that it requires a jumper insertion (see Chapter 4).

### 5.3.12 E (Execute)

Number of Associated Parameters			
0	1	2	3
	Get monitor input from RAM, starting at (1)	Get monitor input from RAM, starting at (2) and store (1) for later use at A64C	Get monitor input from RAM, starting at (3) and store (1) and (2) for later user at A64E and A64C

- The standard form of the execute command uses one parameter.

#### E addr CR

SUPERMON adjusts its INPUT vectors to receive its input from RAM, beginning at addr. It is assumed that the user has entered a string of ASCII codes into RAM locations beginning at addr, terminated by a byte containing 00. When 00 is encountered, input vectors will be restored. The easiest way to enter these codes is to use the M command with the single-quote option (Section 5.3.1).

When E is used with two or three parameters, the additional parameters will be stored in system RAM at A64C and A64E. It is the user's responsibility to interpret them. (Note that the E command is vectored; see Chapter 9.)

```
•U 300↓
0300 'C 'F 'F 'F 'E ' , 00 ↓
•
```

The sequence at 300 is part of a commonly used Calculate routine.

```
•E 300↓
•C FFFE,200,280↓
FF7E
•
```

Notice that part of this C command came from RAM, and part was entered at the terminal.

## 5.4 CASSETTE AND PAPER TAPE COMMANDS

The VIM-1 handles cassette I/O in two formats, KIM-compatible format (8 bytes/sec), and VIM high-speed format (185 bytes/sec).

The S1 and L1 commands refer to KIM format, while the S2 and L2 commands refer to VIM high-speed format.

With each Save command you specify a two-digit ID, as well as starting and ending addresses. The ID, the addresses, and the contents of all memory locations from starting to ending address, inclusive, will be written to tape. Each Save command will create one **RECORD**.

You should be careful to assign unique ID's to different records on the same tape, and to label the tape with the ID's and addresses of all the records it contains.

While VIM is searching for a record or trying to synchronize to the tape, an "S" will be lit in the left-most digit of the display on the on-board keyboard. If the "S" does not turn off, VIM is unable to locate or to read the requested record.

### 5.4.1 S1, S2 (Save Cassette Tape)

Number of Associated Parameters			
0	1	2	3
(S1)			Save cassette tape, locations (2) - (3) with ID = (1) in KIM format
(S2)			Save cassette tape, locations (2) - (3) with ID = (1) in High Speed format

- These commands are discussed together, as their syntax is identical. Recall that S1 refers to KIM format while S2 refers to VIM high-speed format.

Both are defined only for three parameters.

S2 bb,addr<sub>s</sub>,addr<sub>e</sub> CR

The first parameter is a 2-digit ID, which may be any value other than 00 or FF. It is followed by the starting address and the ending address. In the example below, all memory locations from 0200 thru 0222, inclusive are written to tape, and given the ID 05.

• S1 5,200,280)

#### 5.4.2 L2 (Load High-Speed Format Record)

Number of Associated Parameters			
0	1	2	3
Load first Hi Speed record found into locations from which it was saved	Load Hi Speed record with ID = (1)		(1) must = FF. Load first Hi Speed record found into (2) - (3)

- The standard form of this command uses one parameter, as follows:

##### L2 bb CR

The parameter bb is the ID of the record to be loaded. When found, the record will be loaded into memory, using the addresses saved in the record itself.

If the record bb is not the first high-speed record on the tape, the "S" light will go out as VIM reads through, but ignores, the preceding records. After each unselected record is read, the "S" will re-display.

- With no parameters (or a single parameter of zero), the instruction will load the first high-speed format record found, without regard to its ID, using the addresses saved in the record itself.

##### L2 CR

or

##### L2 0 CR

- The L2 command exists in a third form, using three parameters, as follows:

##### L2 FF,addr1,addr2, CR

This usage will load a record into a **different** area of memory from where it was saved. The first parameter **must** be FF, followed by the requested starting and ending address. It is your responsibility to supply addr1 and addr2 such that their difference is the same as the difference of the addresses used to save the record.

### 5.4.3 L1 (Load KIM Format Record From Tape)

Number of Associated Parameters			
0	1	2	3
Load first KIM format record found into locations from which it was saved	Load Kim record with ID = (1) into locations from which it was saved	(1) must = FF. Load first KIM record found, but start at location (2)	

- The L1 command, used with zero or with one parameter, is identical in syntax to the L2 command (see Section 5.4.2, above).
- With two parameters, the L1 command is used to load into a different region of the memory than that with which the record was saved.

#### L1 FF,addr CR

The first parameter must be FF, followed by the requested starting address. No ending address is necessary, as the load operation will halt when the end of the record is found.

### 5.4.4 SP (Save Paper Tape)

Number of Associated Parameters			
0	1	2	3
		Save paper tape locations (1) - (2) in DEMON format. To create end of file record, unlock punch, switch to local mode, lock punch, type ;00 CR	

- Defined only for two parameters, this command will save data from RAM in DEMON paper tape format (see Appendix F).

#### SP addr1,addr2 CR

For example:

```
.SP 200,215)
;10020034AB743B44BB44BB44BB44BB44BB44BB079A
;060210AC1BF49BD4BB03FD
```

#### 5.4.5 LP (Load Paper Tape)

Number of Associated Parameters			
0	1	2	3
Load paper tape in DEMON format. To signal end of file for tape without EOF record, type ;00 CR in on-line mode			

- This command is defined for no parameters only. It will load memory with data in DEMON paper tape format (see Appendix F).

#### LP CR

### 5.5 USER-DEFINED FUNCTIONS

You may, as we have previously pointed out, write programs to be called from the on-board keyboard. You may do this by using any combination of command and number of parameters which is not already defined (e.g., B MOV with only two parameters) or by using any or all of the eight keys along the bottom two rows of the on-board keyboard (those labeled "USR 0" through "USR 7"). The exact means of implementing these special functions is discussed in detail in Chapter 9.

### 5.6 ERROR CODES

The VIM-1 microcomputer system handles error codes in an interactive way, with codes being designed to be determined by the context in which the error occurs. No table of error conditions and their meanings is therefore provided with this manual, since these are context dependent.

However, you should be aware of the general method by which errors are handled by your VIM-1 system.

When your SUPERMON encounters an error of some type, it displays a 2-digit representation of the byte which was being processed when the error was detected. For example, if you attempt to carry out a CALC command with no parameters (and you haven't defined such a routine yourself as explained in Chapter 9), the system will display a "43." which is the ASCII representation for the "C" which represents the CALC function.



Similarly, if you attempt to use an ID of 00 or FF with either SAV1 or SAV2, the system will display the ID used in error.

After the "er" message is printed, a new prompt (decimal point) is displayed, and SUPERMON waits for a new command. Note that you do not need to RESET when an error condition occurs, since that results in System RAM being cleared and necessitates a re-start of your routine. It is also worth noting that when you carry out an EXEC command at the on-board keyboard the system does not halt when an error occurs; rather, it continues in the same fashion as if new commands were coming directly from the keyboard. The error condition therefore flashes too rapidly on the LED display for you to see it. Command sequences to be executed by EXEC should be pretested prior to such use.

Some fixed error codes do exist in the monitor. Four such codes are used in audio cassette operations and are defined in Table 5-3. Additionally, if in carrying out LD P, FILL or B MOV commands you either attempt to store data in a non-existent or WRITE-protected memory location or if during execution of one of these commands a memory error occurs, the LED display will show the number of locations read incorrectly. This number will always stop at "FF" if it exceeds that number, so that the display will have some intelligible meaning.

**Table 5-3. ERROR CODES IN AUDIO CASSETTE OPERATIONS**

Code Displayed	Meaning
2F	Last-character error. The last character in a tape record should be a 2F. If that is not the case, the system displays the error code shown.
CC	Checksum error. Usually indicates data transfer problems. Re-position the tape and try again.
FF	In KIM-1 format loading, this error code means a non-Hexidecimal character has been encountered. This almost always means a synchronization error. Restart the procedure.
	In High-Speed format loading, a framing (i.e., synchronization) error is the cause. Restart the procedure.

The following examples provide some representative errors to enable you to become familiar with how they are reported on VIM-1 using a TTY or CRT.

.W 111 ✓  
 .F EA,300,400 ✓  
 ER 01

Memory location 400 write protected, therefore it could not be modified. One byte only in error.

.S2 200,280 ✓  
 ER 1E

S2 is not defined for two parameters. The hash code for S2 is 1E.

.C A,230,500,  
 ER 2C

Three parameters only permitted.

.C 200,2X  
 ER 58

X is not a valid Hex digit.

.S2 FF,200,280 ✓  
 ER FF

ID may not be FF or 00.

.L2 AA,200,280 ✓  
 ER AA

ID must be FF.

.M 6000 ✓  
6000,60,F5?  
6001,60, ✓

No RAM at 6000, therefore it cannot be modified.

.D 8000 ✓  
8000 AA? DD?  ✓

ROM at 8000, therefore it cannot be modified

.D 200,280 ✓  
 ER 44

Deposit not defined for 2 parameters. D = ASCII 44.

.F EA,5000,6000 ✓  
 ER FF

No RAM at locations 500-6000, therefore no modification was possible. The number of bytes which were not correctly changed is greater than or equal to 255 (decimal).

## **CHAPTER 6**

### **PROGRAMMING THE VIM-1**

Creating a program on the VIM-1 involves several steps. First, the input to the program and its desired output must be carefully defined. The flow of program logic is usually worked out graphically in the form of a flowchart. Next, the symbols on the flowchart are converted to assembly language instructions. These instructions are in turn translated into machine language, which is entered into memory and executed. If (as usual) the program does not run correctly the first time, you must debug it to uncover the errors in the program. This chapter illustrates the steps involved in creating a program to add two 16-bit binary numbers, and provides two other programming problems with suggested solutions. All three programs are designed to communicate basic programming principles and techniques and to demonstrate a programmer's approach to simple problems.

#### **6.1 HARDWARE**

All the sample programs listed here can be loaded and run on the basic VIM-1 with the minimum RAM. The only I/O devices required are the on-board keyboard and display.

If a printing or display terminal is available, by all means use it instead of the Hex keyboard provided. Both types are more comfortable for most users and allow much more data to be displayed at once.

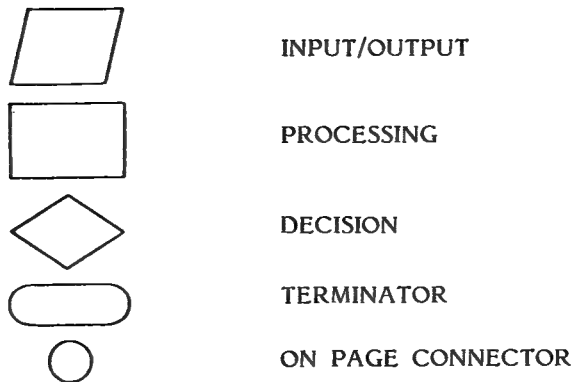
Connect the terminal cable to the appropriate connector on the left edge of the card as described in Chapter 3. Verify that the switches on the terminal are set for full-duplex operation and no parity. The duplexing mode switch will usually be labelled HALF/FULL or H/F; the parity switch will be labelled EVEN/ODD/NO. If your terminal has a CRT, wait for it to warm up. Instructions for "logging on" to a terminal may also be found in Chapter 3.

#### **6.2 DOUBLE-PRECISION ADDITION**

Since the eight bits of the accumulator can represent positive values only in the range 0-255 (00-FF Hex), 255 is the largest sum that can be obtained by simply loading one 8-bit number into the accumulator and adding another. But by utilizing the Carry Flag, which is set to "1" whenever the result of an addition exceeds 255, multiple-byte numbers may be added and the results stored in memory. A 16-bit sum can represent values greater than 65,000 (up to FFFF Hex). Adding 16-bit rather than 8-bit numbers is called "double-precision" addition, using 24-bit numbers yields triple precision, etc.

##### **6.2.1 Defining Program Flow**

Flowcharting is an orderly way of representing a procedure. Much easier to follow than a list of instructions, a flowchart facilitates debugging and also serves as a handy reference when using a program written weeks or months earlier. Some common flowcharting symbols are shown in Figure 6-1. below.



**Figure 6-1. COMMON FLOWCHARTING SYMBOLS**

The object of our program is to add two 16-bit numbers, each stored in two bytes of RAM, and obtain a 16-bit result. The sequence of operations the processor must perform is shown in the flowchart in Figure 6-2.

To accomplish double-precision addition, first clear the Decimal Mode and the Carry Flags. (The addition is in binary, so the system must not be expecting decimal numbers. The Carry Flag is used in the program and must start at zero.) Load the low byte of the first 16-bit number into the accumulator and add the low order byte of the second number using an Add With Carry (ADC) command. The contents of the accumulator are the low order byte of the result. The Carry Flag is set if the low-byte sum was greater than FF (Hex).

You now store the accumulator contents in memory, load the high order byte of the first number into the accumulator, and add the high order byte of the second number. The ADC command automatically adds the carry bit if it is set. After the second addition, the contents of the accumulator are the high order byte of the result. The example below shows the addition of 384 and 128.

```
0000 0001 1000 0000    384 (0180 Hex)
0000 0000 1000 0000    128 (0080 Hex)
```

Add low order bytes: (clear carry)

```
      1000 0000
      1000 0000
  Carry = 1  0000 0000
```

Add high order bytes: (carry = 1)

```
      0000 0001
      0000 0000
      1 CARRY
  Carry = 0  0000 0010
```

Result = 0000 0010 0000 0000 = 512 (0200 Hex)

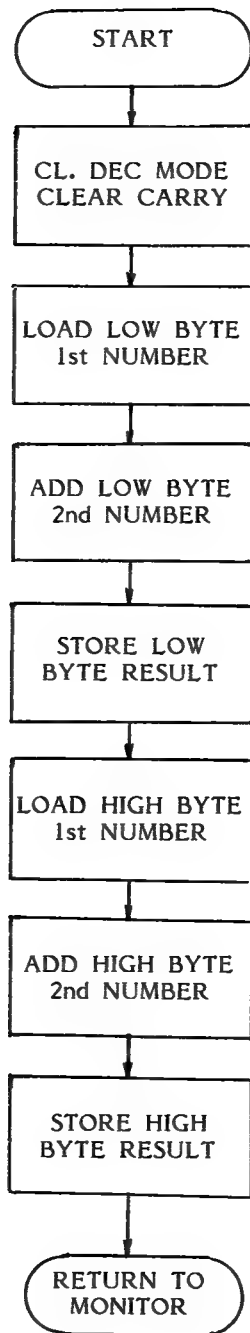


Figure 6-2. DOUBLE-PRECISION ADDITION FLOWCHART

### 6.2.2 Coding and "Hand Assembly"

Once you have flowcharted a program, you may "code" it onto a form like the one shown in Figure 6-3. SY6502 Microprocessor Assembly Language is described in Sections 4.3.3 and 4.3.4. Additional information is available in the Synertek "Programming Manual" for the 6500 family. Figure 6-4 shows the coding for our example.

The first step involves finding the SY6502 commands that correspond to the operations specified in the flowchart. A summary of the commands and their mnemonic codes is given in Table 4-7. Arbitrary labels were assigned to represent the addresses of the monitor, the two addends and the sum and entered in the operand field. As written, the assembly language program does not specify where in memory the program and data will be stored.

To store and execute the program, you must "assemble" it by translating the mnemonics into hexadecimal command codes and assign the program to a set of addresses in user RAM. Performing this procedure with pencil and paper, rather than with a special assembler program, is "hand assembly".

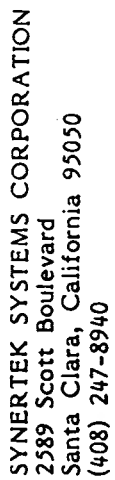
The SUPERMON monitor begins at Hex location 8000, and the addends and the sum have been arbitrarily assigned to locations 0301 through 0306. You should note that the high and low order bytes of a 16-bit number need not be stored in contiguous locations, although they are in this example.

The program will be stored beginning in location 0200, another arbitrary choice. Data and programs may be stored anywhere in user RAM. Columns B1, B2, and B3 represent the three possible bytes in any 6502 instruction. B1 always contains the Hexadecimal operation code. B2 and B3 represent the operand(s). Looking at the coding form, you can see that the CLD and CLC instructions each occupy one byte and that the LDA instruction occupies three bytes. On your instruction set summary card, you'll see that the LDA mnemonic represents several different operation codes depending on the addressing mode chosen. AD indicates absolute addressing and specifies a three-byte command. When all the operation codes and operands have been translated into pairs of Hex digits, the program is ready to be entered into memory and executed.

### 6.2.3 Entering and Executing the Program

The procedure for entering the double precision addition program is shown below.

<u>YOU KEY IN</u>	<u>DISPLAY SHOWS</u>	<u>EXPLANATION</u>
(RST)		
(CR)	SY1.0..	
(MEM) 200 (CR)	0200.**.	Enter memory display and modify mode
D8	0201.**.	Store D8 in location 0200, advance to next location
18	0202.**.	Store 18 in location 0201, advance to next location
AD	0203.**.	.
02	0204.**.	.
03	0205.**.	.
6D	0206.**.	.
	.	
	.	
	.	
80	0217.**.	
(CR)	217.**..	Exit memory display and modify mode



PROGRAM \_\_\_\_\_

PROGRAMMER

DATE \_\_\_\_\_

[illegible]

**Figure 6-3. SAMPLE CODING FORM**



SYNERTEK SYSTEMS CORPORATION  
2589 Scott Boulevard  
Santa Clara, California 95050  
(408) 247-8940

PROGRAM \_\_\_\_\_

PROGRAMMER \_\_\_\_\_

DATE \_\_\_\_\_

Page \_\_\_\_\_ Of \_\_\_\_\_

DUAL-PRECISION ADD ROUTINE

ADDR	INSTRUCTIONS			LABEL	NMEMONIC	OPERAND	COMMENTS
	B1	B2	B3				
200	DB				CLD		CLEAR DECIMAL MODE FLAG (MODE = 0)
201	1B				CLC		CLEAR CARRY FLAG (CARRY=0)
202	AD	02	03		LDA	L1	LOAD LOW ORDER BYTE, FIRST NUMBER
205	6D	04	03		ADC	L2	ADD WITH CARRY, LOW ORDER BYTE, SECOND NUMBER
208	8D	06	03		STA	L3	STORE LOW ORDER BYTE, RESULT
20B	AD	01	03		LDA	H1	LOAD HIGH ORDER BYTE, FIRST NUMBER
20E	6D	03	03		ADC	H2	ADD WITH CARRY HIGH ORDER BYTE, SECOND NUMBER
211	8D	05	03		STA	H3	STORE HIGH ORDER BYTE, RESULT
214	4C	00	80		JMP	START	BRANCH TO MONITOR
301				H1	=	\$ 301	HIGH ORDER BYTE OF FIRST NUMBER
302				L1	=	\$ 302	LOW ORDER BYTE OF FIRST NUMBER
303				H2	=	\$ 303	HIGH ORDER BYTE OF SECOND NUMBER
304				L2	=	\$ 304	LOW ORDER BYTE OF SECOND NUMBER
305				H3	=	\$ 305	HIGH ORDER BYTE OF RESULT
306				L3	=	\$ 306	LOW ORDER BYTE OF RESULT
8000				START	=	\$ 8000	MONITOR



The program is now entered. Examine each location to make sure that all values are correct. Then store the addend values in locations 0301-0304 as shown below. We'll use the numbers that were used in the example in Section 6.2.1, 0180 (Hex) and 0080 (Hex).

<u>YOU KEY IN</u>	<u>DISPLAY SHOWS</u>	<u>EXPLANATION</u>
(MEM) 301 (CR)	0301.**.	
01	0302.**.	Enter high order byte, first addend
80	0303.**.	Enter low order byte, first addend
00	0304.**.	Enter high order byte, second addend
80	0305.**.	Enter low order byte, second addend
(CR)	305.**.	

To execute the program, enter the command shown below.

<u>YOU KEY IN</u>	<u>DISPLAY SHOWS</u>	<u>EXPLANATION</u>
(GO) 200 (CR)	g 200.	Execute program starting at location 0200.

Now use MEM to examine locations 0305 and 0306. Verify that they are high and low order bytes of the result, 02 and 00. If you find other data at these locations, you will be pleased to know that the next section of this chapter tells you how to debug the program.

#### **6.2.4 Debugging Methods**

The first step in debugging is to make sure that the program and data have been entered correctly. Use the MEM command to examine the program starting address, and use the right-pointing arrow key to advance one location at a time and verify that the contents of each are correct. If you have a terminal, you can generate a listing by entering an SP command without turning on the tape punch or by using the VER command. Also examine the locations that contain the initial data.

If the program and data are correct, but the program still does not execute properly, you may want to use the VIM-1 DEBUG function. If DEBUG is ON when the execute (GO) command is entered, the program will execute the first instruction, then return control to the monitor. The address on the display will be the address of the first byte of the next instruction. If you again press GO to execute (do not specify an address this time), the computer will execute the next instruction, then halt as before. The program may be executed one step at a time in this manner.

After certain instructions, you will want to examine the contents of memory locations or registers. Use the MEM or REG commands, then resume operation by entering another GO command.

To examine the Carry Flag after the low order addition, for example, use the REG command as shown below.

<u>YOU KEY IN</u>	<u>DISPLAY SHOWS</u>	<u>EXPLANATION</u>
(ON)	unimportant	Turn DEBUG function ON
(GO) 200 (CR)	0201.2 .	Execute D8 instruction
(GO) (CR)	0202.2 .	Execute 18 instruction
(GO) (CR)	0205.2 .	Execute AD instruction
(GO) (CR)	0208.2 .	Execute 6D instruction, low order add with carry
(REG) (CR)	P 0208.	Program Counter
	r1 Fd.	Stack pointer
	r2 63.	Status register
(CR)	2 63.	End register examination
(GO) (CR)	020B.2 .	Execute 8D instruction
	:	
	:	

The Carry Flag is the lowest (rightmost) bit of the Status Register. To determine whether the flag was set, convert the Hex digits 63 to binary. The result of this conversion is 0110 0011, and since the low bit is "1", this confirms that the sum of the two low order bytes was greater than 255 (FF Hex).

You may turn the DEBUG switch OFF after any instruction. When you next press GO, the program will finish executing.

Since reading from or writing to any I/O port is the same as reading from or writing to a memory location, the DEBUG feature may also be used to debug I/O operations. When the port address is examined with a MEM command, the two Hex digits that represent data indicate the status of each pin in the port. For example, if C2 is displayed, pin status is as follows:

```

      PIN   7   6   5   4   3   2   1   0
STATUS  1   1   0   0   0   0   1   0
0 = open
1 = closed

```

For more advanced debugging techniques, including how to write and use your own trace routines, see Sections 9.5 and 9.6.

You now know how to code, enter, and debug programs on the VIM-1. Let's go look at two more examples that illustrate useful programming concepts.

### 6.3 CONDITIONAL TESTING

Most useful computer programs don't go in straight lines -- they don't simply execute a series of instructions in consecutive memory locations. They do perform different operations for different data by testing data words and jumping to different locations depending on the results of the test. Typical tests answer the following kinds of questions:

1. Is a selected bit of a specified data word a 1 or a 0?
2. Is a specified data word set to a selected ASCII character or numeric value?

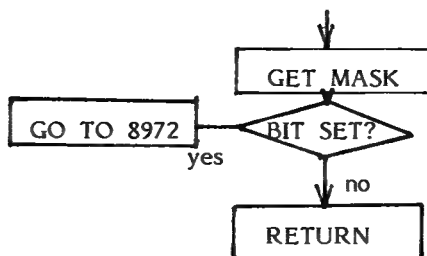
The sample program discussed below will answer question "1". It can be patched easily to answer question "2". You can use the principles you learn in the first two examples to make many more complicated tests.

### Bit Testing

This sample program looks at the word in Hex location 31 and tests bit 3. If bit 3 is set to one, it jumps to location 8972; if bit 3 is zero, it returns to the executive. Location 8972 is a monitor subroutine that makes the VIM-1 go "beep".

The only problem involved is in isolating bit 3. The simplest way is to use a mask -- a word in memory with bit 3 set and none other. If we logically AND the mask with the sample word, the resultant value will be zero if bit 3 was zero and non-zero otherwise. The BIT test performs the AND and tests the value without altering the state of the accumulator.

Here is the flow chart. The code is in Figure 6-5. The mask (F7 Hex) is in location 30, the test value in location 31.



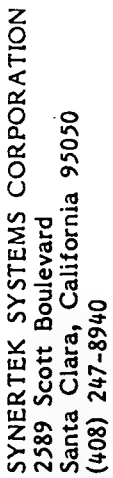
### Hint

If you wish to test bit 0 or bit 7 of a byte, you need not use a mask. Simply use a shift operation to place the selected bit in the CARRY status bit and use a BCC or BCS to test CARRY. This saves one or more program locations. Note that it alters the accumulator - you may have to shift it back for later processing.

### Character, Value, or Magnitude Testing

To test whether a byte is exactly equal to an ASCII character or a value, use the Compare command or first set a mask location exactly equal to the character or value. Then use the EOR command to find the exclusive OR of the two values and test the result for zero. It will be zero if and only if the values were identical. Note that this destroys the test value -- keep another copy of it if you must use it again.

To test whether a byte is greater, equal to, or less than a given value, use the Compare command or set a mask to the test values and subtract it from the test value. The test value will be destroyed. Test the result to see whether it is positive, negative, or zero (this takes two sequential tests) and skip accordingly. Try writing a program that makes a series of magnitude tests to determine whether a given byte is an ASCII control character (0-1F Hex), punctuation mark, number, or letter. The values of the ASCII character set are listed on the summary instruction card.



### BIT 3 TEST ROUTINE

[illegible]

**Figure 6-5. BIT 3 TEST ROUTINE**

## 6.4 MULTIPLICATION

The sample program described here multiplies two one-byte unsigned integers and stores the results in two bytes. Note that in any base of two or more, the product of two numbers may be as long as the sum of the lengths of the numbers. In decimal,  $99 \times 99 = 9801$ ; in Hex  $FF \times FF = FE01$ .

Since many programs will involve multiplication, it is not good practice to write a multiplication routine every time the need comes up. The sample is set up as a subroutine to allow it to be used by many programs. Serious programmers will usually wind up with libraries of subroutines specialized for their applications.

### How to Multiply

Multiplication is normally introduced to students as a form of sequential addition. Humans can in fact multiply 22 (decimal) by 13 by performing an addition:

$$22 + 22 + 22 \dots 22 = 286$$

This technique is of course foolish -- it involves a lot of work and a high probability of error. It would be easy to write a program that would multiply this way (try it) but it would be a terrible waste of time.

How then to multiply? We could use a table. Humans use memorized tables that work up to about  $10 \times 10$ :

$$7 \times 8 = 56$$

Humans cannot, however, remember well enough to know that:

$$22 \times 13 = 286$$

Computers, of course, can "remember" an arbitrarily large table. But the table for the problem at hand would have  $FFFF$  entries, which is far too many for practicality.

Humans solve the problem by breaking the multiplication down into smaller steps. We multiply one factor, one digit at a time, by each digit of the other factor in turn. Then we shift some of the partial products to the left and add:

$$\begin{array}{r} 22 \\ \times 13 \\ \hline 66 \\ 22 \phantom{0} \\ \hline 286 \end{array}$$

We would multiply the binary equivalents of the numbers the same way:

$$\begin{array}{r} 10110 \\ \phantom{00}1101 \\ \hline 10110 \\ \phantom{0000}0 \\ \phantom{000}10110 \\ \phantom{0000}10110 \\ \hline 100011110 \end{array}$$

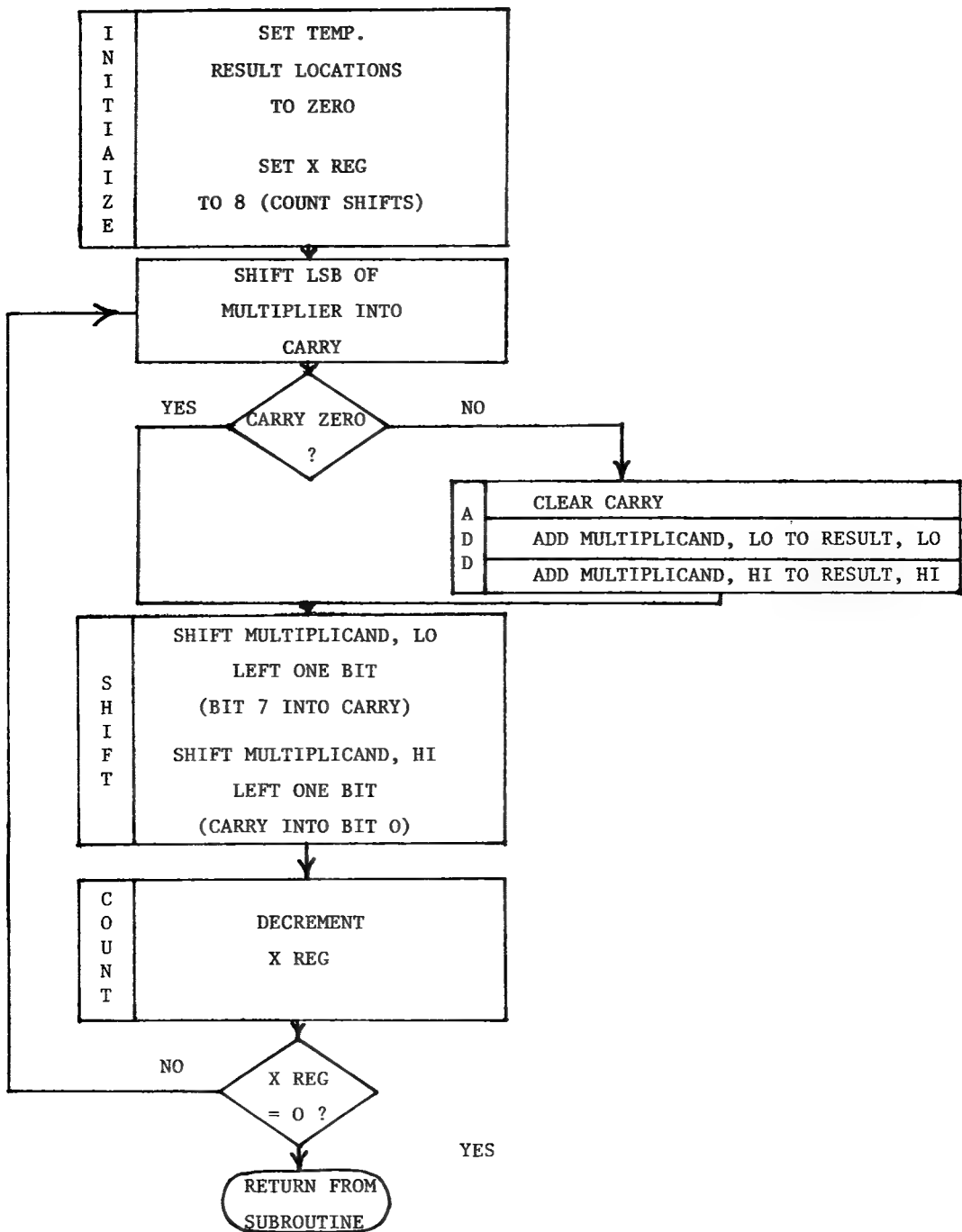


Figure 6-6. GENERAL MULTIPLICATION FLOWCHART

A little figuring will verify that the result is correct. Note that the "tables" for multiplying binary numbers by a single digit are very simple — a number times one is itself; a number times zero is zero. We can multiply, then, by using a series of additions and shifts, as shown in the flow chart below. The first factor is eight bits long; the second is extended to two bytes (the high-order byte is zero), and the result goes into two bytes set initially to zero. The flowchart in Figure 6-6 is general and not suitable for direct coding.

This procedure could be coded quite easily. Each bit test on the first factor could be made with a different mask as shown in the previous example. Note, however, that the same basic set of instructions is repeated eight times, wasting memory space. A more efficient routine would loop over the same code eight times.

The more efficient routine could also use eight masks, but there's a simpler way. Simply shift the factor to the right once per addition. The bit to be tested will wind up in the CARRY indicator, and we can simply test that. Figure 6-7 is a more formal flowchart of the multiply routine as it is coded that it includes the coding details. The coding chart is shown in Figure 6-8.

### Testing

The listing below shows one way to key in the program. The code occupies the RAM space from 200 to 222 Hex. The factor come from locations 21 and 22; the product goes to locations 23 and 24.

Note that the original factors are destroyed by the routine. If it is necessary to preserve them for other subroutines, simply code them into unused memory locations and perform the multiplication on the copies.

### Division

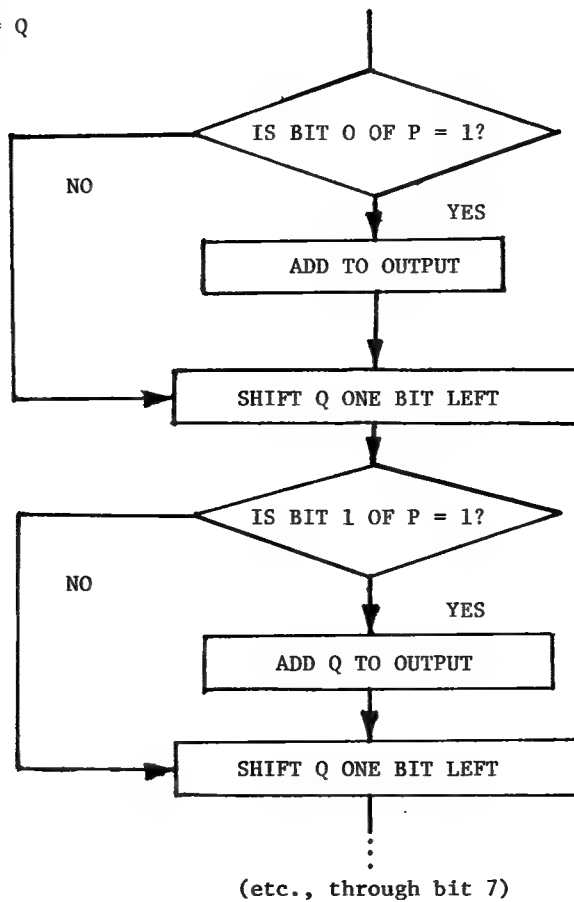
Try to write a parallel routine for performing integer division that divides a two-byte quotient and a two-byte remainder. You may wish to test the remainder and, if its MSB is one, round the result by incrementing the quotient.

### Arithmetic

The examples given so far show some basic integer arithmetic techniques. They may be expanded easily for dual-precision operation. (Multiply two bytes by two bytes for a four-bit product. Use dual-precision addition and fifteen shifts instead of seven.)

MULTIPLIER = P

MULTIPLICAND = Q



**Figure 6-7. DETAILED MULTIPLICATION FLOWCHART**





SYNERTEK SYSTEMS CORPORATION  
2589 Scott Boulevard  
Santa Clara, California 95050  
(408) 247-8940

PROGRAM \_\_\_\_\_

PROGRAMMER \_\_\_\_\_

DATE \_\_\_\_\_

Page \_\_\_\_\_ of \_\_\_\_\_

*SINGLE - PRECISION MULTIPLY ROUTINE*

ADDR	INSTRUCTIONS			LABEL	MNEMONIC	OPERAND	COMMENTS
	B1	B2	B3				
200	A9	00		MULT1	LDA	#0	ZERO ACCUMULATOR
202	B5	20			STA	INH1 (20)	SET TEMPORARY STORAGE LOCATION (20) TO ZERO
204	B5	23			STA	OUTLO (23)	" LOW BYTE RESULT " (23) " "
206	B5	24			STA	OUTH1 (24)	" HIGH " " (24) " "
208	A2	08			LDX	#8	SET X TO 8 TO COUNT SHIFTS
20A	46	22		MORE	LSR	IN2 (22)	SHIFT FACTOR RIGHT
20C	90	0D			BCC	ZERBIT (1D)	IF CARRY = 0 SKIP ADDITION, GO TO ZERBIT
20E	18				CLC		CLEAR CARRY
20F	A5	23			LDA	OUTLO	GET LOW BYTE ASSEMBLED SO FAR
211	65	21			ADC	INI	ADD CURRENT TERM
213	B5	23			STA	OUTLO	SAVE UPDATED LOW BYTE
215	A5	24			LDA	OUTH1	GET HIGH BYTE ASSEMBLED SO FAR
217	65	20			ADC	TEMPHI	ADD CURRENT TERM
219	B5	24			STA	OUTH1	SAVE UPDATED HI BYTE
21B	06	21		ZERBIT	ASL	INI	SHIFT LEFT FOR NEXT ADDITION
21D	26	20			ROL	INH1	SHIFT HIGH BYTE LEFT (ENTER CARRY)
21F	CA				DEX		DECREMENT INDEX REGISTER (COUNT ADDS)
220	DO	E8			BNE	MORE	IF X > 0, GO BACK AND DO NEXT ADD
222	60				RTS		DONE; GO BACK TO CALLING ROUTINE

Figure 6-8. SINGLE-PRECISION MULTIPLY ROUTINE



## CHAPTER 7

### OSCILLOSCOPE OUTPUT FEATURE

#### 7.1 INTRODUCTION

Your VIM-1 module is hardware-equipped to allow you to use an ordinary oscilloscope as a display device. In this section, we will describe the hardware and connections between the system and the oscilloscope and also provide a listing of a software driver for this output. This listing is just one way of handling the oscilloscope output; you may wish to modify it or develop your own.

#### 7.2 OPERATION OF OSCILLOSCOPE OUTPUT

The circuitry shown in the detail on the schematic (Figure 4-9) enables the VIM to output alphanumeric characters to an oscilloscope. The circuitry is adapted from a published schematic and was included on the VIM to help relieve the bottleneck found on most single-board computers, i.e., the 7 segment displays. Many things can be done with the scope-out circuit, like displaying alphanumeric characters, bar graphs, and game displays. The alphanumeric output is usually organized as 16 or 32 characters, each character being a 5-by-7 dot matrix. The characters could be English, Greek or Cuneiform, or could even be stick-men, cars, dog houses, or laser guns.

The "video" signal from the collector of Q10, is 3V peak-to-peak with a cycle time of about 50 ms (using the suggested software driver included in section 7.3). The sync pulse which begins the line should synchronize all triggered sweep scopes and most recurrent sweep scopes. In the driver which follows, sync could be brought out on a separate pin by replacing the code from SYNC to CHAR with a routine that would output a pulse on PB4 or some other output line.

##### 7.2.1 Connection Procedures

Connect the oscilloscope vertical input to pin R on connector AA ("scope out") and connect scope ground to pin 1 of connector AA (VIM ground). Start the software and adjust the scope for the stable 16-character display. If the sync pulse was output on PB4, connect the scope's trigger to pin 4 of connector AA.

##### 7.2.2 Circuit Operation

The operation of the circuit is simple. Basically, the circuit is a sawtooth waveform generator whose output is sometimes the sawtooth and sometimes ground. The sawtooth is generated by the current source, Q9-Q17-R42-R43, charging C9. When C9 gets up to about 3V the discharge path, Q19-Q18-R41-R44, shorts it back to ground due to a pulse sent out by CA-2. The sawtooth waveform is shown below and forms the columns of the display.



By pulling the sawtooth to ground with Q10 any columns or portions thereof can be "removed" from the display. The result of this can be seen below:



The sawtooth is pulled to ground by bringing CB-2 high.

Because Q10 in the "ON" state will cause loading of C9 (thru R45) and C9 will charge a little more slowly, the time for a "dark" column should be slightly longer than for a "light" column.

If more than 8 vertical dots are desired, the charging rate of C9 must be slowed by lowering the charging current. R42 controls the charging current and can be increased up to about 10K before the loading effects of R45 get completely out of hand.

### 7.3 USING OUR SOFTWARE

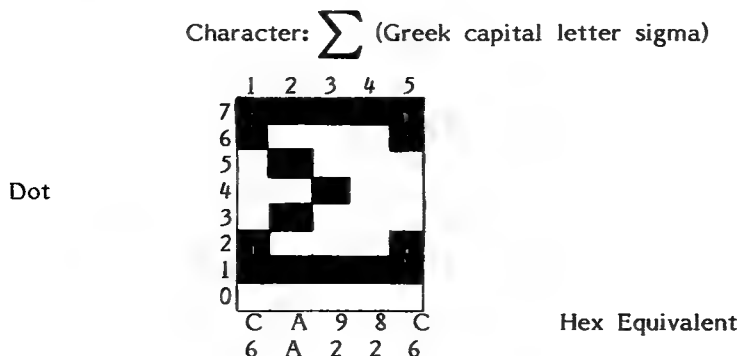
The program listing in Table 7-1 is one way of handling oscilloscope output. After entering the program and character table and attaching an oscilloscope to the scope output, enter the following commands:

	Comments
<u>.SD 500, A670(CR)</u>	Change SCANVEC.
<u>.SD 58C, A664(CR)</u>	Change OUTVEC.
<u>.SD 560, A661(CR)</u>	Change INVEC.

Now enter any stream of characters from the HKB to fill SCPBUF.

Put the scope input on AC couple and the trigger on DC couple. Adjust the time base, attenuation, and trigger until the display becomes readable. If your screen is very small, you may wish to change the number of characters per line by adjusting the value at location \$0506.

Example: Creating translation table for scope driver.



Each byte corresponds to a single column, with each bit corresponding to a single dot.

sigma = \$C6, \$AA, \$92, \$82, \$C6

Bit 0 is always 0 to raise the character off of the Ground line.

**Table 7-1. OSCILLOSCOPE OUTPUT DRIVER SOFTWARE LISTING**

LINE #	LOC	CODE	LINE
0002	0000		; SCOPE LINE DRIVER 05/01/78
0003	0000		; USES CHARACTER SET IN TABLE SYMBLS
0004	0000		; 5 BYTES PER CHAR
0005	0000		; ENTRY 'LINE' IS ANALOGOUS TO 'SCAND'
0006	0000		; BELOW ROUTINES HKEY AND HDOUT INTERFACE TO HEX KB
0007	0000		; CHAR SET PROVIDED IS FOR HEX KB
0008	0000		; AND RELATED TO ASCII TABLE IN MONITOR ROM
0009	0000		; THIS DRIVER CAN ACCESS A MAX OF 51 CHARS
0010	0000		TXTSHV = \$8A06
0011	0000		SCNVEC = \$A66F
0012	0000		GETKEY = \$88AF
0013	0000		KEYQ = \$8923
0014	0000		SAVER = \$8188
0015	0000		BEEPP3 = \$8975
0016	0000		ASCIM1 = \$8BEE
0017	0000		RESALL = \$81C4
0018	0000		PCR3 = \$AC0C ;CA2,CB2 = SCOPE
0019	0000		TXTCR = \$03FE
0020	0000		COLCTR = \$03FF
0021	0000		TEXT = \$A600 ;SCOPE BUFFER IN SYS RAM
0022	0000		SYMBLS = \$0400 ;CHARACTER TABLE
0023	0000		* = \$500
0024	0500	A9 EE	LINE LDA #\$EE ;DISCHARGE CAP
0025	0502	8D 0C AC	STA PCR3
0026	0505	A9 21	LDA #32+1 ;# CHARS PER LINE
0027	0507	8D FE 03	STA TXTCR
0028	050A	A9 CC	SYNC LDA #CC ;CHARGE CAP FOR SYNC
0029	050C	8D 0C AC	STA PCR3
0030	050F	A2 EA	LDLY LDX #EA ;LONG DELAY !
0031	0511	CA	DEX
0032	0512	D0 FC	BNE LDLY+1
0033	0514	CE FE 03	CHAR DEC TXTCR ;LOOP HERE FOR CHAR
0034	0517	AE FE 03	LDX TXTCR
0035	051A	D0 03	BNE POIMFG
0036	051C	4C 23 89	EXIT JMP KEYQ ;SCAN KB AND RETURN
0037	051F		;
0038	051F	8D FF A5	POIMFG LDA TEXT-1,X ;POINTER MANUFACTURER
0039	0522	0A	ASL A ;PTR X 4 + PTR
0040	0523	0A	ASL A
0041	0524	18	CLC
0042	0525	7D FF A5	ADC TEXT-1,X ;MULTIPLY BY 5
0043	0528	AA	TAX
0044	0529	A9 06	LDA #6
0045	052B	8D FF 03	STA COLCTR
0046	052E	A9 EE	COLUMN LDA #\$EE ;LOOP HERE FOR COL'S
0047	0530	8D 0C AC	STA PCR3 ;DISCHARGE CAP
0048	0533	CE FF 03	DEC COLCTR
0049	0536	30 DC	BMI CHAR ;BRANCH IF DONE W/6 COL'S
0050	0538	D0 02	BNE COLUP
0051	053A	A2 00	LDX #0 ;INTER CHAR SPACE
0052	053C	A9 EC	COLUP LDA #EC ;START RAMP UP ...
0053	053E	8D 0C AC	STA PCR3 ;... BUT HOLD DOT DOWN
0054	0541	E8	INX ;NEXT COL
0055	0542	8A	TXA ;SAVE X
0056	0543	48	PHA

Table 7-1. OSCILLOSCOPE OUTPUT DRIVER SOFTWARE LISTING (Continued)

LINE #	LOC	CODE	LINE
0057	0544	BD FF 03	LDA SYMBLS-1,X ;GET COL
0058	0547	A0 08	LDY #8 ;COUNT DOTS
0059	0549	88	DEY
0060	054A	30 0F	BMI CLEAN
0061	054C	4A	LSR A ;NEXT DOT IN CARRY
0062	054D	B0 04	BCS LIGHT ;C SET = LIGHT, C CLEAR = DARK
0063	054F	A2 EC	LDX #\$EC ;PULL OUTPUT LOW
0064	0551	D0 02	BNE *+4
0065	0553	A2 CC	LDX #\$CC ;OUTPUT FOLLOWS RAMP UP
0066	0555	8E 0C AC	STX PCR3
0067	0558	4C 49 05	JMP DOT
0068	055B	68	PLA ;RESTORE X
0069	055C	AA	TAX
0070	055D	4C 2E 05	JMP COLUMN
0071	0560		;
0072	0560		;
0073	0560	20 AF 88	HKEY JSR GETKEY ;GET KEY + ECHO TO SCOPE
0074	0563	20 88 81	SCPDISP JSR SAVER ;FILL SCPBUF FROM ASCII IN A
0075	0566	29 7F	AND #\$7F
0076	0568	C9 07	CMP #\$07 ;BELL?
0077	056A	D0 03	BNE NBELL
0078	056C	4C 75 89	JMP BEEPP3
0079	056F		; SEARCH ASCII TABLE IN MONITOR ROM
0080	056F	A2 36	NBELL LDX #\$36
0081	0571	D0 EE 8B	OUT2 CMP ASCIM1,X
0082	0574	F0 06	BEQ GOTX
0083	0576	CA	DEX
0084	0577	D0 F8	BNE OUT2
0085	0579	4C C4 81	JMP RESALL ;NOT IN TABLE
0086	057C	CA	GOTX DEX
0087	057D	8A	TXA
0088	057E	C9 0B	CMP #\$0B ;TABLE NOT CONTINUOUS
0089	0580	90 03	BCC GOOD
0090	0582	38	SEC
0091	0583	E9 05	SBC #5 ;ADJUST DISCONTINUITY
0092	0585	CA	GOOD DEX
0093	0586	20 06 8A	JSR TXTSHV ;SHOVE SCPBUF DOWN
0094	0589	4C C4 81	JMP RESALL
0095	058C	20 63 05	HDOUT JSR SCPDISP ;CHAR TO SCPBUF AND SINGLE SC
0096	058F	4C 6F A6	JMP SCNVEC
0097	0592		.END

**Table 7-1. OSCILLOSCOPE OUTPUT DRIVER SOFTWARE LISTING (Continued)**

```

;
; 8X5 MATRIX CHAR SET FOR SCOPE LINE DRIVER
; CONTAINS ALL HEX KB CHARS
; FIRST BYTE OF TABLE MUST BE 00
; EACH CHAR : FIRST BYTE = LEFTMOST COLUMN,
;               MSB = TOP DOT, LSB = 0, BIT 1   BOTTOM DOT
;
*=$400 ;PAGE 4 ALLOCATED TO CHARACTER SET
.BYT $00,$7C,$92,$A2,$7C ;ZERO
.BYT $00,$42,$FE,$02,$00 ;ONE
.BYT $4E,$92,$92,$92,$62 ;TWO
.BYT $44,$82,$92,$92,$6C ;THREE
.BYT $18,$28,$48,$FE,$08 ;FOUR
.BYT $E4,$A2,$A2,$A2,$9C ;FIVE
.BYT $3C,$52,$92,$92,$0C ;SIX
.BYT $86,$88,$90,$A0,$C0 ;SEVEN
.BYT $6C,$92,$92,$92,$6C ;EIGHT
.BYT $60,$92,$92,$94,$78 ;NINE
.BYT $3E,$50,$90,$50,$3E ;A
.BYT $00,$1E,$86,$4A,$32 ;C/R
.BYT $10,$10,$10,$10,$10 ;DASH
.BYT $82,$44,$28,$10,$00 ;RIGHT ARROW
.BYT $FE,$FE,$FE,$FE,$FE ;SH
.BYT $7C,$82,$82,$8A,$4E ;G
.BYT $FE,$90,$98,$94,$62 ;R
.BYT $FE,$40,$30,$40,$FE ;H
.BYT $FE,$02,$02,$02,$02 ;L2
.BYT $44,$A2,$92,$8A,$44 ;S2
.BYT $80,$80,$80,$80,$80 ;U0
.BYT $02,$02,$02,$02,$02 ;U1
.BYT $82,$82,$82,$82,$82 ;U2
.BYT $FE,$00,$00,$00,$00 ;U3
.BYT $FE,$00,$00,$00,$FE ;U4
.BYT $1E,$12,$12,$12,$1E ;U5
.BYT $F0,$90,$90,$90,$F0 ;U6
.BYT $80,$80,$80,$80,$F0 ;U7
.BYT $04,$02,$02,$02,$FC ;J
.BYT $E0,$18,$06,$18,$E0 ;V
.BYT $FF,$FF,$FF,$FF,$FF ;ASCII
.BYT $FE,$92,$92,$92,$6C ;B
.BYT $7C,$82,$82,$82,$44 ;C
.BYT $FE,$82,$82,$82,$7C ;D
.BYT $FE,$92,$92,$82,$82 ;E
.BYT $FE,$90,$90,$80,$80 ;F
.BYT $44,$A2,$92,$8A,$44 ;SD
.BYT $10,$10,$7C,$10,$10 ;+
.BYT $00,$10,$28,$44,$82 ;<
.BYT $00,$00,$00,$00,$00 ;SH
.BYT $FE,$02,$02,$02,$02 ;LP
.BYT $44,$A2,$92,$8A,$44 ;SP
.BYT $FE,$04,$08,$04,$FE ;W
.BYT $FE,$02,$02,$02,$02 ;L1
.BYT $44,$A2,$92,$8A,$44 ;S1
.BYT $00,$06,$06,$00,$00 ;DECIMAL
.BYT $00,$00,$00,$00,$00 ;BLANK
.BYT $40,$80,$8A,$90,$60 ;QUESTION
.BYT $FE,$90,$90,$90,$60 ;P
.END

```





## CHAPTER 8

### SYSTEM EXPANSION

This chapter discusses the means by which you can expand your VIM-1 microcomputer system by adding memory and peripheral devices to its basic configuration. By now, you realize that data access, whether from RAM, PROM or ROM is a function of addressing interface devices (i.e., 6522's and 6532). Hardware has been built into your VIM-1 module to allow large-scale expansion of the system. A thorough understanding of the VIM-1 System Memory Map (Figure 4-10) will aid considerably in understanding how to expand your system.

#### 8.1 MEMORY EXPANSION

Your VIM-1 module comes equipped with 1K of on-board RAM. It also contains all address decoding logic required to support an additional 3K on-board with no changes by you. In other words, to add 3K of on-board RAM, all you need to do is purchase additional SY2114 devices and plug them into the sockets provided on your board. Your PC board is marked for easy identification of 1K memory blocks. RO equals the lower 1K block and R3 equals the upper 1K block. LO means low order data lines (D0-D3) and HI means high order data lines (D4-D7).

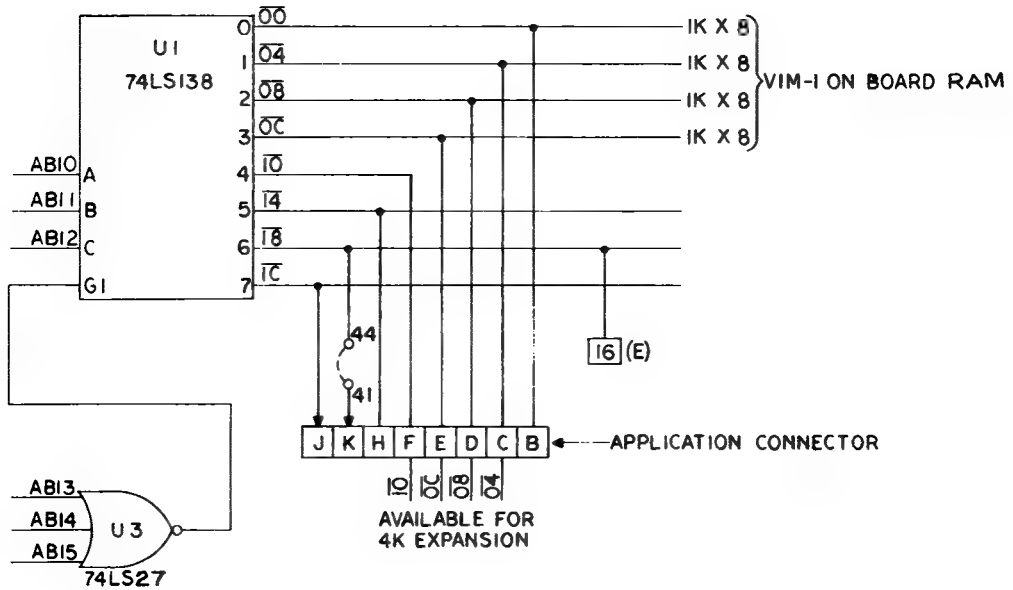
You will recall that the lowest 8K memory locations are defined by an address decoder included on your VIM-1 module (a 74LS138). The eight outputs of this decoder ( $\overline{00}$ - $\overline{1C}$ ) each define a 1K block of addresses in the lowest 8K of the Memory Map. Four of the outputs ( $\overline{00}$ ,  $\overline{04}$ ,  $\overline{08}$ ,  $\overline{1C}$ ) are used to select the on-board static RAM. The remaining four outputs ( $\overline{10}$ ,  $\overline{14}$ ,  $\overline{18}$ ,  $\overline{1C}$ ) are used to interface to the Application Connector (Connector "A"), where you can use them to add another 4K of off-board memory. Again, no external decoding logic is required. By this simple means, you can convert your VIM-1 module into an 8K device quickly. Figure 8-1 shows you how to interface these decode lines at the connector for your VIM-1 system.

To go beyond this 8K size, conceivably up to the maximum 65K addressability limit of the VIM CPU, you could build or buy an additional memory board with on-board decoding logic. In this case, you will use the Expansion Connector (Connector "E") in a manner shown schematically in Figure 8-2. Note that the three high-order address bits (AB13-AB15) not used in the earlier expansion are brought to this connector as shown. These are then used with a decoder to create outputs  $\overline{M0}$  through  $\overline{M7}$ , which in turn are used to select and de-select additional decoders (line receivers). You need add only as many decoders (one for each 8K block of memory) as you need for the expansion you require.

Incidentally, the line receivers shown in Figure 8-2 are provided for electrical reasons. There are loading limitations on the address bus lines of the 6502 CPU, which require the insertion of these receivers. (For your information, each 6502 address line is capable of driving one standard TTL load and 130pf of capacity.)

You should make a careful study of the loading limitations of the required VIM-1 lines before deciding on memory expansion size and devices. It is likely you will want to use additional buffer circuits to attain "cleaner" operation of your expanded memory in conjunction with your VIM-1 system.

## 4K MEMORY EXPANSION



**Figure 8-1. 4K MEMORY EXPANSION**

# MEMORY I/O EXPANSION TO 65K

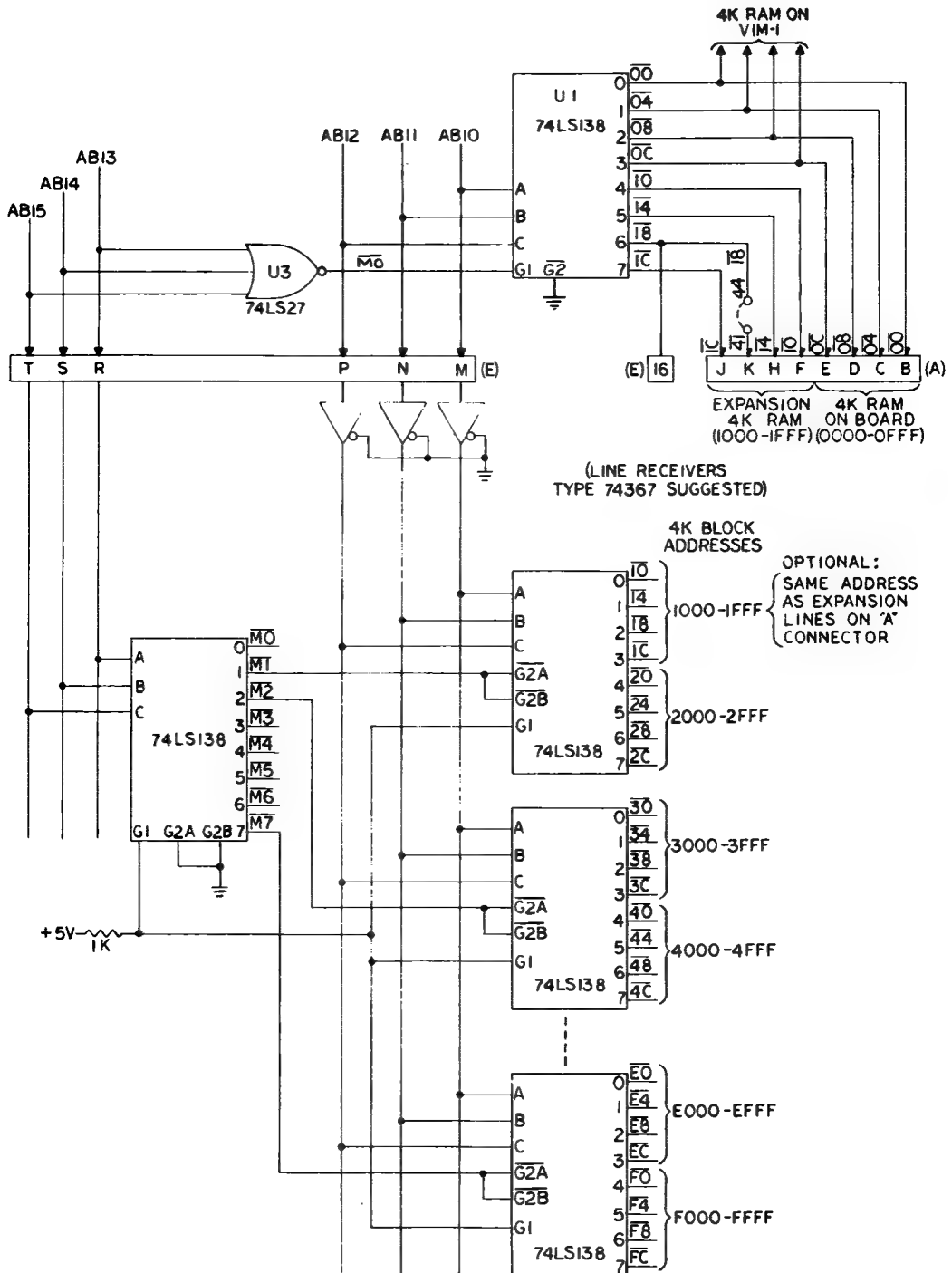


Figure 8-2. MEMORY - I/O EXPANSION TO 65K

## 8.2 PERIPHERAL EXPANSION

As you already know, the VIM-1 microcomputer system includes 51 I/O lines. This means, theoretically, that you could drive as many as 51 peripheral lines (plus 4 control lines) with your VIM-1.

Using either Application Connector ("A" or "AA"), you can add most commercially available printers or other devices requiring parallel interfaces, although you will have to create your own software driver for the printer. Since the provision of that driver is, to some extent, dependent upon the printer you purchase, we do not attempt to discuss the implementation of the software in this manual.

You can expand your VIM-1 system's peripheral I/O capability easily and quickly merely by installing an additional SY6522 in the socket provided for that device. This will give you 16 additional on-board data lines with no requirement for additional work (beyond the software driver) on your part. To go beyond that level, you must use the Expansion Port (Connector "E") described earlier.

Again, we emphasize that the proper understanding and use of the Memory Map in Figure 4-10 will allow you to use your imagination in expanding the I/O capability of your VIM-1 system. Its flexibility is extremely broad and the fact that all I/O and memory are handled as an addressing function allows you expandability to the full capability of the 6502 CPU itself.

## CHAPTER 9

### ADVANCED MONITOR AND PROGRAMMING TECHNIQUES

This chapter contains information which you will find useful as you explore the more sophisticated capabilities of your versatile VIM-1 microcomputer system. As we have pointed out many times, the VIM-1 is the most flexible and expandable monitor of its kind. The SUPERMON monitor uses vectors and other techniques to allow you to modify its operation, and these are provided in detail in this chapter. In addition, the extended use of debug and trace facilities, which are invaluable tools as your programming skill advances, are explained. The use of the Hex keyboard provided on your VIM-1 for configurations using a printer (or other serial device) without a keyboard is also described. And last, an example and discussion of extending SUPERMON's command repertoire.

#### 9.1 MONITOR FLOW

SUPERMON is the 4K byte monitor program supplied with your VIM-1. It resides in locations 8000-8FFF on a single ROM chip. It shares the stack with user programs and uses locations 00F8-00FF in Page Zero. In addition, it uses locations A600-A67F (RAM on the 6532), which are referred to as 'System RAM'. Since these locations are dedicated to monitor functions SUPERMON write protects them before transferring control to user programs.

The flowcharts in Figures 9-1 through 9-5 will demonstrate the major structure of SUPERMON. You will notice that GETCOM (and its entry, PARM), DISPAT, and ERMMSG are subroutines, and therefore available for your programs' use. Note that a JSR to ACCESS to remove write protection from System RAM is necessary before using most monitor routines. Also, notice that the unrecognized command flow (error) is vectored. Thus, you can extend the monitor with your own software.

#### 9.2 MONITOR CALLS

SUPERMON contains many subroutines and entry points which you will want to use in order to save memory and code and avoid duplication of effort. Table 9-1 is a summary of calls and their addresses.

The two calls which you will most commonly use are:

JSR	INCHR	(address 8A1B)
JSR	OUTCHR	(address 8A47)

In performing the input/output, these routines save all registers and use INVEC and OUTVEC, so all you need be concerned with when using them are the ASCII characters passed as arguments in the accumulator.

#### 9.3 MONITOR CALLS, ENTRIES AND TABLES

Table 9-1, which occupies the next several pages of this Chapter, provides you with a comprehensive list of important subroutine symbolic names, addresses, registers and functions of SUPERMON monitor calls, entry points and tables. With this data, you can more easily utilize SUPERMON to perform a wide variety of tasks. All (except those marked with an asterisk) are callable by JSR.

**Table 9-1. MONITOR CALLS, ENTRIES AND TABLES**

<u>NAME</u>	<u>ADDRESS</u>	<u>REGISTERS ALTERED</u>	<u>FUNCTION (S)</u>
*MONITR	8000		Cold entry to monitor. Stack, D flag initialized, System RAM unprotected.
*WARM	8003		Warm entry to monitor
USRENT	8035		User pseudo-interrupt entry - saves all registers when entered with JSR. Displays PC and code 3. Passes control to monitor.
SAVINT	8064	ALL	Saves registers when called after interrupt. Returns by RTS.
DBOFF	80D3	A,F	Simulates depressing debug off key.
DBON	80E4	A,F	Simulates depressing debug on key.
DBNEW	80F6	A,F	Release debug mode to key control.
GETCOM	80FF	A,F	Get command and 0-3 parameters. No error: A=0D (carriage return) Error: A contains erroneous entry.
DISPAT	814A	A,F	Dispatch to execute blocks. Dispatch to URCVEC if error. At return, if error: Carry set, A contains byte in error.
ERMSG	8171	F	If Carry set, print (CR)ER NN, where NN is contents of A.
SAVER	8188	None	Save all registers on stack. At return, stack looks like: <div style="margin-left: 100px;">F A X Y</div> (See paragraph 9.9)
*RESXAF	81B8	restored	Jumped to after SAVER, restore registers from stack <u>except</u> A,F unchanged, perform RTS.
*RESXF	81BE	restored	Jumped to after SAVER, restore registers from stack <u>except</u> F unchanged, perform RTS.
*RESALL	81C4	restored	Jumped to after SAVER, restore <u>all</u> registers from stack, perform RTS.
INBYTE	81D9	A,F	Get 2 ASCII Hex digits from INCHR and pack to byte in A. If Carry set, V clear, first digit non-Hex. If Carry set, V set, second digit nonHex. N and Z reflect compare with carriage return if Carry set.

**Table 9-1. MONITOR CALLS, ENTRIES AND TABLES (Continued)**

<u>NAME</u>	<u>ADDRESS</u>	<u>REGISTERS ALTERED</u>	<u>FUNCTION (S)</u>
PSHOVE	8208	X,F	Shove Params down 16 bits; Move: P2 to P1 P3 to P2 zeros to P3
PARM	8220	A,F	Get 0 to 3 parameters. Return on (CR) or error. A contains last character entered. Flags reflect compare with (CR).
ASCNIB	8275	A,F	Convert ASCII character in A to 4 bits in LO nibble of A. Carry set if non-Hex.
OUTPC	82EE	A,X,F	Print user PC. At return, A=PCL, X=PCH.
OUTXAH	82F4	F	Print X,A (4 Hex digits)
OUTBYT	82FA	A,F	Print A (2 Hex digits)
NIBASC	8309	A,F	Convert LO nibble of A to ASCII Hex in A.
COMMA	833A	F	Print comma.
CRLF	834D	F	Print <b>(CR) (LF)</b> .
DELAY	835A	F	Delay according to TV. (Relation is approximately logarithmic, base=2). Result of INSTAT returned in Carry.
INSTAT	8386	F	If key down, wait for release. Carry set if key down. (Vectored thru INSVEC)
GETKEY	88AF	A,F	Get key from Hex keyboard (more than one if SHIFT or ASCII key used) return with ASCII or HASH code in A. Scans display while waiting (vectored through SCNVEC).
HDOUT	8900	A,X,Y,F	ASCII character from A to Hex display, scan display once, return with Z=0 if key down.
KEYQ	8923	A,F	Determine if key down on Hex keyboard. If down, then Z=0.
KYSTAT	896A	A,F	Determine if key down. If down, then Carry set.
BEEP	8972	None	BEEP on-board beeper.
HKEY	89BE	A,F	Get key from Hex keyboard and echo in DISBUF. ASCII returned in A. Scans display while waiting (vectored thru SCNVEC)

**Table 9-1. MONITOR CALLS, ENTRIES AND TABLES (Continued)**

<b><u>NAME</u></b>	<b><u>ADDRESS</u></b>	<b><u>REGISTERS ALTERED</u></b>	<b><u>FUNCTION (S)</u></b>
OUTDSP	89C1	None	Convert ASCII in A to segment code, put in DISBUF.
TEXT	8A06	F	Shove scope buffer down, push A onto SCPBUF.
INCHR	8A1B	A,F	Get character (vectored thru INVEC). Drop parity, convert to upper case. If character CTL O (0F), toggle Bit 6 of TECHO and get another.
NBASOC	8A44	A,F	Convert low nibble of A to ASCII, output (vectored thru OUTVEC).
OUTCHR	8A47	None	Output ASCII from A (vectored thru OUTVEC). Output inhibited by Bit 6 of TECHO.
INTCHR	8A58	A,F	Get character from serial ports. Echo inhibited by Bit 7 of TECHO. Baud rate determined by SBBTY. Input, echo masked with TOUTFL.
TSTAT	8B3C	A,F	See if break key down on terminal. If down, then Carry set.
*RESET	8B4A	All	Initialize all registers, disable POR, stop tape, initialize system RAM to default values, determine input on keyboard or terminal, determine baud rate, cold monitor entry.
*NEWDEV	8B64		Determine baud rate, cold monitor entry.
ACCESS	8B86	None	Un-write protect System RAM.
NACCESS	8B9C	None	Write protect System RAM.
*TTY	8BA7	A,X,F	Set vectors, TOUTFL, and SDBTY for TTY.
*DFTBLK	8FA0	Table	Default block - entirely copied into System RAM (A620 - A67F) at reset.
*ASCII	8BEF	Table	Table of ASCII codes and HASH codes.
*SEGS	8C29	Table	Table of segment codes corresponding to ASCII codes (above).



## MAIN MONITOR FLOW

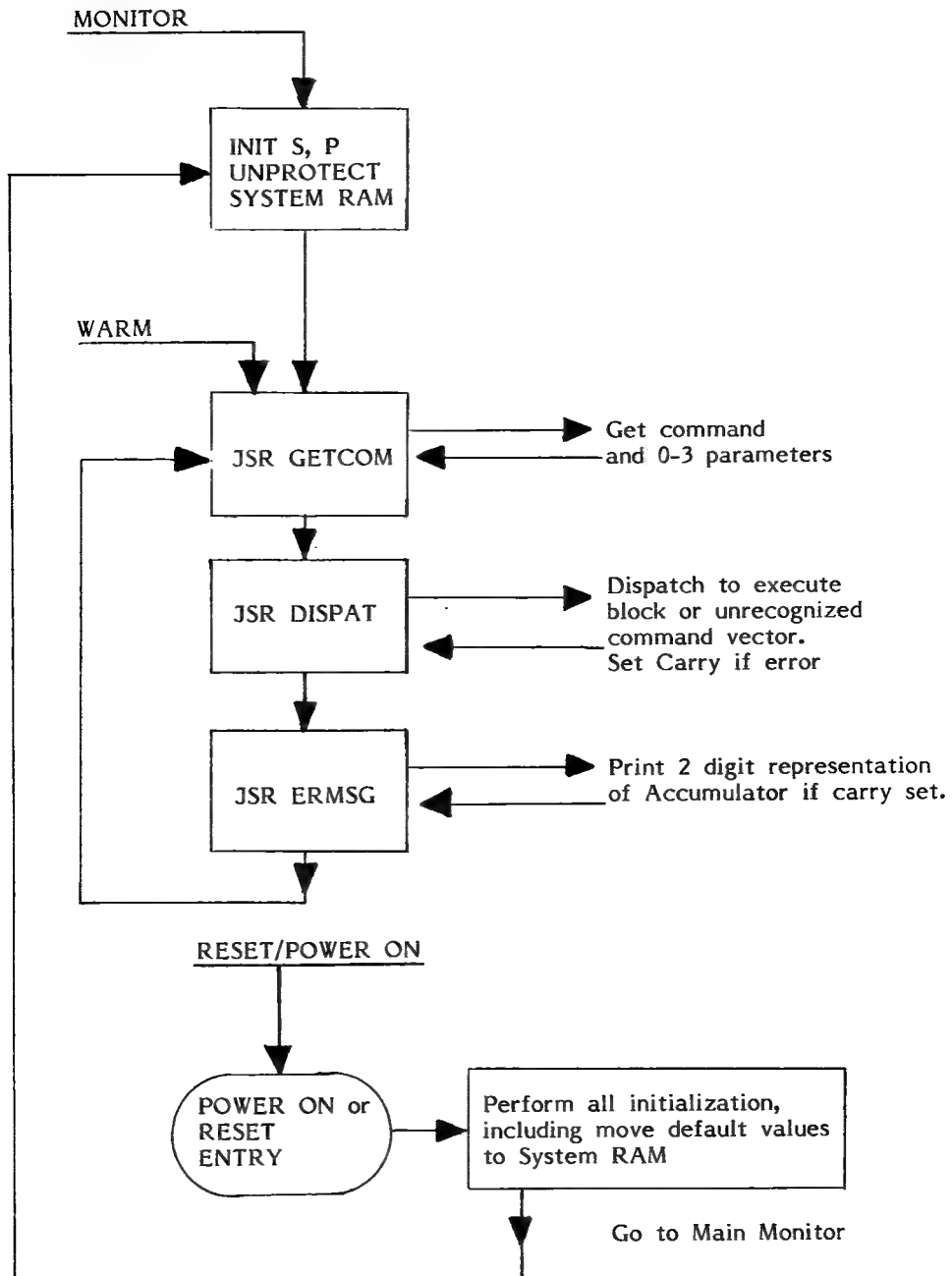


Figure 9-1. MAIN MONITOR FLOW

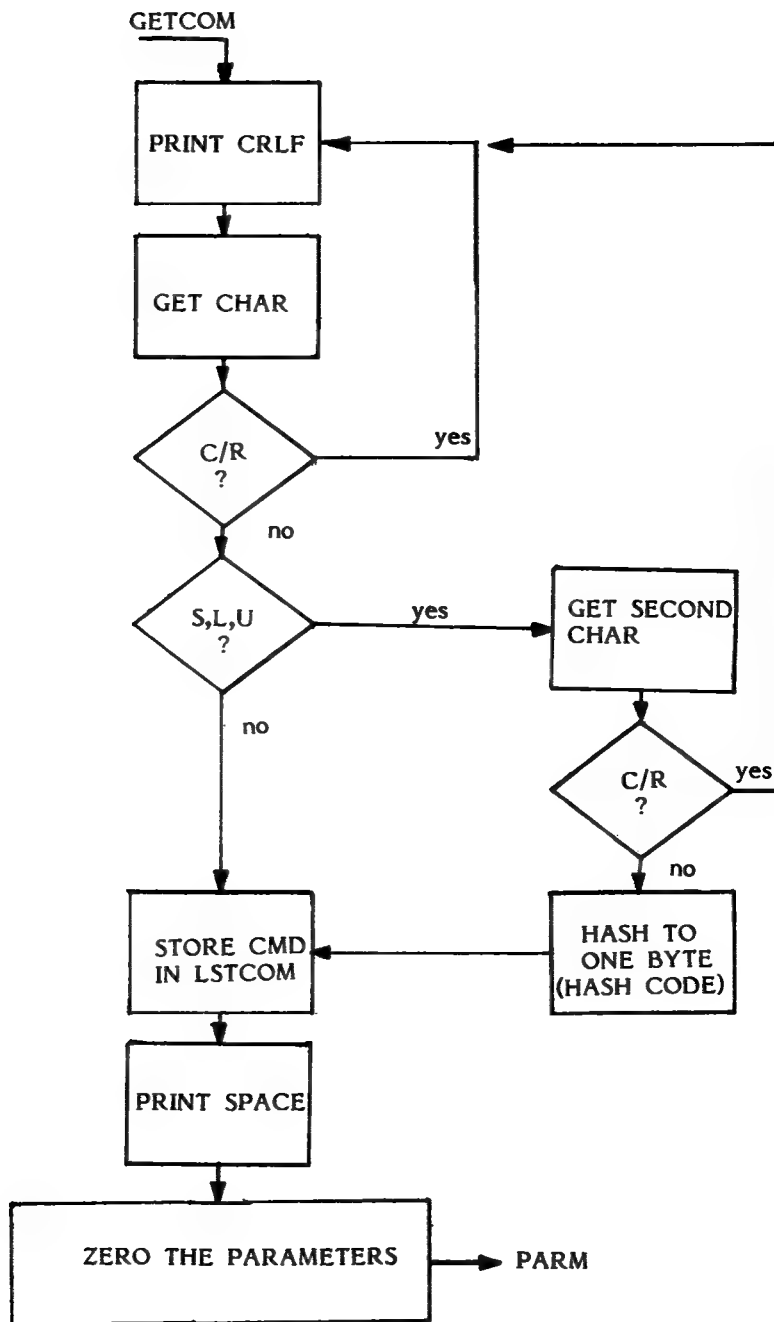


Figure 9-2. GETCOM FLOWCHART

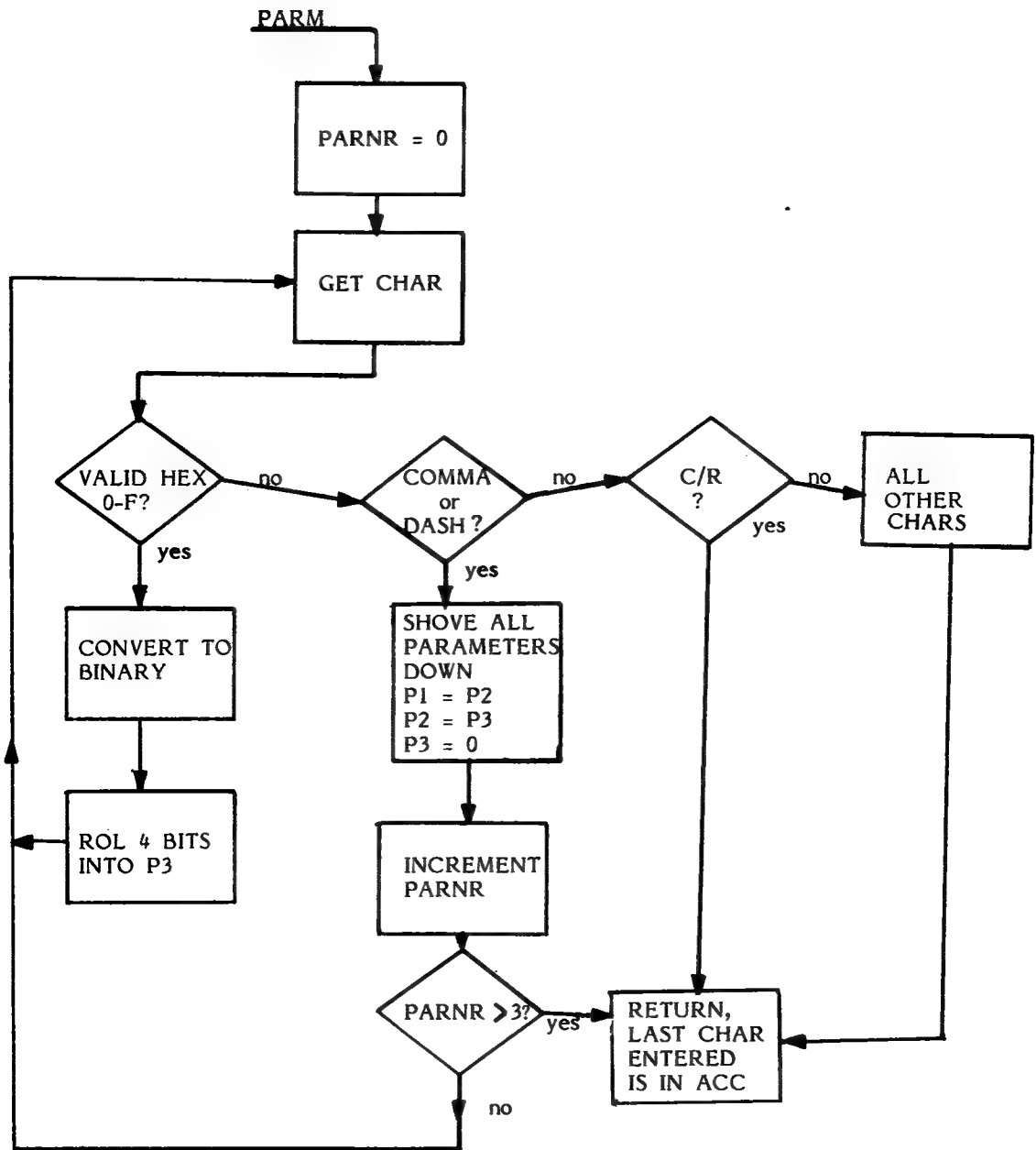


Figure 9-3. PARM FLOWCHART

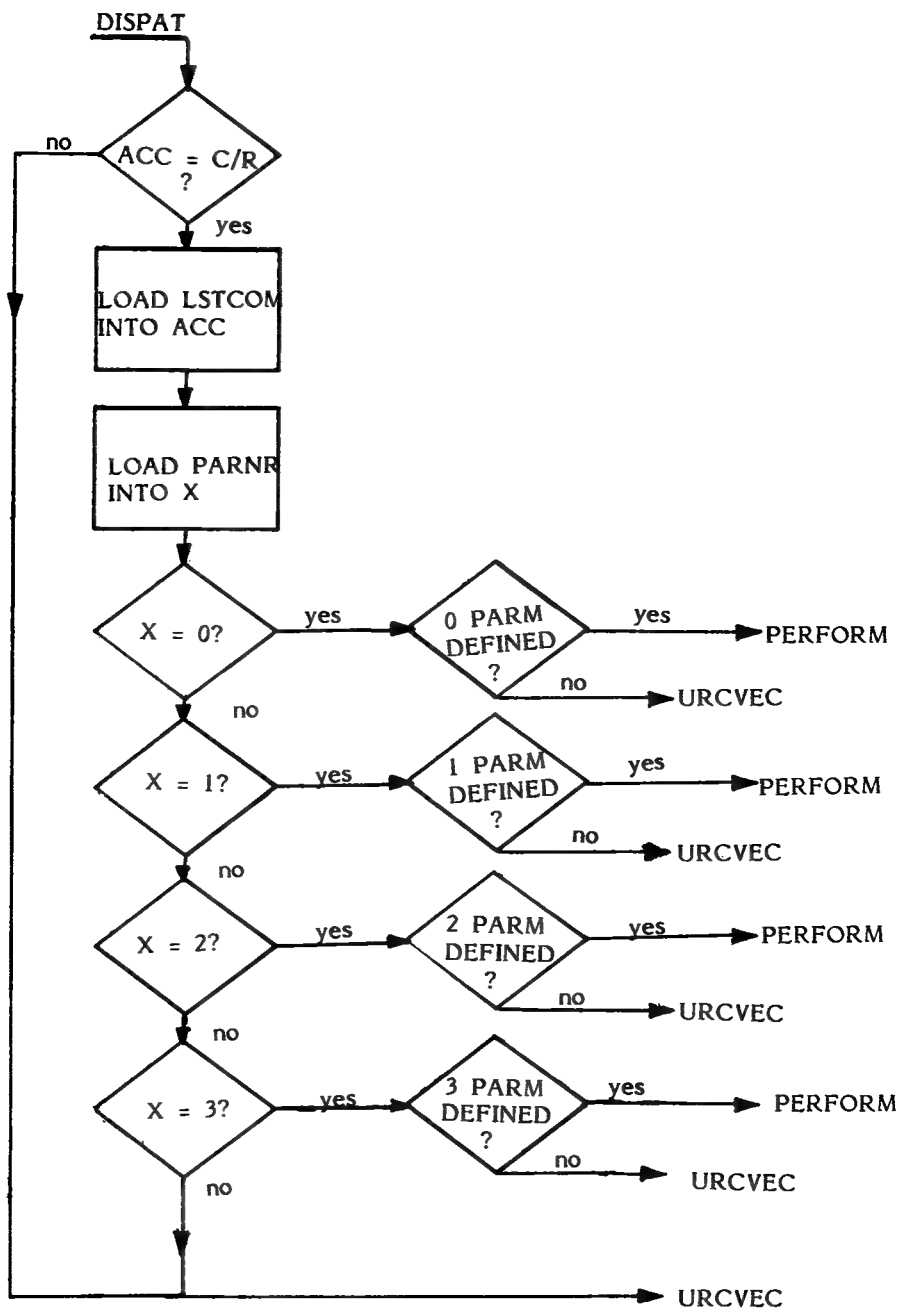


Figure 9-4. DISPAT FLOWCHART

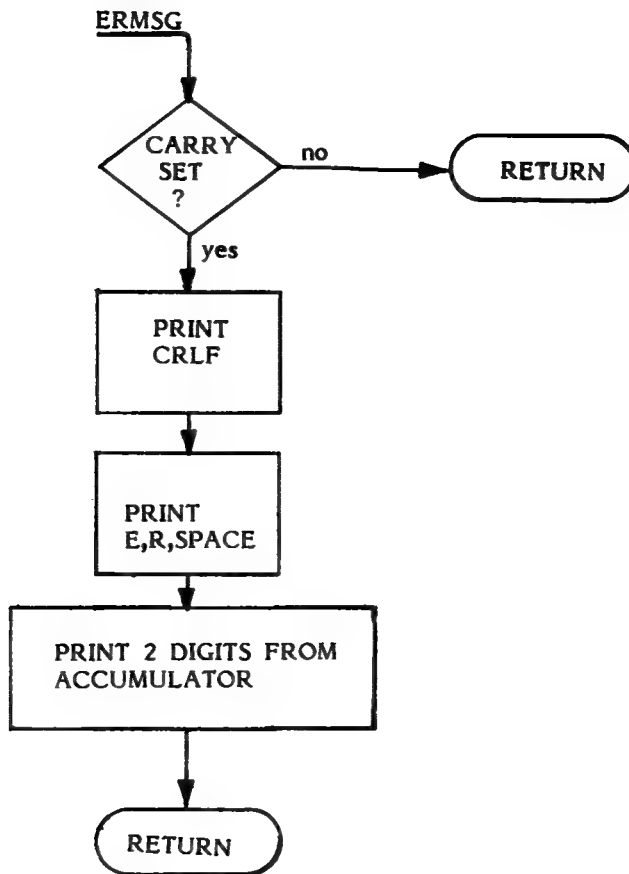


Figure 9-5. ERMSG FLOWCHART

## 9.4 VECTORS AND INTERRUPTS

A concept which is very important in understanding the SY6502 and SUPERMON is that of a vector pointer. A vector pointer consists of two or three locations at a fixed address in memory. These locations contain an address, or a Hex 4C (**JMP**) and an address. The address is in low-order, high-order byte order.

As an example, consider the function of outputting a character. In some cases, the character is to go to the display, in others to a terminal device. The action required in each case is radically different. It would be inefficient, in code and in time, to make the decision before outputting each character. The solution is a vector pointer. Whenever SUPERMON must output a character, it performs a JSR to OUTCHR. OUTCHR saves all registers, then performs a JSR to OUTVEC (at A663, in System RAM). If you are working at the Hex keyboard OUTVEC will contain a JMP HDOUT. HDOUT is the subroutine which will enter a character, in segment code, into the display buffer. If you are using a TTY or CRT, OUTVEC will contain a JMP TOUT. TOUT is the subroutine which sends a character, one bit at a time, to the serial I/O ports. When HDOUT or TOUT performs an RTS, control passes back to OUTCHR. OUTCHR restores the registers and performs an RTS, returning control to the caller.

Notice that the calling routine need not worry where the output is going. It is all taken care of by OUTCHR and OUTVEC.

When a vector is to be referenced by a JMP Indirect, only two bytes are required. Two-byte vectors are normally used only for interrupts.

An **INTERRUPT** is a method of transferring program control, or interrupting, the processor during execution. There are three interrupts defined on the SY6502:

<b>NMI</b>	--	non-maskable interrupt
<b>RST</b>	--	reset/power-on
<b>IRQ</b>	--	interrupt request

When one of these interrupts occurs, the processor pushes the PC register and the Flags register onto the stack, and gets a new PC from the **INTERRUPT VECTOR**. The interrupt vectors are located at the following addresses:

FFFA,FFFB	--	NMI
FFFC,FFFD	--	RESET
FFFE,FFFF	--	IRQ

These locations must contain the addresses of programs which will determine the cause of the interrupt, and respond appropriately.

In the VIM-1, System RAM (A600-A67F) is duplicated at FF80-FFFF (it is "echoed" there). On Reset, SUPERMON points these vectors to its own interrupt-handling routines. When an interrupt occurs, SUPERMON displays the address where the interrupt occurred with a code indicating the cause of the interrupt.

0	=	BRK instruction
1	=	IRQ
2	=	NMI
3	=	USER ENTRY (caused by JSR to USRENT at 8035)

Because all registers are saved, a **(G) (CR)** will cause execution to resume at the point of interruption. The user can intercept interrupt handling by inserting pointers to user interrupt routines in TRCVEC, UBRKVC, NMIVEC, or IRQVEC. See Section 9.7.2 for a discussion of the User Entry pseudo-interrupt. Table 9-2 describes all vectors used by the Monitor.

**Table 9-2. SUPERMON VECTORS**

<u>NAME</u>	<u>LOCATION</u>	<u>FUNCTION</u>
INVEC	A660-A662	Points to input driver.
OUTVEC	A663-A665	Points to output driver.
INSVEC	A666-A668	Points to routine which determines whether or not a key is down.
URCVEC	A66C-A66E	Unrecognized command. All unrecognized commands and parameter entry errors vectored here. Points to a sequence of: SEC - Set Carry RTS - Return
SCNVEC	A66F-A671	Points to routine which performs one scan of display from DISBUF.
EXEVEC	A672-A673	Points to RIN - get ASCII from RAM subroutine.  The Execute (E) command temporarily replaces INVEC with EXEVEC, saving INVEC in SCRA, SCRB. The Hi byte of EXEVEC must be different from the Hi byte of INVEC.
TRCVEC	A674-A675	May be used to point to user trace routine after TRCOFF (See Section 9.6).
UBRKVC	A676-A677	May be used to point to user BRK routine after IRQVEC.
UIRQVC	A678-A679	May be used to point to user NON-BRK IRQ routine after IRQVEC.
NMIVEC	A67A-A67B	Points to routine which saves registers, determines whether or not to trace, based on TV.
IRQVEC	A67E-A67F	Points to routine which saves registers, determines whether or not BRK has occurred, and continues thru UBRKVC or UIRQVC.

## 9.5 DEBUG ON and TRACE

When the DEBUG ON key on your VIM-1 is depressed, DEBUG mode is enabled. In DEBUG mode, an NMI interrupt occurs every time an instruction is fetched from an address that is not within the monitor. SUPERMON's response is to save the registers and display the PC, with code 2 (for NMI). With each **(G) (CR)**, one instruction of the user program will be executed. This is called Single-Stepping.

In order to TRACE, alter the Trace Velocity (TV, at A656) to a non-zero value. (09 is a good value.) If you now enter **(G) (CR)**, SUPERMON will display the PC and the contents of the accumulator, pause, and resume execution. Addresses and accumulator contents will flash by one at a time. To stop the flow, depress any key (Hex keyboard) or the BREAK key (terminal). Execution will halt. A **(G) (CR)** will resume execution. The length of the delay is related to TV (not linearly; try different values) and, of course, the baud rate, if you are working from a terminal.

## 9.6 USER TRACE ROUTINES

As the complexity of your programs increases, you may wish to implement other types of trace routines. To demonstrate how this is done, an example of a user trace routine is provided in Figure 9-6. It prints the op code of the instruction about to be executed, instead of the accumulator contents.

But first of all, we don't want to be interrupted during trace mode by responding to an interrupt (a problem called recursion). SUPERMON will handle this by turning DEBUG OFF, then back ON. However, to implement this program control of DEBUG, you must add jumpers to your VIM-1 board (see Chapter 4).

Now that you have added the jumpers, we are ready to enter the program UTRC and change vectors.

First, enter the program UTRC as given in Figure 9-6. Then change NMIVC to point to TRCOFF, which will save registers, turn DEBUG OFF, and vector thru TRCVEC:

```
SD 80C0,A67A (CR)
```

Now, point TRCVEC to UTRC.

```
SD 0380,A674 (CR)
```

Enter a non-zero value in TV, depress DEBUG ON, and you're ready to trace.

**NOTE: BRK instructions should not be executed with DEBUG ON.**



LINE #	LOC	CODE	LINE
0002	0000		; UTRC - USER TRACE ROUTINE -
0003	0000		; PRINT NEXT OP CODE INSTEAD OF ACCUMULATOR
0004	0000		;
0005	0000		OPPCOM = \$8337 ;PRINT PC, PRINT COMMA
0006	0000		PCLR = \$A659
0007	0000		PCHR = \$A65A
0008	0000		OBCRLF = \$834A ;PRINT BYTE FROM ACC, PRINT CRLF
0009	0000		DELAY = \$835A ;DELAY BASED ON TV
0010	0000		WARM = \$8003 ;WARM MONITOR ENTRY
0011	0000		TRACON = \$80CD ;TURN TRACE ON, RESUME EXECUTION
0012	0000		TV = \$A656 ;TRACE VELOCITY
0013	0000		;
0014	0000		* = \$380 ;PUT IN HI RAM (ENTIRELY RELOCATED)
0015	0380	20 37 83	UTRC JSR OPPCOM ;PRINT PC, COMMA
0016	0383	AD 59 A6	LDA PCLR ;USE PC AS PTR TO OP CODE
0017	0386	85 F0	STA \$F0
0018	0388	AD 5A A6	LDA PCHR
0019	038B	85 F1	STA \$F1
0020	038D	A0 00	LDY #0
0021	038F	B1 F0	LDA (\$F0),Y ;PICK UP OP CODE
0022	0391	20 4A 83	JSR OBCRLF ;OUTPUT OP CODE, CRLF
0023	0394	AE 56 A6	LDX TV ;GET TRACE VELOCITY
0024	0397	F0 05	BEQ NOGO ;NOGO IF ZERO
0025	0399	20 5A 83	JSR DELAY ;DELAY ACCORDING TO TV
0026	039C	90 03	BCC GO ;CARRY SET IF KEY DOWN
0027	039E	4C 03 80	NOGO JMP WARM ;HALT
0028	03A1	4C CD 80	GO JMP TRACON ;CONTINUE
0029	03A4		.END

Figure 9-6. LISTING OF SAMPLE USER TRACE ROUTINE

## USER TRACE EXAMPLE

```

.V 200,20A (CR)
  0200 A9 00 A9 11 A9 22 A9 33,0A
  0208 4C 00 02,58
0358
.SD 80C0,A67A (CR)
.SD 380,A674 (CR)
.G 200 (CR)
0202,A9

  G (CR)
0204,A9

.M A656(CR)
A656,00,09(CR)
A657,4D (CR)
.G 200 (CR)
0202,A9
0204,A9
0206,A9
0208,4C
0200,A9
0202,A9
0204,A9
0206,A9
0208,4C
0200,A9
0202,A9

```

Vector modification  
Vector modification  
Single-Step (Remember  
to set DEBUG ON before  
each (G) (CR)

Trace Velocity = 9

Continuous trace of op codes

## 9.7 MIXED I/O CONFIGURATIONS

The Reset routine that is activated when power is turned on or RST is pressed establishes the terminal I/O configuration by loading a specified value into a location in System RAM, TOUTFL (A654). The high-order four bits of TOUTFL define which terminal devices may be used for input and output. A "1" signifies that a device is enabled, a "0" that it is disabled. The meaning of each bit and the values assigned at system reset are shown below. The routine referenced by entry (1) in the JUMP table will enable the TTY for input. For other configurations, load the appropriate value into TOUTFL.

TOUTFL	bit: <u>7</u>	<u>6</u>	<u>5</u>	<u>4</u>
default value:	1	0	1	1
meaning:	CRT	TTY	TTY	CRT
	INPUT	INPUT	OUTPUT	OUTPUT

Bits 6 and 7 of another location in System RAM, TECHO (A653), are used to inhibit serial output (bit 6) and to control echo to a terminal (bit 7). Bit 6 may be toggled by entering "(CONTROL) O" (0F Hex) on the terminal keyboard or in software. The possible values for TECHO are shown below.

TECHO	80	echo output	(default value)
	C0	echo no output	
	40	no echo no output	
	00	no echo output	

With this information, you can alter the SUPERMON standard I/O configurations to suit your special needs. A common use would be routing your output to a terminal while using the Hex keyboard as an input device. Two possible ways of doing this will be discussed.

First, by merely altering SDBYT and OUTVEC, your input and echo will use the on-board keyboard and display, while Monitor and program output will go to the serial device. Choose the proper baud rate value for your device from the following table and put it in SDBYT (at A651) with the "M" command. Then enter the address of TOUT into OUTVEC as follows:

**.SD 8AA0,A664 (CR)**

Terminal Baud Rate	Value Placed in SDBYT
110	D5
300	4C
600	24
1200	10
2400	06
4800	01

Second, if you wish your input to be echoed on the terminal device, a small program must be entered. First, complete the sequence discussed above. Then, enter the following program:

```

UIN JSR GETKEY      20 AF 88
    BIT TECHO       2C 53 A6
    BPL UOUT        10 03
    JMP OUTCHR      4C 47 8A
UOUT RTS           60

```

Enter the program called "UIN" above at any user RAM location. Then use the "SD" command to put the address of UIN into INVEC (at A661) as follows:

**.SD (UIN),A661 (CR)**

where (UIN) is the address of the program UIN.

## 9.8 USER MONITOR EXTENSIONS

Having read the section on Monitor flow, you will have noticed that unrecognized commands and parameter entries are vectored through URCVEC (A66C-A66E), which normally points to a SEC, RTS sequence at 81D1. By pointing URCVEC to a user-supplied routine in RAM or PROM, SUPERMON can easily be extended. The following example will illustrate the basic principle; many more sophisticated extensions are left to your imagination.

### 9.8.1 Monitor Extension Example

This example will define U0 with two parameters as a logical AND. The parameters and the result are in Hexadecimal.

```
LOGAND    CMP    LSTCOM    ;CMD loaded?
          BEQ    OK
BAD        SEC
          RTS
OK         CMP    #$14    ;USR0
          BNE    BAD      ;branch to next
                                ;command if defined
                                ;two parms
          CPX    #2
          BNE    BAD
DOAND      LDA    P2H
          AND    P3H      ;here's the 'and' hi
          TAX
          LDA    P2L
          AND    P3L      ;'and' lo
          JSR    CRLF      ;get new line
          JSR    SPACE
          JMP    OUTXAH    ;PRINT X and A
          .END
```

To attach LOGAND to the monitor, it must be assembled (probably by hand), entered into memory, and URCVEC altered to contain a JMP to LOGAND.

### 9.8.2 SUPERMON As Extension to User Routines

Because SUPERMON contains a user entry, it can easily be appended to your software. An example of the utility of this feature is a user trace routine, which could have an 'M' command, which would direct it to make SUPERMON available to the user. Here's what the code would look like.

```
UTRACE
...
```

Trace code

```
JSR INCHR
CMP #'M
BNE ELSE
JSR USRENT
JMP UTRACE
...
```

ELSE

Code executed if character  
input is not 'M.'

In this example, the user will type an 'M' to get into monitor, and a **(G) (CR)** to return to the calling portion of UTRACE. Note that the user PC and S registers should not be modified while in monitor if a return to UTRACE is intended.

## 9.9 USE OF SAVER AND RES ROUTINES

SAVER and the RES routines are designed to be used with subroutines. Their usage is as follows:

```

      UPROG      JSR  USUB      USUB      JSR  SAVER
                  {
                  (UPROG CODE)
                  {
                                {
                                (USUB CODE)
                                {
                                JMP RESALL

```

In this example, UPROG calls USUB. USUB calls SAVER, performs its function, and then jumps to RESALL. RESALL restores all registers and returns to UPROG. If RESXF or RESXAF were used instead of RESALL, UPROG would receive the F, or F and A registers as left by USUB.

4



## **APPENDIX A**

### **IMMEDIATE ACTION**

Your VIM-1 microcomputer has been thoroughly tested at the factory and carefully packed to prevent damage in shipping. It should provide you with years of trouble-free operation. If your unit does not respond properly when you attempt to apply power, enter commands from the keyboard, or attach peripheral devices to the system, do not immediately assume that it is defective. Re-read the appropriate sections of this manual and verify that all connections have been properly wired and all procedures properly executed.

If you finally conclude that your VIM-1 is defective, you should return it for repair to an authorized service representative. Specific instructions for obtaining a service authorization number and shipping your unit are contained with warranty information on the card entitled "LIMITED WARRANTY AND SERVICE PLAN" that is included with system reference material.





## APPENDIX B

### PARTS LIST AND COMPONENT LAYOUT

#### MATERIALS AND ACCESSORIES

QTY.	DESCRIPTION	MANUFACTURER/PART NUMBER
1	CONNECTOR, DUAL 22/44	Microplastic 15622DPIS
1	CONNECTOR, DUAL 6/12	Teka TP3-061-E04
6	RUBBER FEET	3M SJ5018
1	SYNERTEK SOFTWARE MANUAL	
1	VIM-1 WARRANTY/USER CLUB REFERENCE CARD	
1	VIM REFERENCE MANUAL	
1	VIM-1 PC BOARD ASSEMBLY	

#### VIM-1 PC BOARD COMPONENTS

QTY.	DESCRIPTION	MFR. NO.	REFERENCE DESIGNATION
1	CPU	SYP6502	U5
2	VIA	SYP6522	U25,U29
1	RAM-I/O	SYP6532	U27
2	4K BIT RAM	SYP2114	U12, U13
1	32K BIT ROM	SYP2332	U20
1	NAND GATE	7400	U8
1	HEX INVERTER	7404	U2
1	AND GATE	7408	U24
2	HEX INVERTER-O.C.	7416	U30, U38
1	NAND GATE	74LS00	U4
1	HEX INVERTER	74LS04	U9
1	TRIPLE NOR GATE	74LS27	U3
1	TIMER	555	U6

QTY.	DESCRIPTION	MFR. NO.	REFERENCE DESIGNATION
1	DECODER	74LS138	U1
1	TRIPLE 3 INPUT NAND	74LS10	U7
1	DECODER	74145	U37
2	DECODER	74LS145	U10, U11
1	COMPARATOR	311	U26
9	RES-100 ohm, ¼W, 5%	RF14J100B	R115-122, 128
9	RES-200 ohm, ¼W, 5%	RF14J200B	R43, 53-58, 111, 114
1	RES-300 ohm, ¼W, 5%	RF14J300B	R107
4	RES-470 ohm, ¼W, 5%	RF14J470B	R84, 88, 124, 127
22	RES-1K, ¼W, 5%	RF14J1KB	R9-12, 41, 47-53, 61-63 73, 78, 85, 92, 101, 112, 113, 123
1	RES-1M, ¼W, 5%	RF14J1MB	R72
2	RES-2.2K, ¼W, 5%	RJ14J2.2KB	R103, 108
18	RES-3.3K, ¼W, 5%	RF14J3.3KB	R59, 60, 70, 74, 79-82, 87, 94- 95, 97, 98, 102, 105, 106, 109, 126
1	RES-4.7K, ¼W, 5%	RF14J4.7KB	R42
10	RES-10K, ¼W, 5%	RF14J10KB	R45, 67-69, 75, 76, 83, 89, 93, 104
3	RES-47K, ¼W, 5%	RF14J47KB	R44, 46,71
1	RES-330K, ¼W, 5%	RF14J330KB	R77
2	RES-27K, ¼W, 5%	RF14J27KC	R90, 96
1	RES-27 ohm, ¼W, 5%	RF14J27B	R125
2	RES-150 ohm, ¼W, 5%	RF14J150B	R99, 110
1	RES-6.8K, ¼W, 5%	RF14J6.8KB	R100
1	CAP-10pf	DM15100J	C13
13	CAP - .01 mfd, 100V	D8203YZ1032	C1, 3, 5, 7, 10, 11, 16, 19, 21, 23, 25, 27, 29
11	CAP - 10 mfd, 25V	T368B106K025PS	C2, 4, 6, 8, 12, 20, 22, 24, 26, 28, 30

QTY.	DESCRIPTION	MFR. NO.	REFERENCE DESIGNATION
3	CAP - .1 mfd, 50V	3429-050E-104M	C9, 17, 18
1	CAP - .47 mfd	C330C474M5V5EA	C15
1	CAP - .0047 mfd	UR2025100X7R472K	C14
12	NPN TRANSISTOR	2N2222A	Q1-4, 10, 18, 19, 27-29, 32, 33
11	PNP TRANSISTOR	2N2907A	Q9, 17, 20-26, 30-31
11	DIODE, G.P.	1N914	CR25-33, 37, 38
1	DIODE, ZENER	1N4735	CR34
4	SOCKET - 24-PIN DIP	C8424-02	SK20-23
5	SOCKET - 40-PIN DIP	C8440-02	SK5, 25, 27-29
8	SOCKET - 18-PIN DIP	C8418-02	SK12-19
1	DUAL HEADER	929665-01-07	"K" Connector
1	KEYBOARD		KB1
1	PC BOARD		PC1
6	7-SEGMENT DISPLAY, 0.3"	MAN 71A	U31-36
2	LED	RL4850	CR35,36
1	SPEAKER	70057	SP1
1	CRYSTAL	CY1A	Y1



## APPENDIX C

### AUDIO TAPE FORMATS

**HIGH-SPEED FORMAT** — High speed data transfer takes place at 185 bytes per second. Every byte consists of a start bit (0), followed by eight data bits. The least significant bit is transmitted first. A "1" bit is represented by 1 cycle of 3000 Hz, while a "0" bit is represented by 1½ cycles of 1500 Hz. Physical record format is shown below.

8 sec. "mark"	256 SYN chars.	*	ID	SAL	SAH	EAL +1	EAH +1	DATA	/	CKL	CKH	EOT	EOT
---------------	----------------	---	----	-----	-----	-----------	-----------	------	---	-----	-----	-----	-----

- 8 sec. "mark" - Allows the tape to advance beyond the leader and creates an inter-record gap.
- SYN (16 Hex) - ASCII sync characters that allow the VIM-1 to synchronize with the data stream.
- \* (2A Hex) - ASCII character that indicates the start of a valid record.
- ID - Single byte that uniquely identifies the record.
- SAL - Low order byte of the Starting Address of data which was taken from memory.
- SAH - High order byte of the Starting Address of data which was taken from memory.
- EAL +1 - Low order byte of the address following the Ending Address of data which was taken from memory.
- EAH +1 - High order byte of the address following the Ending Address of data which was taken from memory.
- DATA - Data bytes.
- / (2F Hex) - ASCII character that indicates the end of the data portion of a record.
- CKL - Low order byte of a computed checksum.
- CKH - High order byte of a computed checksum.
- EOT (04 Hex) - ASCII characters that indicate the end of the tape record.

KIM FORMAT -- Data transfer in KIM format takes place at approximately 8 bytes per second. A "1" bit is represented by 18 half-cycles of 3600 Hz followed by 24 half-cycles of 2400 Hz, while a "0" bit is represented by 36 half-cycles of 3600 Hz followed by 12 half-cycles of 2400 Hz. Each 8-bit byte from memory is represented by two ASCII characters. The byte is separated into two half-bytes, then each half-byte is converted into an ASCII character that represents a Hex digit. The least significant bit is transmitted first. The KIM physical record format is shown below.

128 SYN chars.	*	ID	SAL	SAH	DATA	/	CKL	CKH	EOT	EOT
----------------	---	----	-----	-----	------	---	-----	-----	-----	-----

The ASCII characters SYN, "\*" (2A Hex) and "/" (2F Hex) as well as ID, SAL, SAH, CKL, CKH and EOT serve the same functions as in HIGH-SPEED format. Sync characters, \*, / and EOT are represented by single ASCII characters, while the remaining record items require two ASCII characters. Note that EAL and EAH are not used in the KIM format.

## APPENDIX D

### PAPER TAPE FORMAT

When data from memory is stored on paper tape, each 8-bit byte is separated into two half-bytes, then each half-byte is converted into an ASCII character that represents a Hex digit (0-F). Consequently, two ASCII characters are used to represent one byte of data. In the paper tape record format shown below, each N, A, D, and X represents one ASCII character.

; N<sub>1</sub>N<sub>0</sub> A<sub>3</sub>A<sub>2</sub>A<sub>1</sub>A<sub>0</sub> (D<sub>1</sub>D<sub>0</sub>)<sub>1</sub> (D<sub>1</sub>D<sub>0</sub>)<sub>2</sub> . . . (D<sub>1</sub>D<sub>0</sub>)<sub>n</sub> X<sub>3</sub>X<sub>2</sub>X<sub>1</sub>X<sub>0</sub>

;	- Start of record mark
N <sub>1</sub> N <sub>0</sub>	- Number of data bytes in (Hex) contained in the record
A <sub>3</sub> A <sub>2</sub> A <sub>1</sub> A <sub>0</sub>	- Starting address from which data was taken
(D <sub>1</sub> D <sub>0</sub> ) <sub>1</sub> -(D <sub>1</sub> D <sub>0</sub> ) <sub>n</sub>	- Data
X <sub>3</sub> X <sub>2</sub> X <sub>1</sub> X <sub>0</sub>	- 16-bit checksum of all preceding bytes in the record including N <sub>1</sub> N <sub>0</sub> and A <sub>3</sub> A <sub>2</sub> A <sub>1</sub> A <sub>0</sub> , but excluding the start of record mark.

A single record will normally contain a maximum of 16 (10 Hex) data bytes. This is the system default value that is stored in system RAM at power-up or reset in location MAXRC (A658). You can substitute your own value by storing different number in MAXRC. To place an end of file after the last data record saved, place the TTY in local mode punch on, and enter ;00 followed by **(CR)**.





## APPENDIX E

### VIM COMPATABILITY WITH KIM PRODUCTS

If you are a VIM-1 user who has peripheral devices which you have previously used with the KIM system or software which has been run on a KIM module, you'll find VIM to be generally upward compatible with your hardware and software. The following two sections describe the levels of compatability between the two systems to allow you to undertake any necessary modifications.

#### E.1 HARDWARE COMPATABILITY

Table E-1 describes the upward compatability between VIM and KIM at the Expansion (E) connector, while Table E-2 describes the compatability on the Applications (A) connector.

I/O port addresses differ between the two systems; you should consult the Memory Map in Figure 4-10 for details.

Power Supply inputs are provided on a separate connector with VIM-1, which means that if you have been using your power supply with a KIM device it will be necessary to rewire its connections to use the special connector on the VIM-1 board.

#### E.2 SOFTWARE COMPATABILITY

Table E-3 lists important user-available addresses and routines in the KIM-1 monitor program and their counterparts in VIM-1's SUPERMON. Many of the routines do not perform identically in the two systems, however, and you should check their operation in Table 9-1 before using them.

**Table E-1. EXPANSION CONNECTOR (E) COMPATABILITY**

VIM DESCRIPTION	VIM NAME	PIN #	KIM NAME	KIM DESCRIPTION
Jumper (Y,26) Selectable: OFF - Open Pin ON - Debug On/Off Output (U8-8)	DBOUT	17	SSTOUT	From (SYNC • NOT MONITOR) U26-6
Power On Reset Signal Output: "0" After power on "1" When reset by software	POR	18		No equivalent

**Table E-2. APPLICATION CONNECTOR (A) COMPATABILITY**

VIM DESCRIPTION	VIM NAME	PIN #	KIM NAME	KIM DESCRIPTION
Jumper (V,23) Selectable: OFF - Open Pin ON - Remote Audio Control Out	AUD.RC	N	+12V	+12V Not required on VIM
Jumper (HH,41) Selectable: OFF Open Pin ON ICXX Decode Out		K	DECODE Enable	Enable 8K Decoder

**Table E-3. VIM-KIM SOFTWARE COMPATABILITY**

VIM		KIM		FUNCTION
Label	Address(es)	Label	Address(es)	
PCLR	A659	PCL	00EF	Program Counter - low
PCHR	A65A	PCH	00F0	Program Counter - high
FR	A65C	P	00F1	Status Register
SR	A65B	SP	00F2	Stack Pointer
AR	A65D	A	00F3	Accumulator
YR	A65F	Y	00F4	Y - Register
XR	A65E	X	00F5	X - Register
SCR6	A636	CHKH1	00F6	Checksum - low
SCR7	A637	CHKSUM	00F7	Checksum - high
P2L	A64C	SAL	17F5	Start Addr Low - audio/paper tape
P2H	A64D	SAH	17H6	Start Addr High - audio/paper tape
P3L	A64A	EAL	17F7	End Addr+1 Low - audio/paper tape
P3H	A64B	EAH	17F8	End Addr+1 High - audio/paper tape
P1L	A64E	ID	17F9	ID Byte audio Tape
NMIVEC	A67A-B FFFA-B	NMIV	17FA-B FFFA-B	NMI Vector
RSTVEC	FFFC-D	RSTV	17FC-D FFFC-D	Reset Vector
IRQVEC	A67E-F FFFE-F	IRQV	17FE-F FFFE-F	IRQ Vector
DUMPT	8E87	DUMPT	1800	Dump memory to audio tape
LOADT	8C78	LOADT	1873	Load memory from audio tape
CHKT	8E78	CHKT	194C	Compute checksum for audio tape
OUTBTC	8F4A	OUTBTC	195E	Output one KIM byte
HEXOUT	8F52	HEXOUT	196F	Convert LSD of A to ASCII AND write to audio tape

**Table E-3. VIM-KIM SOFTWARE COMPATABILITY (Continued)**

VIM		KIM		FUNCTION
Label	Address(es)	Label	Address(es)	
OUTCHT	8F5D	OUTCHT	197A	Write one ASCII character to audio tape
RDBYT	8E2C	RDBYT	19F3	Read one byte from audio tape
PACKT	8E3E	PACKT	1A00	Pack ASCII to nibble
RDCHT	8E61	RDCHT	1A24	Read one character from audio tape
RDBITK	8E0F	RDBIT	1A41	Read one bit from tape
SVNMI	809B	SAVE	1C00	Monitor NMI entry
RESET	8B4A	RST	1C22	Monitor RESET entry
OUTPC	82EE	PCCMD	1CDC	Display PC
INCHR	8A1B	READ	1CGA	Get character
LP2B+7	841E	LOAD	1CE7	Load paper tape
SP2B+4	869C	DUMP	1D42	Save paper tape
OUTS2	8319	PRTPNT	1E1E	Print pointer
OUTBYT	82FA	PRTBYT	1E3B	Print 1 byte as 2 ASCII character
INCHR	8A1B	GETCH	1E5A	Get character
DLYF	8AE6	DELAY	1ED4	Delay 1 bit time
DLYH	8AE9	DEHALF	1EEB	Delay ½ bit time
INSTAT	8386	AK	1EFE	Determine if key is down
OUTDSP	89C1	SCAND	1F19	Output to LED display
SCAND	8906	SCANDS	1F1F	Scan LED display
INCCMP	82B2	INCPT	1F63	Increment pointer
GETKEY	88AF	GETKEY	1F6A	Get key
CHKSAD	82DD	CHK	1F91	Compute checksum
INBYTE	81D9	GETBYT	1F9D	Get 2 Hex characters and pack



## APPENDIX F

### CREATING AND USING A SYNC TAPE

To read serial data from tape, the VIM-1 makes use of synchronizing (sync) characters that are part of every tape record. For a complete description of audio tape record formats, refer to Appendix C.

When the VIM-1 searches for a record, an "S" is displayed until the sync characters are recognized and data transfer begins. However, if the volume and tone controls on the recorder are not set correctly, the sync characters will not be recognized, the "S" on the display will not go out, and the record will not be loaded into memory.

Before attempting to save and load data for the first time, or whenever the control levels have been changed since the recorder was last used, you should perform a load operation using a tape containing only sync characters. By adjusting the volume and tone controls until the displayed "S" goes out, you can set the control levels properly for actual data.

You may want to generate two sync tapes, one for HIGH-SPEED format, the other for KIM format, just once, and save them for future use.

To generate a sync tape, enter the sync character generation program for one of the formats into RAM starting in location 0200 (Hex). The assembly language code and the machine language code for both formats are shown below. Read the pairs of Hex digits from left to right and top to bottom. For example, the code for HIGH-SPEED format should be entered in the following sequence: A0 80 20 B6 8D A9 . . . .

Next, insert a tape into the cassette unit. If the unit is equipped with remote control, place it in Record mode. Set the volume and tone controls to mid-range, then enter the command to execute the program:

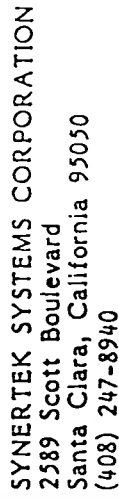
(GO) 200 (CR)

If you are operating the cassette controls manually, place the unit in Record mode after entering the command, but before entering (CR). Remote controlled units will advance the tape automatically. Let the tape run for several minutes, then press RST to end the program. For manual operation, also press STOP on the tape unit.

To set the volume and tone controls for loading data into memory, rewind the tape to the beginning (you may need to pull out the Remote jack or keep your finger on RST), then place the unit in Play mode if it is equipped with remote control. Next, enter the load command for the appropriate format ( LD 1) for KIM, (LD 2) for HIGH-SPEED, followed by a carriage return (CR) ).

If you have a manually operated unit, place it in Play mode after entering the command. While the tape advances, adjust the volume and tone controls until the "S" on the display goes out and remains out, then press RST and stop the tape.

You can now remove the sync tape and proceed to save and load actual programs and data.

[illegible]

**APPENDIX G**  
**SY6502 DATA SHEET**

MARCH 1978

## Memory Products

### Static Shift Registers

<b>SY2533</b>	1024x1, 1.5MHz, Dual Input
<b>SY2833</b>	1024x1, 2MHz, Dual Input
<b>SY2833A</b>	1024x1, 3MHz, Dual Input
<b>SY2833B</b>	1024x1, 4MHz, Dual Input
<b>SY2833C</b>	1024x1, 5MHz, Dual Input
<b>SY2535/2535A</b>	480x2, 1.5MHz/3MHz, Recirculate
<b>SY2534/2534A</b>	512x2, 1.5MHz/3MHz, Recirculate

### Dynamic Shift Registers

<b>SY2401/2401-1</b>	1024x2, 1MHz/2.5MHz, Recirculate
<b>SY2825A</b>	1024x2, 6MHz, Common Recirculate
<b>SY2826</b>	1024x2, 6MHz
<b>SY2827</b>	2048x1, 6MHz, Recirculate
<b>SY1402A/2802</b>	256x4, 5MHz/10MHz, Low Power, Low Capacitance
<b>SY1403A/2803</b>	512x2, 5MHz/10MHz, Low Power, Low Capacitance
<b>SY1404A/2804</b>	1024x1, 5MHz/10MHz, Low Power, Low Capacitance

### Static Random Access Memories

<b>SY21H02/-2</b>	1024x1, 175/200nsec
<b>SY2102A-2</b>	1024x1, 250nsec, 65mA
<b>SY2102A-4/-8</b>	1024x1, 450/650nsec, 55mA
<b>SY21L02A/B</b>	1024x1, 350nsec/400nsec, 30mA
<b>SY2102-1</b>	1024x1, 500nsec, 55mA
<b>SY21L02-1</b>	1024x1, 500nsec, 40mA
<b>SY21L02</b>	1024x1, 1000nsec, 15mA
<b>SY21H01/-2</b>	256x4, 175/200nsec, Separate I/O
<b>SY2101-1</b>	256x4, 500nsec, 70mA, Separate I/O
<b>SY2101A/-2/-4</b>	256x4, 350/250/450nsec, 55mA, Separate I/O
<b>SY21H11/-2</b>	256x4, 175/200nsec, Common I/O
<b>SY2111-1</b>	256x4, 500nsec, 70mA, Common I/O
<b>SY2111A/-2/-4</b>	256x4, 350/250/450nsec, 55mA, Common I/O
<b>SY21H12/-2</b>	256x4, 175/200nsec, Common I/O
<b>SY2112-1</b>	256x4, 500nsec, 70mA, Common I/O
<b>SY2112A/-2/-4</b>	256x4, 350/250/450nsec, Common I/O
<b>SY2114/-3/-2</b>	1024x4, 450/300/200nsec, 18 pin
<b>SY2114L/-3/-2</b>	1024x4, 450/300/200nsec, 70mA, 18 pin
<b>SY2114LV/-3/-2</b>	1024x4, Power Down, 450/300/200nsec, 70mA
<b>SY2142/-3/-2</b>	1024x4, 450/300/200nsec, 20 pin
<b>SY2142L/-3/-2</b>	1024x4, 450/300/200nsec, 20 pin, 70mA
<b>SY2142LV/-3/-2</b>	1024x4, 450/300/200nsec, Power Down, 20 pin, 70mA
<b>SY2147</b>	• 4096x1, 55nsec, 160mA operating, 20mA standby
<b>SY5101L/-3</b>	CMOS, 256x4, 650nsec, 200/10pA Standby, Power Down
<b>SY5101L-1</b>	CMOS, 256x4, 450nsec, 10pA Standby, Power Down
<b>SY5101-8</b>	CMOS, 256x4, 800nsec

## Memory Products

### Static Read Only Memories

<b>SY2530</b>	512x8, 550nsec
<b>SY3514/15</b>	512x8, 700/500nsec
<b>SY4000</b>	2048x8 or 4096x4, 550nsec
<b>SY2316A</b>	2048x8, 550nsec
<b>SY2316B</b>	2048x8, 450nsec, 8K/16K PROM Compatible
<b>SY2332</b>	4096x8, 450nsec, 16K PROM (2716) Compatible
<b>SY2304</b>	• 8192x8, 450nsec, 24 pin

## Timekeeping Products

<b>SY5001</b>	CMOS 7 Function, 1 button, 6 digit LCD 12/24 hour and U.S./European Option
<b>SY5002</b>	CMOS 7 Function, 1 button, 6 digit LED 12/24 hour and U.S./European Option
<b>SY500B</b>	CMOS analog Frequency Divider, 1/2Hz 1/12Hz 20 stepper motor Driver
<b>SY5009A</b>	CMOS Chronograph/Alarm, 6 digit LCD, 12/24 hour and U.S./European Options, Digital Speed Adjust, Event Counter, Taylor/Standard Split, Accumulate

## Custom Products

Custom circuit design and processing is an integral part of Synertek's business. Ion implanted N-channel, P-channel and CMOS silicon gate processes all are used for custom circuit manufacturing. Synertek is experienced in interfacing at all levels of development: Logic definition, circuit design, or customer designed tooling. For detailed information contact our sales offices or product marketing in Santa Clara.

## Microprocessor Products

<b>SY0500/1</b>	• Single Chip Microprocessor, 40 Pin CPU with 2K bytes of ROM, 64 bytes of RAM and 32 I/O Ports, software compatible with 6502
<b>SY0502</b>	40 Pin CPU, on-chip clock, 65K addressable bytes
<b>SY0503</b>	28 Pin CPU, on-chip clock, 4K addressable bytes
<b>SY0504</b>	28 Pin CPU, one interrupt, on-chip clock, 8K addressable bytes
<b>SY0505</b>	28 Pin CPU, one interrupt, on-chip clock, RDY feature, 4K addressable bytes
<b>SY0506</b>	28 Pin CPU, on-chip clock, 2 phases brought out, 4K addressable bytes
<b>SY0512</b>	40 Pin CPU, external clock, 65K addressable bytes
<b>SY0513</b>	28 Pin CPU, external clock, 4K addressable bytes
<b>SY0514</b>	28 Pin CPU, one interrupt, external clock, 8K addressable bytes
<b>SY0515</b>	28 Pin CPU, one interrupt, external clock, RDY feature, 4K addressable bytes
<b>SY0520</b>	40 Pin Peripheral Interface Adapter Plug replaceable to Motorola's PIA
<b>SY0522</b>	40 Pin VIA—Versatile Interface Adapter—Features of 6520 Plus: Two Interval Timers, Latching on I/O Pins, Shift Register for P/S and S/P interface, Interrupt Flag and Enable registers for ease of use
<b>SY0530</b>	40 Pin COMBO, 64 bytes RAM, 1K bytes ROM, 16 I/O channels, Interval Timer
<b>SY0531</b>	• ROM/RAM/I-O/Timer Array, 40 Pin COMBO, 128 bytes RAM, 2K bytes ROM, 16 I/O channels, Interval Timer
<b>SY0532</b>	40 Pin COMBO, 128 bytes RAM, 16 I/O channels, Interval Timer
<b>SY0551</b>	• 40 Pin Asynchronous Communications Chip with on-board programmable baud rate generator

\* To be announced.



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## SY6500

### SY6500 MICROPROCESSORS

#### The SY6500 Microprocessor Family Concept —

The SY6500 Series Microprocessors represent the first totally software compatible microprocessor family. This family of products includes a range of software compatible microprocessors which provide a selection of addressable memory range, interrupt input options and on-chip clock oscillators and drivers. All of the microprocessors in the SY6500 group are software compatible within the group and are bus compatible with the M6800 product offering.

The family includes five microprocessors with on-board clock oscillators and drivers and four microprocessors driven by external clocks. The on-chip clock versions are aimed at high performance, low cost applications where single phase inputs, crystal or RC inputs provide the time base. The external clock versions are geared for the multi processor system applications where maximum timing control is mandatory. All versions of the microprocessors are available in 1 MHz and 2 MHz ("A" suffix on product numbers) maximum operating frequencies.

#### Features of the SY6500 Family

- . Single five volt supply
- . N channel, silicon gate, depletion load technology
- . Eight bit parallel processing
- . 56 Instructions
- . Decimal and binary arithmetic
- . Thirteen addressing modes
- . True indexing capability
- . Programmable stack pointer
- . Variable length stack
- . Interrupt capability
- . Non-maskable interrupt
- . Use with any type or speed memory
- . Bi-directional Data Bus
- . Instruction decoding and control
- . Addressable memory range of up to 65K bytes
- . "Ready" input
- . Direct memory access capability
- . Bus compatible with MC6800
- . Choice of external or on-board clocks
- . 1MHz and 2MHz operation
- . On-the-chip clock options
  - \* External single clock input
  - \* RC time base input
  - \* Crystal time base input
- . 40 and 28 pin package versions
- . Pipeline architecture

#### Members of the Family

##### Microprocessors with On-Board Clock Oscillator

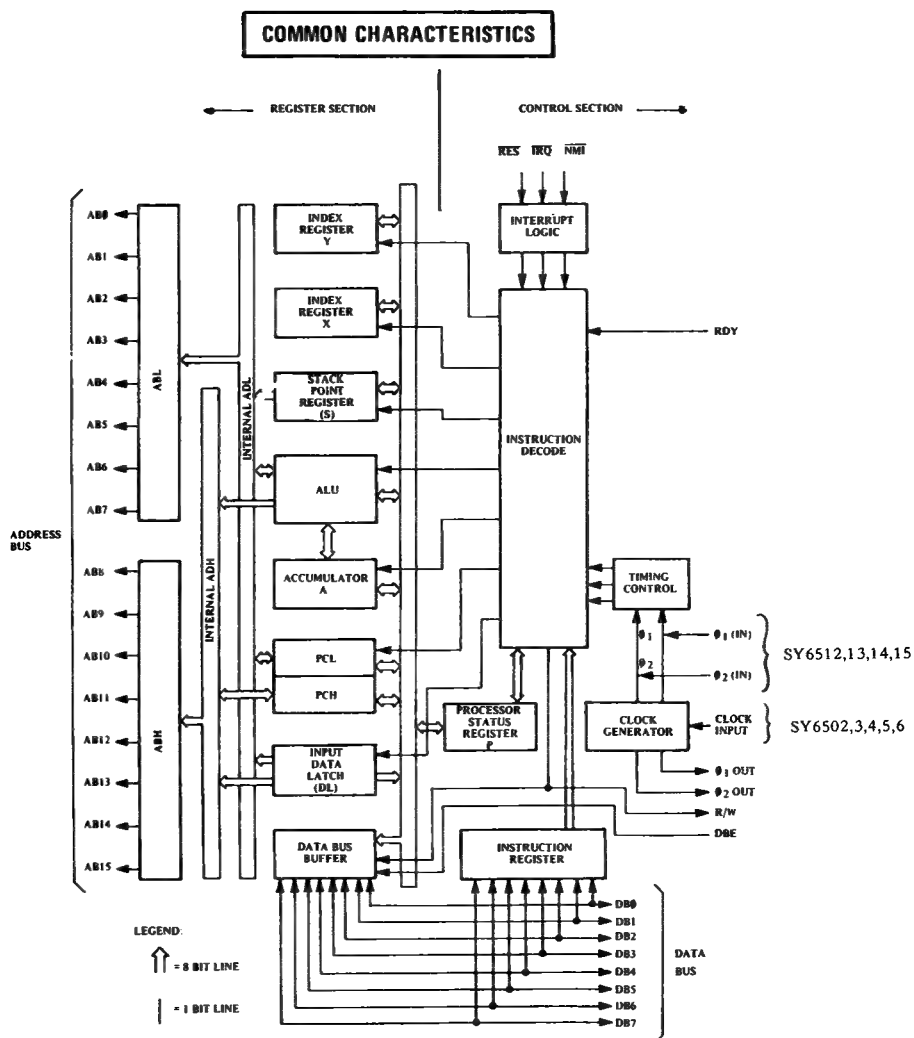
- SY6502
- SY6503
- SY6504
- SY6505
- SY6506

##### Microprocessors with External Two Phase Clock Input

- SY6512
- SY6513
- SY6514
- SY6515

## Comments on the Data Sheet

The data sheet is constructed to review first the basic "Common Characteristics" - those features which are common to the general family of microprocessors. Subsequent to a review of the family characteristics will be sections devoted to each member of the group with specific features of each.



Note: 1. Clock Generator is not included on SY6512,13,14,15

2. Addressing Capability and control options vary with each of the SY6500 Products.

## SY6500 Internal Architecture

# COMMON CHARACTERISTICS

## MAXIMUM RATINGS

RATING	SYMBOL	VALUE	UNIT
SUPPLY VOLTAGE	V <sub>CC</sub>	-0.3 to +7.0	Vdc
INPUT VOLTAGE	V <sub>IN</sub>	-0.3 to +7.0	Vdc
OPERATING TEMPERATURE	T <sub>A</sub>	0 to +70	°C
STORAGE TEMPERATURE	T <sub>STG</sub>	-55 to +150	°C

This device contains input protection against damage due to high static voltages or electric fields; however, precautions should be taken to avoid application of voltages higher than the maximum rating.

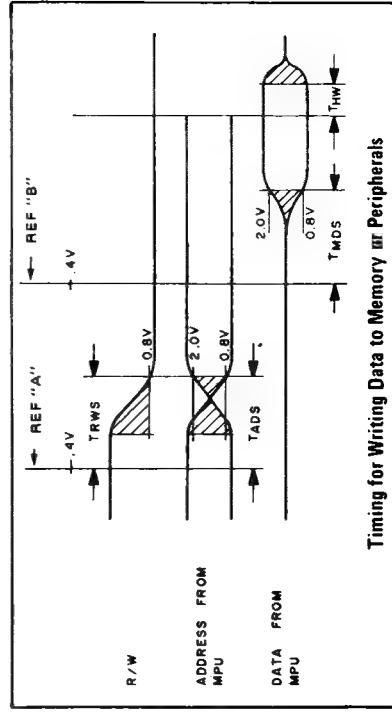
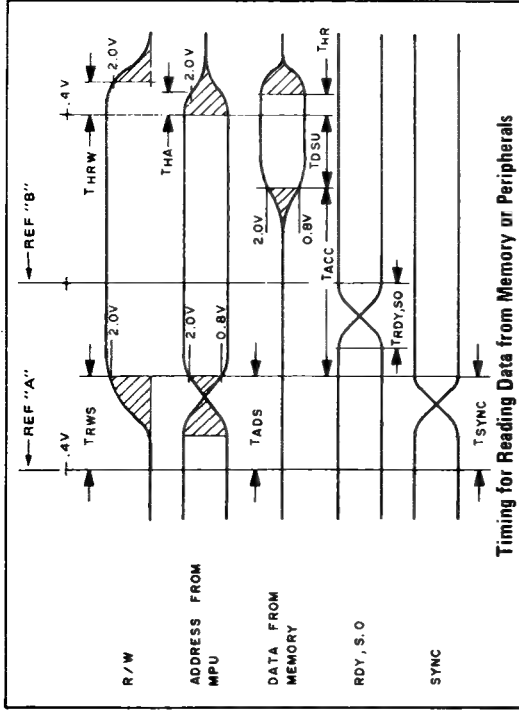
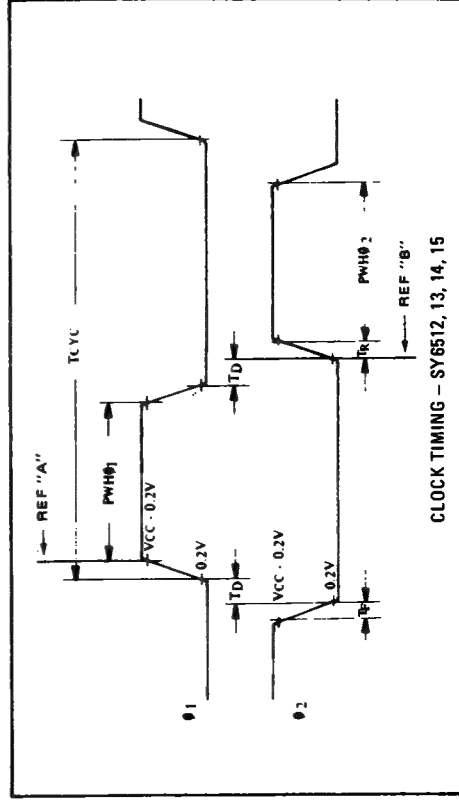
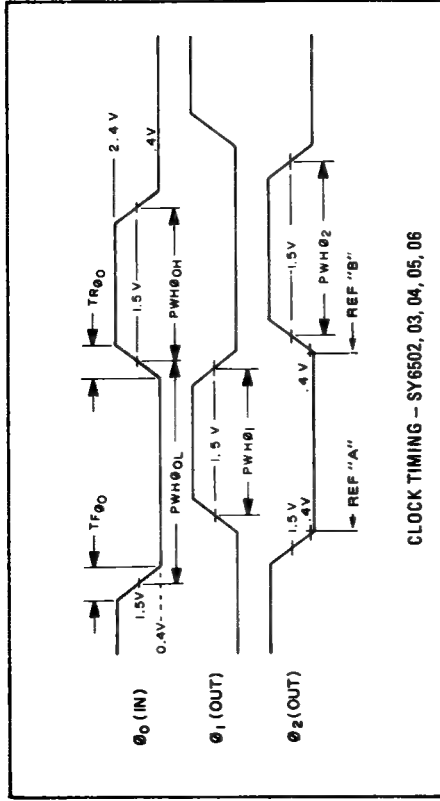
## ELECTRICAL CHARACTERISTICS (V<sub>CC</sub> = 5.0V ± 5%, V<sub>SS</sub> = 0, T<sub>A</sub> = 25° C)

Ø<sub>1</sub>, Ø<sub>2</sub> applies to SY6512, 13, 14, 15, Ø<sub>0</sub> (in) applies to SY6502, 03, 04, 05 and 06

CHARACTERISTIC	SYMBOL	MIN.	TYP.	MAX.	UNIT
Input High Voltage Logic, Ø <sub>0</sub> (in) Ø <sub>1</sub> , Ø <sub>2</sub>	V <sub>IH</sub>	V <sub>SS</sub> + 2.4 V <sub>CC</sub> - 0.2	- -	V <sub>CC</sub> V <sub>CC</sub> + 0.25	Vdc
Input Low Voltage Logic, Ø <sub>0</sub> (in) Ø <sub>1</sub> , Ø <sub>2</sub>	V <sub>IL</sub>	V <sub>SS</sub> - 0.3 V <sub>SS</sub> - 0.3	- -	V <sub>SS</sub> + 0.4 V <sub>SS</sub> + 0.2	Vdc
Input High Threshold Voltage RES, NMI, RDY, IRQ, Data, S.O.	V <sub>IHT</sub>	V <sub>SS</sub> + 2.0	-	-	Vdc
Input Low Threshold Voltage RES, NMI, RDY, IRQ, Data, S.O.	V <sub>ILT</sub>	-	-	V <sub>SS</sub> + 0.8	Vdc
Input Leakage Current (V <sub>in</sub> = 0 to 5.25V, V <sub>CC</sub> = 0) Logic (Excl. RDY, S.O.) Ø <sub>1</sub> , Ø <sub>2</sub> Ø <sub>0</sub> (in)	I <sub>in</sub>	- - -	- - -	2.5 100 10.0	µA µA µA
Three-State (Off State) Input Current (V <sub>in</sub> = 0.4 to 2.4V, V <sub>CC</sub> = 5.25V) Data Lines	I <sub>TSI</sub>	-	-	10	µA
Output High Voltage (I <sub>LOAD</sub> = -100µAdc, V <sub>CC</sub> = 4.75V) SYNC, Data, A0-A15, R/W	V <sub>OH</sub>	V <sub>SS</sub> + 2.4	-	-	Vdc
Output Low Voltage (I <sub>LOAD</sub> = 1.6mAdc, V <sub>CC</sub> = 4.75V) SYNC, Data, A0-A15, R/W	V <sub>OL</sub>	-	-	V <sub>SS</sub> + 0.4	Vdc
Power Dissipation	P <sub>D</sub>	-	.25	.70	W
Capacitance (V <sub>in</sub> = 0, T <sub>A</sub> = 25°C, f = 1MHz)	C				pF
Logic	C <sub>in</sub>	-	-	10	
Data		-	-	15	
A0-A15, R/W, SYNC	C <sub>out</sub>	-	-	12	
Ø <sub>0</sub> (in)	C <sub>Ø<sub>0</sub>(in)</sub>	-	-	15	
Ø <sub>1</sub>	C <sub>Ø<sub>1</sub></sub>	-	30	50	
Ø <sub>2</sub>	C <sub>Ø<sub>2</sub></sub>	-	50	80	

Note: IRQ and NMI require 3K pull-up resistors.

# COMMON CHARACTERISTICS



Note: "REF." means Reference Points on clocks.

## 1 MHz TIMING

CLOCK TIMING - SY6512, 13, 14, 15

CHARACTERISTIC	SYMBOL	MIN.	TYP.	MAX.	UNITS
Cycle Time	$T_{CYC}$	1000	---	---	nsec
Clock Pulse Width (Measured at $V_{CL} = 0.5V$ )	$PWH_{\phi_1}$ $PWH_{\phi_2}$	430 470	---	---	nsec
Fall Time (Measured from 0.2V to 0.8V)	$T_F$	---	---	25	nsec
Delay Time between Clocks (Measured at 0.2V)	$t_D$	0	---	---	nsec

CLOCK TIMING - SY6502, 03, 04, 05, 06

CHARACTERISTIC	SYMBOL	MIN.	TYP.	MAX.	UNITS
Cycle Time	$T_{CYC}$	1000	---	---	ns
$\phi_1$ (IN) Pulse Width (measured at 1.5V)	$PWH_{\phi_1}$	460	---	520	ns
$\phi_2$ (IN) Rise, Fall Time	$TR_{\phi_2}, TF_{\phi_2}$	---	---	10	ns
Delay Time between Clocks (measured at 1.5V)	$t_D$	5	---	---	ns
$\phi_1$ (OUT) Pulse Width (measured at 1.5V)	$PWH_{\phi_1}$	$PWH_{\phi_1} - 20$	---	$PWH_{\phi_1} - 10$	ns
$\phi_2$ (OUT) Pulse Width (measured at 1.5V)	$PWH_{\phi_2}$	$PWH_{\phi_2} - 40$	---	$PWH_{\phi_2} - 10$	ns
$\phi_1$ (OUT), $\phi_2$ (OUT) Rise, Fall Time (measured .AV to 2.0 V) $\pm 1$ TTL	$T_R, T_F$	---	---	25	ns

READ/WRITE TIMING

CHARACTERISTIC	SYMBOL	MIN.	TYP.	MAX.	UNITS
Read/Write Setup Time from SY6500	$T_{RWS}$	---	100	300	ns
Address Setup Time from SY6500	$T_{ADS}$	---	100	300	ns
Memory Read Access Time	$T_{ACC}$	---	---	575	ns
Data Stability Time Period	$T_{DSU}$	100	---	---	ns
Data Hold Time - Read	$T_{HR}$	10	---	---	ns
Data Hold Time - Write	$T_{HW}$	30	60	---	ns
Data Setup Time from SY6500	$T_{PDS}$	---	150	200	ns
RDV, S.O. Setup Time	$T_{SDY}$	100	---	---	ns
SYNC Setup Time from SY6500	$T_{SYNC}$	---	---	350	ns
Address Hold Time	$T_{HA}$	30	60	---	ns
R/W Hold Time	$T_{HRW}$	30	60	---	ns

## 2 MHz TIMING

CLOCK TIMING - SY6512, 13, 14, 15, 16

CHARACTERISTIC	SYMBOL	MIN.	TYP.	MAX.	UNITS
Cycle Time	$T_{CYC}$	500	---	---	nsec
Clock Pulse Width (Measured at $V_{CL} = 0.5V$ )	$PWH_{\phi_1}$ $PWH_{\phi_2}$	215 235	---	---	nsec
Fall Time (Measured from 0.2V to 0.8V)	$T_F$	---	---	12	nsec
Delay Time between Clocks (Measured at 0.2V)	$t_D$	0	---	---	nsec

CLOCK TIMING - SY6502, 03, 04, 05, 06

CHARACTERISTIC	SYMBOL	MIN.	TYP.	MAX.	UNITS
Cycle Time	$T_{CYC}$	500	---	---	ns
$\phi_1$ (IN) Pulse Width (measured at 1.5V)	$PWH_{\phi_1}$	240	---	260	ns
$\phi_2$ (IN) Rise, Fall Time	$TR_{\phi_2}, TF_{\phi_2}$	---	---	10	ns
Delay Time between Clocks (measured at 1.5V)	$t_D$	5	---	---	ns
$\phi_1$ (OUT) Pulse Width (measured at 1.5V)	$PWH_{\phi_1}$	$PWH_{\phi_1} - 20$	---	$PWH_{\phi_1} - 10$	ns
$\phi_2$ (OUT) Pulse Width (measured at 1.5V)	$PWH_{\phi_2}$	$PWH_{\phi_2} - 40$	---	$PWH_{\phi_2} - 10$	ns
$\phi_1$ (OUT), $\phi_2$ (OUT) Rise, Fall Time (measured .AV to 2.0 V) $\pm 1$ TTL	$T_R, T_F$	---	---	25	ns

READ/WRITE TIMING

CHARACTERISTIC	SYMBOL	MIN.	TYP.	MAX.	UNITS
Read/Write Setup Time from SY6500 A	$T_{RWS}$	---	100	150	ns
Address Setup Time from SY6500 A	$T_{ADS}$	---	100	150	ns
Memory Read Access Time	$T_{ACC}$	---	---	300	ns
Data Stability Time Period	$T_{DSU}$	50	---	---	ns
Data Hold Time - Read	$T_{HR}$	10	---	---	ns
Data Hold Time - Write	$T_{HW}$	30	60	---	ns
Data Setup Time from SY6500 A	$T_{PDS}$	---	75	100	ns
RDV, S.O. Setup Time	$T_{SDY}$	50	---	---	ns
SYNC Setup Time from SY6500 A	$T_{SYNC}$	---	---	175	ns
Address Hold Time	$T_{HA}$	30	60	---	ns
R/W Hold Time	$T_{HRW}$	30	60	---	ns

## COMMON CHARACTERISTICS

### Clocks ( $\Phi_1$ , $\Phi_2$ )

The SY650X requires a two phase non-overlapping clock that runs at the Vcc voltage level.

The SY650X clocks are supplied with an internal clock generator. The frequency of these clocks is externally controlled. Details of this feature are discussed in the SY6502 portion of this data sheet.

### Address Bus ( $A_0$ - $A_{15}$ ) (See sections on each micro for respective address lines on those devices.)

These outputs are TTL compatible, capable of driving one standard TTL load and 130pf.

### Data Bus ( $D_0$ - $D_7$ )

Eight pins are used for the data bus. This is a bi-directional bus, transferring data to and from the device and peripherals. The outputs are tri-state buffers capable of driving one standard TTL load and 130pf.

### Data Bus Enable (DBE)

This TTL compatible input allows external control of the tri-state data output buffers and will enable the microprocessor bus driver when in the high state. In normal operation DBE would be driven by the phase two ( $\Phi_2$ ) clock, thus allowing data output from microprocessor only during  $\Phi_2$ . During the read cycle, the data bus drivers are internally disabled, becoming essentially an open circuit. To disable data bus drivers externally, DBE should be held low.

### Ready (RDY)

This input signal allows the user to single cycle the microprocessor on all cycles except write cycles. A negative transition to the low state during or coincident with phase one ( $\Phi_1$ ) will halt the microprocessor with the output address lines reflecting the current address being fetched. This condition will remain through a subsequent phase two ( $\Phi_2$ ) in which the Ready signal is low. This feature allows microprocessor interfacing with low speed PROMs as well as fast (max. 2 cycle) Direct Memory Access (DMA). If Ready is low during a write cycle, it is ignored until the following read operation.

### Interrupt Request ( $\overline{IRQ}$ )

This TTL level input requests that an interrupt sequence begin within the microprocessor. The microprocessor will complete the current instruction being executed before recognizing the request. At that time, the interrupt mask bit in the Status Code Register will be examined. If the interrupt mask flag is not set, the microprocessor will begin an interrupt sequence. The Program Counter and Processor Status Register are stored in the stack. The microprocessor will then set the interrupt mask flag high so that no further interrupts may occur. At the end of this cycle, the program counter low will be loaded from address FFFE, and program counter high from location FFFF, therefore transferring program control to the memory vector located at these addresses. The RDY signal must be in the high state for any interrupt to be recognized. A 3K $\Omega$  external resistor should be used for proper wire-OR operation.

### Non-Maskable Interrupt ( $\overline{NMI}$ )

A negative going edge on this input requests that a non-maskable interrupt sequence be generated within the microprocessor.

$\overline{NMI}$  is an unconditional interrupt. Following completion of the current instruction, the sequence of operations defined for  $\overline{IRQ}$  will be performed, regardless of the state interrupt mask flag. The vector address loaded into the program counter, low and high, are locations FFEA and FFFB respectively, thereby transferring program control to the memory vector located at these addresses. The instructions loaded at these locations cause the microprocessor to branch to a non-maskable interrupt routine in memory.

$\overline{NMI}$  also requires an external 3K $\Omega$  register to Vcc for proper wire-OR operations.

Inputs  $\overline{IRQ}$  and  $\overline{NMI}$  are hardware interrupts lines that are sampled during  $\Phi_2$  (phase 2) and will begin the appropriate interrupt routine on the  $\Phi_1$  (phase 1) following the completion of the current instruction.

### Set Overflow Flag (S.O.)

A NEGATIVE going edge on this input sets the overflow bit in the Status Code Register. This signal is sampled on the trailing edge of  $\Phi_1$ .

### SYNC

This output line is provided to identify those cycles in which the microprocessor is doing an OP CODE fetch. The SYNC line goes high during  $\Phi_1$  of an OP CODE fetch and stays high for the remainder of that cycle. If the RDY line is pulled low during the  $\Phi_1$  clock pulse in which SYNC went high, the processor will stop in its current state and will remain in the state until the RDY line goes high. In this manner, the SYNC signal can be used to control RDY to cause single instruction execution.

### Reset

This input is used to reset or start the microprocessor from a power down condition. During the time that this line is held low, writing to or from the microprocessor is inhibited. When a positive edge is detected on the input, the microprocessor will immediately begin the reset sequence.

After a system initialization time of six clock cycles, the mask interrupt flag will be set and the microprocessor will load the program counter from the memory vector locations FFFC and FFFD. This is the start location for program control.

After Vcc reaches 4.75 volts in a power up routine, reset must be held low for at least two clock cycles. At this time the R/W and (SYNC) signal will become valid.

When the reset signal goes high following these two clock cycles, the microprocessor will proceed with the normal reset procedure detailed above.

## COMMON CHARACTERISTICS

### INSTRUCTION SET – ALPHABETIC SEQUENCE

ADC Add Memory to Accumulator with Carry	DEC Decrement Memory by One	PHA Push Accumulator on Stack
AND "AND" Memory with Accumulator	DEX Decrement Index X by One	PHP Push Processor Status on Stack
ASL Shift left One Bit (Memory or Accumulator)	DEY Decrement Index Y by One	PLA Pull Accumulator from Stack
		PLP Pull Processor Status from Stack
BCR Branch on Carry Clear	EOR "Exclusive-or" Memory with Accumulator	
BCS Branch on Carry Set		ROL Rotate One Bit Left (Memory or Accumulator)
BEQ Branch on Result Zero	INC Increment Memory by One	ROR Rotate One Bit Right (Memory or Accumulator)
BIT Test Bits in Memory with Accumulator	INX Increment Index X by One	RTI Return from Interrupt
BMI Branch on Result Minus	INY Increment Index Y by One	RTS Return from Subroutine
BNE Branch on Result not Zero		
BPL Branch on Result Plus	JMP Jump to New Location	SBC Subtract Memory from Accumulator with Borrow
BRK Force Break	JSR Jump to New Location Saving Return Address	SEC Set Carry Flag
BVC Branch on Overflow Clear		SED Set Decimal Mode
BVS Branch on Overflow Set	LDA Load Accumulator with Memory	SEI Set Interrupt Disable Status
	LDX Load Index X with Memory	STA Store Accumulator in Memory
CLC Clear Carry Flag	LDY Load Index Y with Memory	STX Store Index X in Memory
CLED Clear Decimal Mode	LSR Shift One Bit Right (Memory or Accumulator)	STY Store Index Y in Memory
CLI Clear Interrupt Disable Bit		
CLV Clear Overflow Flag	NOP No Operation	TAX Transfer Accumulator to Index X
CMP Compare Memory and Accumulator	ORA "OR" Memory with Accumulator	TAY Transfer Accumulator to Index Y
CPX Compare Memory and Index X		TSX Transfer Stack Pointer to Index X
CPY Compare Memory and Index Y		TXA Transfer Index X to Accumulator
		TXS Transfer Index Y to Stack Pointer
		TYA Transfer Index Y to Accumulator

### ADDRESSING MODES

**ACCUMULATOR ADDRESSING** - This form of addressing is represented with a one byte instruction, implying an operation on the accumulator.

**IMMEDIATE ADDRESSING** - In immediate addressing, the operand is contained in the second byte of the instruction, with no further memory addressing required.

**ABSOLUTE ADDRESSING** - In absolute addressing, the second byte of the instruction specifies the eight low order bits of the effective address while the third byte specifies the eight high order bits. Thus, the absolute addressing mode allows access to the entire 65K bytes of addressable memory.

**ZERO PAGE ADDRESSING** - The zero page instructions allow for shorter code and execution times by only fetching the second byte of the instruction and assuming a zero high address byte. Careful use of the zero page can result in significant increase in code efficiency.

**INDEXED ZERO PAGE ADDRESSING** - (X, Y indexing) - This form of addressing is used in conjunction with the index register and is referred to as "Zero Page, X" or "Zero Page, Y". The effective address is calculated by adding the second byte to the contents of the index register. Since this is a form of "Zero Page" addressing, the content of the second byte references a location in page zero. Additionally due to the "Zero Page" addressing nature of this mode, no carry is added to the high order 8 bits of memory and crossing of page boundaries does not occur.

**INDEXED ABSOLUTE ADDRESSING** - (X, Y indexing) - This form of addressing is used in conjunction with X and Y index register and is referred to as "Absolute, X", and "Absolute, Y". The effective address is formed by adding the contents of X or Y to the address contained in the second and third bytes of the instruction. This mode allows the index register to contain the index or count value and the instruction to contain the base address. This type of indexing allows any location referencing and the index to modify multiple fields resulting in reduced coding and execution time.

**IMPLIED ADDRESSING** - In the implied addressing mode, the address containing the operand is implicitly stated in the operation code of the instruction.

**RELATIVE ADDRESSING** - Relative addressing is used only with branch instructions and establishes a destination for the conditional branch.

The second byte of the instruction becomes the operand which is an "Offset" added to the contents of the lower eight bits of the program counter when the counter is set at the next instruction. The range of the offset is -128 to +127 bytes from the next instruction.

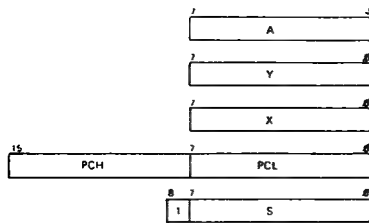
**INDEXED INDIRECT ADDRESSING** - In indexed indirect addressing (referred to as (Indirect,X)), the second byte of the instruction is added to the contents of the X index register, discarding the carry. The result of this addition points to a memory location on page zero whose contents is the low order eight bits of the effective address. The next memory location in page zero contains the high order eight bits of the effective address. Both memory locations specifying the high and low order bytes of the effective address must be in page zero.

**INDIRECT INDEXED ADDRESSING** - In indirect indexed addressing (referred to as (Indirect),Y), the second byte of the instruction points to a memory location in page zero. The contents of this memory location is added to the contents of the Y index register, the result being the low order eight bits of the effective address. The carry from this addition is added to the contents of the next page zero memory location, the result being the high order eight bits of the effective address.

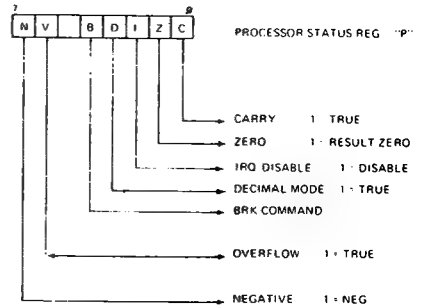
**ABSOLUTE INDIRECT** - The second byte of the instruction contains the low order eight bits of a memory location. The high order eight bits of that memory location is contained in the third byte of the instruction. The contents of the fully specified memory location is the low order byte of the effective address. The next memory location contains the high order byte of the effective address which is loaded into the sixteen bits of the program counter.

# COMMON CHARACTERISTICS

## PROGRAMMING MODEL



ACCUMULATOR A  
INDEX REGISTER Y  
INDEX REGISTER X  
PROGRAM COUNTER "PC"  
STACK POINTER "S"



## INSTRUCTION SET – OP CODES, Execution Time, Memory Requirements

INSTRUCTIONS	IMMEDIATE	ABSOLUTE	ZERO PAGE	ACCUM.	IMPLICIT	(IND. X)	(IND. Y)	Z-PAGE X	ABS. X	ABS. Y	RELATIVE	INDIRECT	Z-PAGE Y	CONDITION CODES
HEX/DEC	OP N	OP N	OP N	OP N	OP N	OP N	OP N	OP N	OP N	OP N	OP N	OP N	OP N	N Z C I O V
ADC	A ← M ← A	65 2 2	8D 4 3	85 3 2			81 6 2	71 5 2	75 4 2	7D 4 3				1 1 1 1 1
AND	A ← M ← A	7B 2 2	7D 4 3	75 3 2			71 6 2	61 5 2	65 4 2	7D 4 3				1 1 1 1 1
ASL	A ← A ← 1	9E 6 3	96 5 2	8A 2 1					45 6 2	1E 7 3				1 1 1 1 1
BCC	BRANCH ON C = 0										90 2 2			1 1 1 1 1
BCS	BRANCH ON C = 1										80 2 2			1 1 1 1 1
BEQ	BRANCH ON Z = 1											FB 2 2		1 1 1 1 1
BIT	A ← M		2C 4 3	24 3 2										1 1 1 1 1
BMI	BRANCH ON M = 1										3B 2 2			1 1 1 1 1
BNE	BRANCH ON Z = 0										0B 2 2			1 1 1 1 1
BPL	BRANCH ON M = 0										1B 2 2			1 1 1 1 1
BRK	(See Fig. 1)						80 2 1							1 1 1 1 1
BVC	BRANCH ON V = 0										5B 2 2			1 1 1 1 1
BVS	BRANCH ON V = 1										7B 2 2			1 1 1 1 1
CLC	0 ← C						1B 2 1							1 1 1 1 1
CLD	0 ← D						0B 2 1							1 1 1 1 1
CLI	0 ← I						5B 2 1							1 1 1 1 1
CLV	0 ← V						8B 2 1							1 1 1 1 1
CMP	A ← M	1B 2 2	CD 4 3	C5 3 2			C1 6 2	D1 5 2	05 4 2	0D 4 3				1 1 1 1 1
CPX	X ← M	8B 2 2	EC 4 3	E4 3 2										1 1 1 1 1
CPY	Y ← M	CB 2 2	CC 4 3	CA 3 2										1 1 1 1 1
DEC	M ← M		CF 6 3	C6 5 2					06 6 2	0F 7 3				1 1 1 1 1
DEX	X ← X - 1						CA 2 1							1 1 1 1 1
DEY	Y ← Y - 1						BA 2 1							1 1 1 1 1
EOR	A ← M ← A	1B 2 2	4D 4 3	45 3 2			41 6 2	51 5 2	55 4 2	5D 4 3				1 1 1 1 1
INC	M ← M + 1		EE 6 3	E6 5 2					FE 6 2	FE 7 3				1 1 1 1 1
INX	X ← X + 1						EB 2 1							1 1 1 1 1
INY	Y ← Y + 1						CB 2 1							1 1 1 1 1
JMP	JUMP TO NEW LOC.		4C 3 3									BC 5 3		1 1 1 1 1
JSR	(See Fig. 2) JUMP SUB		2B 6 3											1 1 1 1 1
LDA	M ← A	1B 2 2	AD 4 3	A5 3 2			A1 6 2	B1 5 2	85 4 2	BD 4 3				1 1 1 1 1

INSTRUCTIONS	IMMEDIATE	ABSOLUTE	ZERO PAGE	ACCUM.	IMPLICIT	(IND. X)	(IND. Y)	Z-PAGE X	ABS. X	ABS. Y	RELATIVE	INDIRECT	Z-PAGE Y	CONDITION CODES
HEX/DEC	OP N	OP N	OP N	OP N	OP N	OP N	OP N	OP N	OP N	OP N	OP N	OP N	OP N	N Z C I O V
LDX	M ← X	A2 2 2	AE 4 3	AE 3 2									BE 4 3	1 1 1 1 1
LDY	M ← Y	AB 2 2	AC 4 3	AC 3 2										1 1 1 1 1
LSR	A ← A ← 1		9E 6 3	96 5 2	8A 2 1				45 6 2	1E 7 3				1 1 1 1 1
NOP	NO OPERATION													1 1 1 1 1
ORA	A ← M ← A	9B 2 2	BD 4 3	B5 3 2			91 6 2	11 5 2	15 4 2	1D 4 3				1 1 1 1 1
PHA	A ← M ← A						4B 3 1							1 1 1 1 1
PHP	P ← M ← P						5B 3 1							1 1 1 1 1
PLA	M ← A ← 1						6B 4 3							1 1 1 1 1
PLP	M ← P ← 1						7B 4 3							1 1 1 1 1
ROL	A ← A ← 1		2E 6 3	26 5 2	2A 2 1				35 6 2	3E 7 3				1 1 1 1 1
ROR	A ← A ← 1		6E 6 3	66 5 2	6A 2 1				75 6 2	7E 7 3				1 1 1 1 1
RTI	(See Fig. 1) RETURN INT.						8B 6 3							1 1 1 1 1
RTS	(See Fig. 2) RETURN SUB.						9B 6 3							1 1 1 1 1
SBC	A ← M ← A	1B 2 2	ED 4 3	E5 3 2			E1 6 2	F1 5 2	F5 4 2	FD 4 3				1 1 1 1 1
SEC	1 ← C						3B 2 1							1 1 1 1 1
SED	1 ← D						FB 2 1							1 1 1 1 1
SEI	1 ← I						7B 2 1							1 1 1 1 1
STA	A ← M		BD 4 3	B5 3 2			B1 6 2	C1 5 2	C5 4 2	C9 4 3				1 1 1 1 1
STX	X ← M		BE 4 3	BE 3 2										1 1 1 1 1
STY	Y ← M		BC 4 3	BC 3 2										1 1 1 1 1
TAX	A ← X						AB 2 1							1 1 1 1 1
TAY	A ← Y						BB 2 1							1 1 1 1 1
TSX	S ← X						BA 2 1							1 1 1 1 1
TXA	X ← A						BB 2 1							1 1 1 1 1
TXS	X ← S						BA 2 1							1 1 1 1 1
TYA	Y ← A						BB 2 1							1 1 1 1 1

(1) ADD 1 TO N IF PAGE BOUNDARY IS CROSSED

(2) ADD 1 TO N IF BRANCH OCCURS TO SAME PAGE

(3) ADD 2 TO N IF BRANCH OCCURS TO DIFFERENT PAGE

(4) CARRY NOT BORROW

(5) IF IN DECIMAL MODE Z FLAG IS INVALID

ACCUMULATOR MUST BE CHECKED FOR ZERO RESULT

X: INDEX REGISTER

Y: INDEX REGISTER

A: ACCUMULATOR

M: MEMORY (FROM ADDRESS TO ADDRESS)

N: MEMORY (FROM ADDRESS TO ADDRESS)

N: MEMORY (FROM ADDRESS TO ADDRESS)

N: NO CYCLES

N: NO BYTES

N: NO BYTES

N: NO BYTES

N: NO BYTES

N: NO BYTES



### SY6502 – 40 Pin Package

V <sub>ss</sub>	1	40	RES
RDY	2	39	$\overline{\theta_2}$ (OUT)
$\overline{\theta_1}$ (OUT)	3	38	S.O.
IRQ	4	37	$\overline{\theta_0}$ (IN)
N.C.	5	36	N.C.
NMI	6	35	N.C.
SYNC	7	34	R/W
V <sub>cc</sub>	8	33	DB0
AB0	9	32	DB1
AB1	10	31	DB2
AB2	11	30	DB3
AB3	12	29	DB4
AB4	13	28	DB5
AB5	14	27	DB6
AB6	15	26	DB7
AB7	16	25	AB15
AB8	17	24	AB14
AB9	18	23	AB13
AB10	19	22	AB12
AB11	20	21	V <sub>ss</sub>

SY6502

- \* 65K Addressable Bytes of Memory
- \*  $\overline{\text{IRQ}}$  Interrupt      \*  $\overline{\text{NMI}}$  Interrupt
- \* On-the-chip Clock
  - ✓ TTL Level Single Phase Input
  - ✓ RC Time Base Input
  - ✓ Crystal Time Base Input
- \* SYNC Signal  
(can be used for single instruction execution)
- \* RDY Signal  
(can be used for single cycle execution)
- \* Two Phase Output Clock for Timing of Support Chips

Features of SY6502

### SY6503 – 28 Pin Package

RES	1	28	$\overline{\theta_2}$ (OUT)
V <sub>ss</sub>	2	27	$\overline{\theta_0}$ (IN)
IRQ	3	26	R/W
NMI	4	25	DB0
V <sub>cc</sub>	5	24	DB1
AB0	6	23	DB2
AB1	7	22	DB3
AB2	8	21	DB4
AB3	9	20	DB5
AB4	10	19	DB6
AB5	11	18	DB7
AB6	12	17	AB11
AB7	13	16	AB10
AB8	14	15	AB9

SY6503

- \* 4K Addressable Bytes of Memory (AB00-AB11)
- \* On-the-chip Clock
- \*  $\overline{\text{IRQ}}$  Interrupt
- \*  $\overline{\text{NMI}}$  Interrupt
- \* 8 Bit Bi-Directional Data Bus

Features of SY6503

### SY6504 – 28 Pin Package

RES	1	28	$\overline{\theta_2}$ (OUT)
V <sub>ss</sub>	2	27	$\overline{\theta_0}$ (IN)
IRQ	3	26	R/W
V <sub>cc</sub>	4	25	DB0
AB0	5	24	DB1
AB1	6	23	DB2
AB2	7	22	DB3
AB3	8	21	DB4
AB4	9	20	DB5
AB5	10	19	DB6
AB6	11	18	DB7
AB7	12	17	AB12
AB8	13	16	AB11
AB9	14	15	AB10

SY6504

- \* 8K Addressable Bytes of Memory (AB00-AB12)
- \* On-the-chip Clock
- \*  $\overline{\text{IRQ}}$  Interrupt
- \* 8 Bit Bi-Directional Data Bus

Features of SY6504

### SY6505 – 28 Pin Package

RES	1	28	$\phi_2$ (OUT)
Vss	2	27	$\phi_0$ (IN)
RDY	3	26	R/W
$\overline{\text{IRQ}}$	4	25	DB0
Vcc	5	24	DB1
AB0	6	23	DB2
AB1	7	22	DB3
AB2	8	21	DB4
AB3	9	20	DB5
AB4	10	19	DB6
AB5	11	18	DB7
AB6	12	17	AB11
AB7	13	16	AB10
AB8	14	15	AB9

SY6505

- \* 4K Addressable Bytes of Memory (AB00-AB11)
- \* On-the-chip Clock
- \*  $\overline{\text{IRQ}}$  Interrupt
- \* RDY Signal
- \* 8 Bit Bi-Directional Data Bus

Features of SY6505

### SY6506 – 28 Pin Package

RES	1	28	$\phi_2$ (OUT)
Vss	2	27	$\phi_0$ (IN)
$\phi_1$ (OUT)	3	26	R/W
$\overline{\text{IRQ}}$	4	25	DB0
Vcc	5	24	DB1
AB0	6	23	DB2
AB1	7	22	DB3
AB2	8	21	DB4
AB3	9	20	DB5
AB4	10	19	DB6
AB5	11	18	DB7
AB6	12	17	AB11
AB7	13	16	AB10
AB8	14	15	AB9

SY6506

- \* 4K Addressable Bytes of Memory (AB00-AB11)
- \* On-the-chip Clock
- \*  $\overline{\text{IRQ}}$  Interrupt
- \* Two phases off
- \* 8 Bit Bi-Directional Data Bus

Features of SY6506

### SY6512 – 40 Pin Package

Vss	1	40	RES
RDY	2	39	$\phi_2$ (OUT)
$\phi_1$	3	38	S.O.
$\overline{\text{IRQ}}$	4	37	$\phi_2$
Vcc	5	36	DBE
NMI	6	35	N.C.
SYNC	7	34	R/W
Vcc	8	33	DB0
AB0	9	32	DB1
AB1	10	31	DB2
AB2	11	30	DB3
AB3	12	29	DB4
AB4	13	28	DB5
AB5	14	27	DB6
AB6	15	26	DB7
AB7	16	25	AB15
AB8	17	24	AB14
AB9	18	23	AB13
AB10	19	22	AB12
AB11	20	21	Vss

SY6512

- \* 65K Addressable Bytes of Memory
- \*  $\overline{\text{IRQ}}$  Interrupt
- \* NMI Interrupt
- \* RDY Signal
- \* 8 Bit Bi-Directional Data Bus
- \* SYNC Signal
- \* Two phase input
- \* Data Bus Enable

Features of SY6512

### SY6513 – 28 Pin Package

Vss	1	28	RES
$\phi_1$	2	27	$\phi_2$
IRQ	3	26	R/W
NMI	4	25	DB0
Vcc	5	24	DB1
AB0	6	23	DB2
AB1	7	22	DB3
AB2	8	21	DB4
AB3	9	20	DB5
AB4	10	19	DB6
AB5	11	18	DB7
AB6	12	17	AB11
AB7	13	16	AB10
AB8	14	15	AB9

SY6513

- \* 4K Addressable Bytes of Memory (AB00-AB11)
- \* Two phase clock input
- \*  $\overline{\text{IRQ}}$  Interrupt
- \*  $\overline{\text{NMI}}$  Interrupt
- \* 8 Bit Bi-Directional Data Bus

Features of SY6513

### SY6514 – 28 Pin Package

Vss	1	28	RES
$\phi_1$	2	27	$\phi_2$
IRQ	3	26	R/W
Vcc	4	25	DB0
AB0	5	24	DB1
AB1	6	23	DB2
AB2	7	22	DB3
AB3	8	21	DB4
AB4	9	20	DB5
AB5	10	19	DB6
AB6	11	18	DB7
AB7	12	17	AB12
AB8	13	16	AB11
AB9	14	15	AB10

SY6514

- \* 8K Addressable Bytes of Memory (AB00-AB12)
- \* Two phase clock input
- \*  $\overline{\text{IRQ}}$  Interrupt
- \* 8 Bit Bi-Directional Data Bus

Features of SY6514

### SY6515 – 28 Pin Package

Vss	1	28	RES
RDY	2	27	$\phi_2$
$\phi_1$	3	26	R/W
IRQ	4	25	DB0
Vcc	5	24	DB1
AB0	6	23	DB2
AB1	7	22	DB3
AB2	8	21	DB4
AB3	9	20	DB5
AB4	10	19	DB6
AB5	11	18	DB7
AB6	12	17	AB11
AB7	13	16	AB10
AB8	14	15	AB9

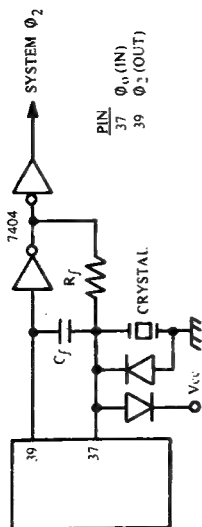
SY6515

- \* 4K Addressable Bytes of Memory (AB00-AB11)
- \* Two phase clock input
- \*  $\overline{\text{IRQ}}$  Interrupt
- \* 8 Bit Bi-Directional Data Bus

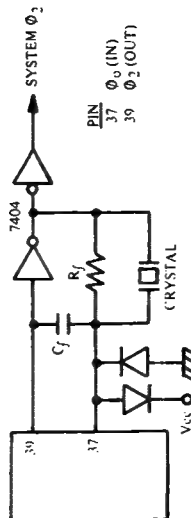
Features of SY6515

# TIME BASE GENERATION OF INPUT CLOCK

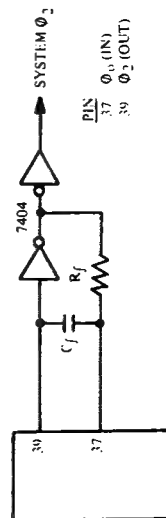
**SY6502**



**SY6502 Parallel Mode Crystal Controlled Oscillator**

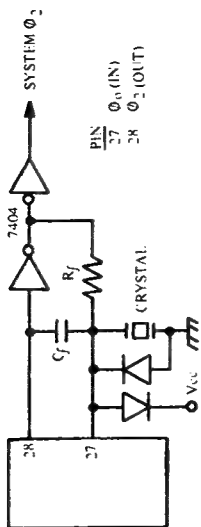


**SY6502 Series Mode Crystal Controlled Oscillator**

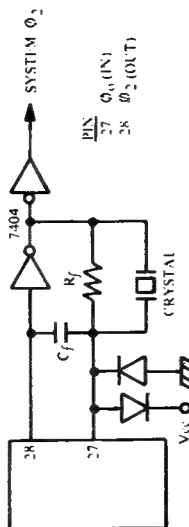


**SY6502 Time Base Generator - RC Network**

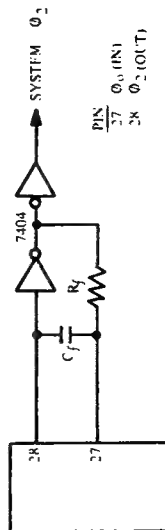
**SY6503, SY6504, SY6505, SY6506**



**SY6503,4,5,6 Parallel Mode Crystal Controlled Oscillator**



**SY6503,4,5,6 Series Mode Crystal Controlled Oscillator**



**SY6503,4,5,6 Time Base Generation RC Network**

**APPENDIX H**  
**SY6522 DATA SHEET**



# Synertek®



3050 Coronado Drive, Santa Clara, CA. 95051  
(408) 984-8900 TWX 910-338-0135

## SY6522

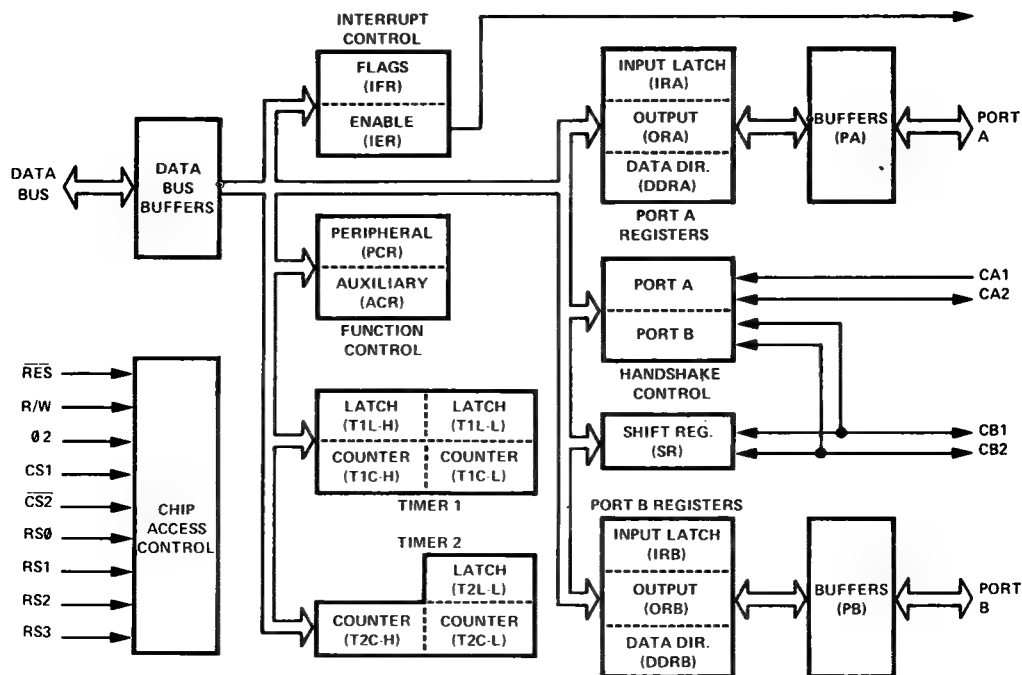
### SY6522 (VERSATILE INTERFACE ADAPTER)

The SY6522 Versatile Interface Adapter (VIA) provides all of the capability of the SY6520. In addition, this device contains a pair of very powerful interval timers, a serial-to-parallel/parallel-to-serial shift register and input data latching on the peripheral ports. Expanded handshaking capability allows control of bi-directional data transfers between VIA's in multiple processor systems.

Control of peripheral devices is handled primarily through two 8-bit bi-directional ports. Each of these lines can be programmed to act as either an input or an output. Also, several peripheral I/O lines can be controlled directly from the interval timers for generating programmable frequency square waves and for counting externally generated pulses. To facilitate control of the many powerful features of this chip, the internal registers have been organized into an interrupt flag register, an interrupt enable register and a pair of function control registers.

- Very powerful expansion of basic SY6520 capability.
- N channel, depletion load technology, single +5V Supply.
- Completely static and TTL compatible.
- CMOS compatible peripheral control lines.
- Expanded "handshake" capability allows very positive control of data transfers between processor and peripheral devices.

**Figure 1. SY6522 BLOCK DIAGRAM**



## MAXIMUM RATINGS

	Symbol	Value	Unit
Supply Voltage	V <sub>CC</sub>	-0.3 to +7.0	Vdc
Input Voltage	V <sub>IN</sub>	-0.3 to +7.0	Vdc
Operating Temperature Range	T <sub>A</sub>	0 to +70	°C
Storage Temperature Range	T <sub>stg</sub>	-55 to +150	°C

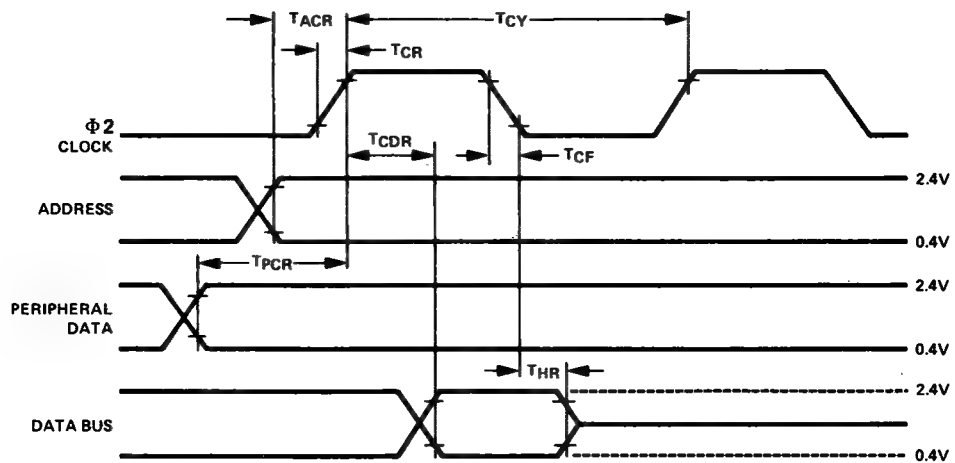
This device contains circuitry to protect the inputs against damage due to high static voltages. However, it is advised that normal precautions be taken to avoid application of any voltage higher than maximum rated voltages.

### Electrical Characteristics (V<sub>CC</sub> = 5.0V ±5%, V<sub>SS</sub> = 0, T<sub>A</sub> = 0°C to 70°C unless otherwise noted)

CHARACTERISTIC	SYMBOL	MIN	TYP	MAX	UNIT
Input high voltage (normal operation)	V <sub>IH</sub>	+2.4	—	V <sub>CC</sub>	Vdc
Input Low Voltage (normal operation)	V <sub>IL</sub>	-0.3	—	+0.4	Vdc
Input Leakage current - V <sub>IN</sub> = 0 to 5 Vdc R/W, $\overline{\text{RES}}$ , RS0, RS1, RS2, RS3, CS1, $\overline{\text{CS2}}$ , CA1, $\Phi$ 2	I <sub>IN</sub>	—	±1.0	±2.5	μAdc
Off-state input current - V <sub>IN</sub> = .4 to 2.4 V V <sub>CC</sub> = Max, D0 to D7	I <sub>TSI</sub>	—	±2.0	±10	μAdc
Input high current - V <sub>IH</sub> = 2.4 V PA0 - PA7, CA2, PB0 - PB7, CB1, CB2	I <sub>IH</sub>	-100	-250	—	μAdc
Input low current - V <sub>IL</sub> = 0.4 Vdc PA0 - PA7, CA2, PB0 - PB7, CB1, CB2	I <sub>IL</sub>	—	-1.0	-1.6	mAdc
Output high voltage V <sub>CC</sub> = min, I <sub>load</sub> = -100 μAdc PA0 - PA7, CA2, PB0 - PB7, CB1, CB2	V <sub>OH</sub>	2.4	—	—	Vdc
Output low voltage V <sub>CC</sub> = min, I <sub>load</sub> = 1.6 mAdc	V <sub>OL</sub>	—	—	+0.4	Vdc
Output high current (sourcing) V <sub>OH</sub> = 2.4 V V <sub>OH</sub> = 1.5 V, PB0 - PB7, CB1, CB2	I <sub>OH</sub>	-100 -3.0	-1000 -5.0	— —	μAdc mAdc
Output low current (sinking) V <sub>OL</sub> = 0.4 Vdc	I <sub>OL</sub>	1.6	—	—	mAdc
Output leakage current (off state) IRQ	I <sub>off</sub>	—	1.0	10	μAdc
Input capacitance - T <sub>A</sub> = 25°C, f = 1 Mhz R/W, $\overline{\text{RES}}$ , RS0, RS1, RS2, RS3, CS1, $\overline{\text{CS2}}$ DO - D7, PA0 - PA7, CA1, CA2, PB0 - PB7, CB1, CB2 $\Phi$ 2 input	C <sub>in</sub>	— — —	— — —	7.0 10 20	pF pF pF
Output capacitance - T <sub>A</sub> = 25°C, f = 1 Mhz	C <sub>out</sub>	—	—	10	pF
Power dissipation	P <sub>d</sub>	—	—	1000	MW



**Figure 2. READ TIMING CHARACTERISTICS**



## DYNAMIC CHARACTERISTICS

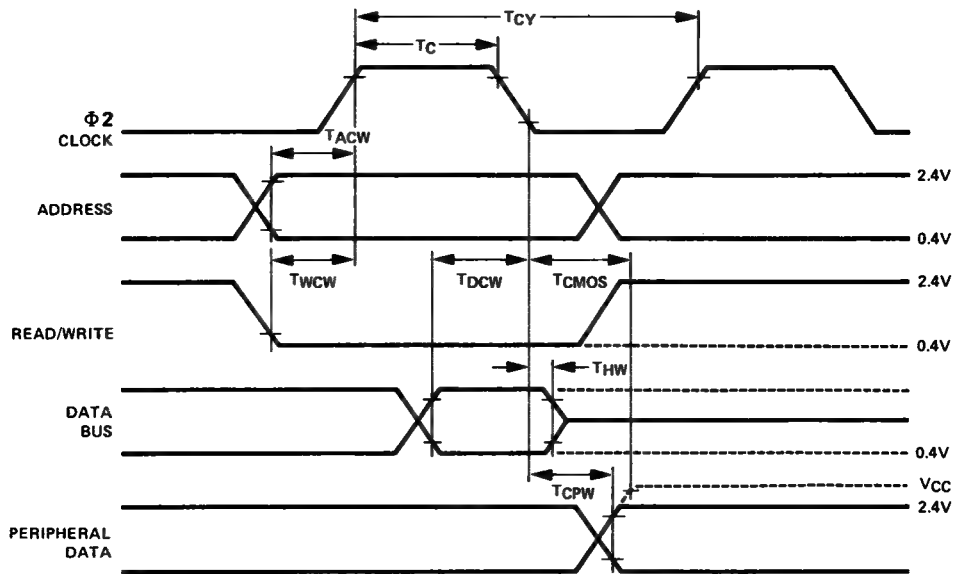
Read Timing Characteristics (Figure 2, loading 130 pF and one TTL load)

Characteristic	Symbol	Min	Typ	Max	Unit
Cycle time	$T_{CY}$	1	—	50	$\mu s$
Delay time, address valid to clock positive transition	$T_{ACR}$	180	—	—	nS
Delay time, clock positive transition to data valid on bus	$T_{CDR}$	—	—	395	nS
Peripheral data setup time	$T_{PCR}$	300	—	—	nS
Data bus hold time	$T_{HR}$	10	—	—	nS
Rise and fall time for clock input	$T_{CR}$ $T_{CF}$	—	—	25	nS

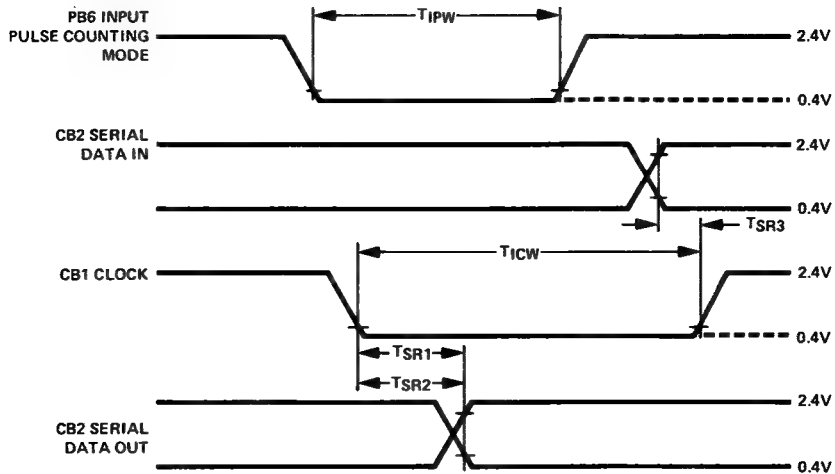
## Write Timing Characteristics (Figure 3)

Characteristic	Symbol	Min	Typ	Max	Unit
Cycle Time	$T_{CY}$	1	—	50	$\mu S$
Enable pulse width	$T_C$	0.47	—	25	$\mu S$
Delay time, address valid to clock positive transition	$T_{ACW}$	180	—	—	nS
Delay time, data valid to clock negative transition	$T_{DCW}$	300	—	—	nS
Delay time, read/write negative transition to clock positive transition	$T_{WCW}$	180	—	—	nS
Data bus hold time	$T_{HW}$	10	—	—	nS
Delay time, Enable negative transition to peripheral data valid	$T_{CPW}$	—	—	1.0	$\mu S$
Delay time, clock negative transition to peripheral data valid CMOS ( $V_{CC} - 30\%$ )	$T_{CMOS}$	—	—	2.0	$\mu S$

**Figure 3. WRITE TIMING CHARACTERISTICS**



**Figure 4. I/O TIMING CHARACTERISTICS**



**PERIPHERAL INTERFACE CHARACTERISTICS**

Characteristic	Symbol	Min	Typ	Max	Unit
Rise and fall time for CA1, CB1, CA2, and CB2 input signals.	T <sub>RF</sub>	—	—	1.0	μS
Delay time, clock negative transition to CA2 negative transition (read handshake or pulse mode).	T <sub>CA2</sub>	—	—	1.0	μS
Delay time, clock negative transition to CA2 positive transition (pulse mode).	T <sub>RS1</sub>	—	—	1.0	μS
Delay time, CA1 active transition to CA2 positive transition (handshake mode).	T <sub>RS2</sub>	—	—	2.0	μS
Delay time, clock positive transition to CA2 or CB2 negative transition (write handshake).	T <sub>WHS</sub>	—	—	1.0	μS
Delay time, peripheral data valid to CB2 negative transition.	T <sub>DC</sub>	0	—	1.5	μS
Delay time, clock positive transition to CA2 or CB2 positive transition (pulse mode).	T <sub>RS3</sub>	—	—	1.0	μS
Delay time, CB1 active transition to CA2 or CB2 positive transition (handshake mode).	T <sub>RS4</sub>	—	—	2.0	μS
Delay time, peripheral data valid to CA1 or CB1 active transition (input latching).	T <sub>IL</sub>	300	—	—	nS
Delay time, CB1 negative transition to CB2 data valid (internal SR clock, shift out).	T <sub>SR1</sub>	—	—	300	nS
Delay time, negative transition of CB1 input clock to CB2 data valid (external clock, shift out).	T <sub>SR2</sub>	—	—	300	nS
Delay time, CB2 data valid to positive transition of CB1 clock (shift in, internal or external clock)	T <sub>SR3</sub>	—	—	300	nS
Pulse Width - PB6 Input Pulse	T <sub>IPW</sub>	2	—	—	μS
Pulse Width - CB1 Input Clock	T <sub>ICW</sub>	2	—	—	μS
Pulse Spacing - PB6 Input Pulse	I <sub>IPS</sub>	2	—	—	μS
Pulse Spacing - CB1 Input Pulse	I <sub>ICS</sub>	2	—	—	μS

## PROCESSOR INTERFACE

This section contains a description of the buses and control lines which are used to interface the SY6522 to the system processor. Electrical parameters associated with this interface are specified elsewhere in this document.

### 1. Phase Two Clock ( $\Phi 2$ )

Data transfers between the SY6522 and the system processor take place only while the Phase Two Clock is high. In addition,  $\Phi 2$  acts as the time base for the various timers, shift registers, etc. on the chip.

### 2. Chip Select Lines ( $CS1$ , $\overline{CS2}$ )

The two chip select inputs are normally connected to processor address lines either directly or through decoding. The selected SY6522 register will be accessed when  $CS1$  is high and  $\overline{CS2}$  is low.

### 3. Register Select Lines ( $RS0$ , $RS1$ , $RS2$ , $RS3$ )

The four Register select lines are normally connected to the processor address bus lines to allow the processor to select the internal SY6522 register which is to be accessed. The sixteen possible combinations access the registers as follows:

RS3	RS2	RS1	RS0	REGISTER	REMARKS
L	L	L	L	ORB, IRB	
L	L	L	H	ORA, IRA	Controls Handshake
L	L	H	L	DDRB	
L	L	H	H	DDRA	
L	H	L	L	T1L-L	Write Latch Read Counter
L	H	L	H	T1C-H	Trigger T1L-L/ T1C-L Transfer
L	H	H	L	T1L-L	
L	H	H	H	T1L-H	
H	L	L	L	T2L-L T2C-L	Write Latch Read Counter
H	L	L	H	T2C-H	Triggers T2L-L/ T2C-L Transfer
H	L	H	L	SR	
H	L	H	H	ACR	
H	H	L	L	PCR	
H	H	L	H	IFR	
H	H	H	L	IER	
H	H	H	H	ORA	No Effect on Handshake

NOTE: L  $\leq$  0.4V  
H  $\geq$  2.4V

### 4. Read/Write Line (R/W)

The direction of the data transfers between the SY6522 and the system processor is controlled by the R/W line. If R/W is low, data will be transferred out of the processor into the selected SY6522 register (write operation). If R/W is high and the chip is selected, data will be transferred out of the SY6522 (read operation).

### 5. Data Bus (DB0 - DB7)

The 8 bi-directional data bus lines are used to transfer data between the SY6522 and the system processor. The internal drivers will remain in the high-impedance state except when the chip is selected ( $CS1=HI$ ,  $CS2=LO$ ), Read/Write is high and the Phase Two Clock is high. At this time, the contents of the selected register are placed on the data bus. When the chip is selected, with Read/Write low and  $\Phi 2 = 1$ , the data on the data bus will be transferred into the selected SY6522 register.

## 6. Reset ( $\overline{RES}$ )

The reset input clears all internal registers to logic 0 (except T1, T2 and SR). This places all peripheral interface lines in the input state, disables the timers, shift register, etc. and disables interrupting from the chip.

## 7. Interrupt Request ( $\overline{IRQ}$ )

The Interrupt Request output goes low whenever an internal interrupt flag is set and the corresponding interrupt enable bit is a logic 1. This output is "open-drain" to allow the interrupt request signal to be "wire-or'd" with other equivalent signals in the system.

## PERIPHERAL INTERFACE

This section contains a brief description of the buses and control lines which are used to drive peripheral devices under control of the internal SY6522 registers.

### 1. Peripheral A Port (PA0 - PA7)

The Peripheral A port consists of 8 lines which can be individually programmed to act as an input or an output under control of a Data Direction Register. The polarity of output pins is controlled by an output Register and input data can be latched into an internal register under control of the CA1 line. All of its modes of operation are controlled by the system processor through the internal control registers. These lines represent one standard TTL load in the input mode and will drive one standard TTL load in the output mode.

### 2. Peripheral A Control Lines (CA1, CA2)

The two peripheral A control lines act as interrupt inputs or as handshake outputs. Each line controls an internal interrupt flag with a corresponding interrupt enable bit. In addition, CA1 controls the latching of data on Peripheral A Port Input lines. The various modes of operation are controlled by the system processor through the internal control registers. CA1 is a high-impedance input only while CA2 represents one standard TTL load in the input mode. CA2 will drive one standard TTL load in the output mode.

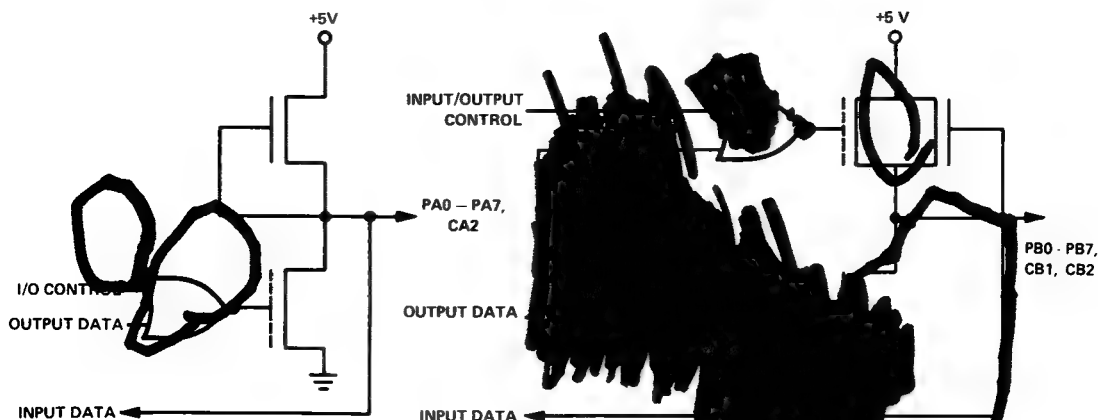
### 3. Peripheral B Port (PB0 - PB7)

The Peripheral B Port consists of 8 bi-directional lines which are controlled by an output register and a data direction register in much the same manner as the PA port. In addition, the polarity of the PB7 output signal can be controlled by one of the interval timers while the second timer can be programmed to count pulses on the PB6 pin. These lines represent one standard TTL load in the input mode and will drive one standard TTL load in the output mode. In addition, they are capable of sourcing 3.0 ma at 1.5 VDC in the output mode to allow the outputs to directly drive Darlington transistor switches.

### 4. Peripheral B Control Lines (CB1, CB2)

The Peripheral B control lines act as interrupt inputs or as handshake outputs. As with CA1 and CA2, each line controls an interrupt flag with a corresponding interrupt enable bit. In addition, these lines act as a serial port under control of the Shift Register. These lines represent one standard TTL load in the input mode and will drive one standard TTL load in the output mode. In addition, they are capable of sourcing 3.0 ma at 1.5 VDC in the output mode to allow the outputs to directly drive Darlington transistor switches.

Figure 5. PERIPHERAL DATA OUTPUT BUFFERS



## SY6522 OPERATION

This section contains a discussion of the various blocks of logic shown in Figure 1. In addition, the internal operation of the SY6522 is described in detail.

### A. Data Buses (DB), Peripheral A Buffers (PA), Peripheral B Buffers (PB)

The characteristics of the buffers which provide the required voltage and current drive capability were discussed in the previous section. Electrical parameters for these buffers are specified elsewhere in this document.

### Chip Access Control

The Chip Access Control contains the necessary logic to detect the chip select condition and to decode the Register Select inputs to allow accessing the desired internal registers. In addition, the R/W and  $\Phi 2$  signals are utilized to control the direction and timing of data transfers. When writing into the SY6522, data is first latched into a data input register during  $\Phi 2$ . Data is then transferred into the desired internal register during  $\Phi 2$  · Chip Select. This allows the peripheral I/O lines to change states cleanly. When the processor reads the SY6522, data is transferred from the desired internal register directly onto the Data Bus during  $\Phi 2$ .

### C. Port A Registers, Port B Registers

Three registers are used in accessing each of the 8-bit peripheral ports. Each port has a Data Direction Register (DDRA, DDRB) for specifying whether the peripheral pins are to act as inputs or outputs. A 0 in a bit of the Data Direction Register causes the corresponding peripheral pin to act as an input. A 1 causes the pin to act as an output.

Each peripheral pin is also controlled by a bit in the Output Register (ORA, ORB) and an Input Register (IRA, IRB). When the pin is programmed to act as an output, the voltage on the pin is controlled by the corresponding bit of the Output Register. A 1 in the Output Register causes the pin to go high, and a 0 causes the pin to go low. Data can be written into Output Register bits corresponding to pins which are programmed to act as inputs; however, the pin will be unaffected.

Reading a peripheral port causes the contents of the Input Register (IRA, IRB) to be transferred onto the Data Bus. With input latching disabled, IRA will always reflect the data on the PA pins. With input latching enabled, IRA will reflect the contents of the Port A prior to setting the CA1 Interrupt Flag (IFR1) by an active transition on CA1.

The IRB register operates in a similar manner. However, for output pins, the corresponding IRB bit will reflect the contents of the Output Register bit instead of the actual pin. This allows proper data to be read into the processor if the output pin is not allowed to go to full voltage. With input latching enabled on Port B, setting CB1 interrupt flag will cause the IRB to latch this combination of input data and ORB data until the interrupt flag is cleared.

### D. Handshake Control

The SY6522 allows very positive control of data transfers between the system processor and peripheral devices through the operation of "handshake" lines. Port A lines (CA1, CA2) handshake data on both a read and a write operation while the Port B lines (CB1, CB2) handshake on a write operation only.

#### Read Handshake

Positive control of data transfers from peripheral devices into the system processor can be accomplished very effectively using "Read" handshaking. In this case, the peripheral device must generate "Data Ready" to signal the processor that valid data is present on the peripheral port. This signal normally interrupts the processor, which then reads the data. The peripheral device responds by making new data available as processor until the data transfer is complete.

In the SY6522, automatic "Read" handshaking is possible on the Peripheral A port only. The CA1 interrupt input pin accepts the "Data Ready" signal from the peripheral device. When the CA1 input is active, the processor will set an internal flag which can be polled by the processor or which can be polled under software control. The Data Taken signal can be generated by the processor which is set low by the system processor and is cleared by the Data Ready signal from the peripheral device. Figure 16 which illustrates the normal Read Handshaking sequence.

### Write Handshake

The sequence of operations which allows handshaking data from the system processor to a peripheral device is very similar to that described in Section A for Read Handshaking. However, for "Write" handshaking, the processor must generate the "Data Ready" signal (through the SY6522) and the peripheral device must respond with the "Data Taken" signal. This can be accomplished on both the PA port and the PB port on the SY6522. CA2 or CB2 acts as a Data Ready Output in either the DC level or pulse mode and CA1 or CB1 accepts the "Data Taken" signal from the peripheral device, setting the interrupt flag and clearing the "Data Ready" output. This sequence is shown in Figure 7.

Figure 6. READ HANDSHAKE TIMING SEQUENCE

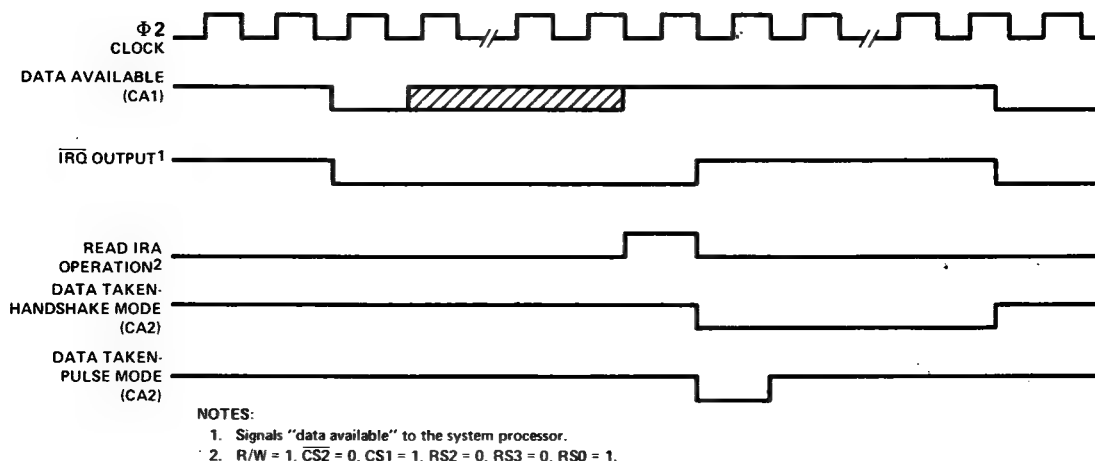
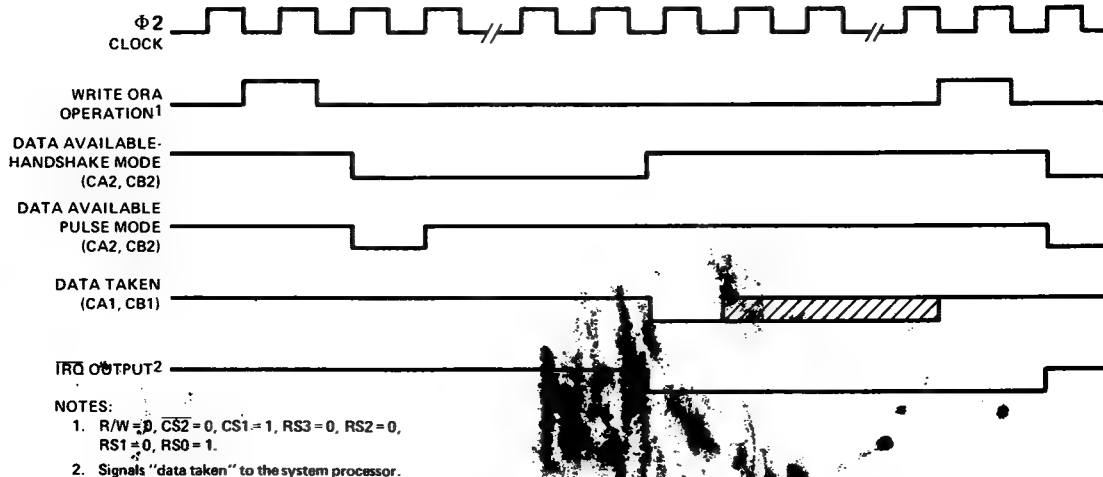


Figure 7. WRITE HANDSHAKE TIMING SEQUENCE



### E. Timer 1

Interval Timer T1 consists of two 8-bit latches and a 16-bit counter. The latches are used to store data which is to be loaded into the counter. After loading, the counter decrements at system clock rate, i.e., under control of the clock applied to the Phase Two input pin. Upon reaching zero, an interrupt flag will be set, and  $\overline{IRQ}$  will go low. The timer will then disable any further interrupts, or will automatically transfer the contents of the latches into the counter and will continue to decrement. In addition, the timer can be instructed to invert the output signal on a peripheral pin each time it "times-out". Each of these modes is discussed separately below.

#### Writing the Timer 1 Registers

The operations which take place when writing to each of the four T1 addresses are as follows:

RS3	RS2	RS1	RS0	Operation (R/W = L)
L	H	L	L	Write into low order latch.
				Write into high order latch.
L	H	L	H	Write into high order counter. Transfer low order latch into low order counter. Reset T1 interrupt flag.
L	H	H	L	Write into low order latch.
L	H	H	H	Write into high order latch. Reset T1 interrupt flag.

Note that the processor does not write directly into the low order counter (T1C-L). Instead, this half of the counter is loaded automatically from the low order latch when the processor writes into the high order counter. In fact, it may not be necessary to write to the low order counter in some applications since the timing operation is triggered by writing to the high order counter.

The second set of addresses allows the processor to write into the latch register without affecting the count-down in progress. This is discussed in detail below.

#### Reading the Timer 1 Registers

For reading the Timer 1 registers, the four addresses relate directly to the four registers as follows.

RS3	RS2	RS1	RS0	Operation (R/W = H)
L	H	L	L	Read T1 low order counter. Reset T1 interrupt flag.
L	H	L	H	Read T1 high order counter.
L	H	H	L	Read T1 low order latch.
L	H	H	H	Read T1 high order latch.

#### Timer 1 Operating Modes

Two bits are provided in the Auxiliary Control Register to allow selection of the T1 operating modes. These bits and the four possible modes are as follows:

ACR7 Output Enable	ACR6 "Free-Run" Enable	Mode
0	0	Generate a time-out interrupt each time T1 is loaded. PB7 disabled.
0	1	Generate continuous interrupts. PB7 disabled.
1	0	Generate a single interrupt and an output pulse on PB7 for each T1 load operation.
1	1	Generate continuous interrupts and a square wave output on PB7.



## TIMER 1 ONE-SHOT MODE

The interval timer one-shot mode allows generation of a single interrupt for each timer load operation. As with any interval timer, the delay between the "write T1C-H" operation and generation of the processor interrupt is a direct function of the data loaded into the timing counter. In addition to generating a single interrupt, Timer 1 can be programmed to produce a single negative pulse on the PB7 peripheral pin. With the output enabled (ACR7=1) a "write T1C-H" operation will cause PB7 to go low. PB7 will return high when Timer 1 times out. The result is a single programmable width pulse.

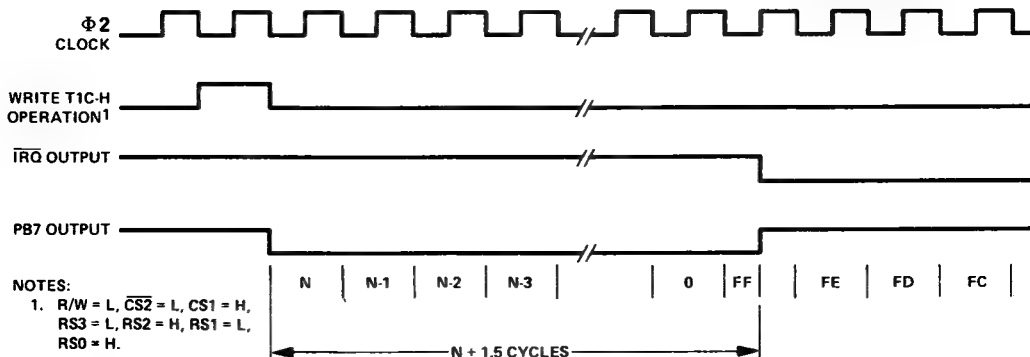
### NOTE

PB7 will act as an output if DDRB7 = 1 or if ACR7 = 1. However, if both DDRB7 and ACR7 are logic 1, PB7 will be controlled from Timer 1 and ORB7 will have no effect on the pin.

In the one-shot mode, writing into the high order latch has no effect on the operation of Timer 1. However, it will be necessary to assure that the low order latch contains the proper data before initiating the count-down with a "write T1C-H" operation. When the processor writes into the high order counter, the T1 interrupt flag will be cleared, the contents of the low order latch will be transferred into the low order counter, and the timer will begin to decrement at system clock rate. If the PB7 output is enabled, this signal will go low on the phase two following the write operation. When the counter reaches zero, the T1 interrupt flag will be set, the  $\overline{\text{IRQ}}$  pin will go low (interrupt enabled), and the signal on PB7 will go high. At this time the counter will continue to decrement at system clock rate. This allows the system processor to read the contents of the counter to determine the time since interrupt. However, the T1 interrupt flag cannot be set again unless it has been cleared as described elsewhere in this specification.

Timing for the SY6522 interval timer one-shot modes is shown in figure 8.

**Figure 8. INTERVAL TIMER "ONE-SHOT" MODE TIMING SEQUENCE**



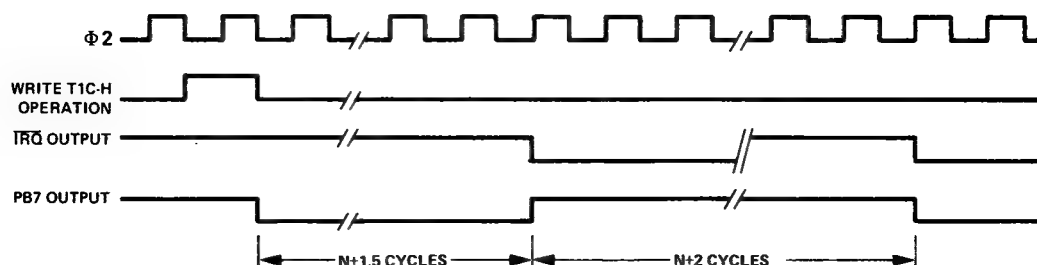
## TIMER 1 FREE-RUNNING MODE

The most important advantage associated with the latches in T1 is the ability to produce a continuous series of evenly spaced interrupts and the ability to produce a square wave on PB7 whose frequency is not affected by variations in the processor interrupt response time. This is accomplished in the "free-running" mode.

In the free-running mode (ACR6 = 1), the interrupt flag is set and the signal on PB7 is inverted each time the counter reaches zero. However, instead of continuing to decrement from zero after a time-out, the timer automatically transfers the contents of the latch into the counter (16 bits) and continues to decrement from there. The interrupt flag can be cleared by writing T1C-H, by reading T1C-L, or by writing directly into the flag as described below. However, it is not necessary to rewrite the timer to enable setting the interrupt flag on the next time-out.

All interval timers in the SY6500 family devices are "re-triggerable". Rewriting the counter will always re-initialize the time-out period. In fact, the time-out can be prevented completely if the processor continues to rewrite the timer before it reaches zero. Timer 1 will operate in this manner if the processor writes into the high order counter (T1C-H). However, by loading the latches only, the processor can access the timer during each down-counting operation without affecting the time-out in process. Instead, the data loaded into the latches will determine the length of the next time-out period. This capability is particularly valuable in the free-running mode with the output enabled. In this mode, the signal on PB7 is inverted and the interrupt flag is set with each time-out. By responding to the interrupts with new data for the latches, the processor can determine the period of the next half cycle during each half cycle of the output signal on PB7. In this manner, very complex waveforms can be generated. Timing for the free-running mode is shown in Figure 9.

**Figure 9. TIMER 1 "FREE-RUNNING" MODE**



#### F. Timer 2

Timer 2 operates as an interval timer (in the "one-shot" mode only), or as a counter for counting negative pulses on the PB6 peripheral pin. A single control bit is provided in the Auxiliary Control Register to select between these two modes. This timer is comprised of a "write-only" low-order latch (T2L-L), a "read-only" low-order counter and a read/write high order counter. The counter registers act as a 16-bit counter which decrements at  $\Phi 2$  rate.

Timer 2 addressing can be summarized as follows:

RS3	RS2	RS1	RS0	R/W = 0	R/W = 1
H	L	L	L	Write T2L-L	Read T2C-L Clear Interrupt flag
H	L	L	H	Write T2C-H Transfer T2L-L to T2C-L Clear Interrupt flag	Read T2C-H

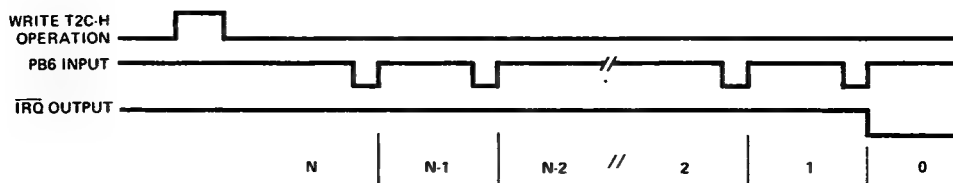
#### Timer 2 Interval Timer Mode

As an interval timer, T2 operates in the "one-shot" mode similar to Timer 1. In this mode, T2 provides a single interrupt for each "write T2C-H" operation. After timing out, the counter will continue to decrement. However, setting of the interrupt flag will be disabled after initial time-out so that it will not be set by the counter continuing to decrement through zero. The processor must rewrite T2C-H to enable setting of the interrupt flag. The interrupt flag is cleared by reading T2C-L or by writing T2C-H. Timing for this operation is shown in Figure 8.

#### Timer 2 Pulse Counting Mode

In the pulse counting mode, T2 serves primarily to count a predetermined number of negative-going pulses on PB6. This is accomplished by first loading a number into T2. Writing into T2C-H clears the interrupt flag and allows the counter to decrement each time a pulse is applied to PB6. The interrupt flag will be set when T2 reaches zero. At this time the counter will continue to decrement with each pulse on PB6. However, it is necessary to rewrite T2C-H to allow the interrupt flag to set on subsequent down-counting operations. Timing for this mode is shown in Figure 10. The pulse must be low on the leading edge of  $\Phi 2$ .

**Figure 10. TIMER 2 PULSE COUNTING MODE**



### G. Shift Register

The Shift Register (SR) performs serial data transfers into and out of the CB2 pin under control of an internal modulo-8 counter. Shift pulses can be applied to the CB1 pin from an external source or, with the proper mode selection, shift pulses generated internally will appear on the CB1 pin for controlling external devices.

The control bits which select the various shift register operating modes are located in the Auxiliary Control Register. These bits can be set and cleared by the system processor to select one of the operating modes discussed in the following paragraphs.

#### Shift Register Input Modes

Bit 4 of the Auxiliary Control Register selects the input or output modes. There are three input modes and four output modes, differing primarily in the source of the pulses which control the shifting operation. With ACR4 = 0 the input modes are selected by ACR3 and ACR2 as follows:

ACR4	ACR3	ACR2	Mode
0	0	0	Shift Register Disabled
0	0	1	Shift in under control of Timer 2
0	1	0	Shift in at System Clock Rate.
0	1	1	Shift in under control of external input pulses

#### Mode 000 - Shift Register Disabled

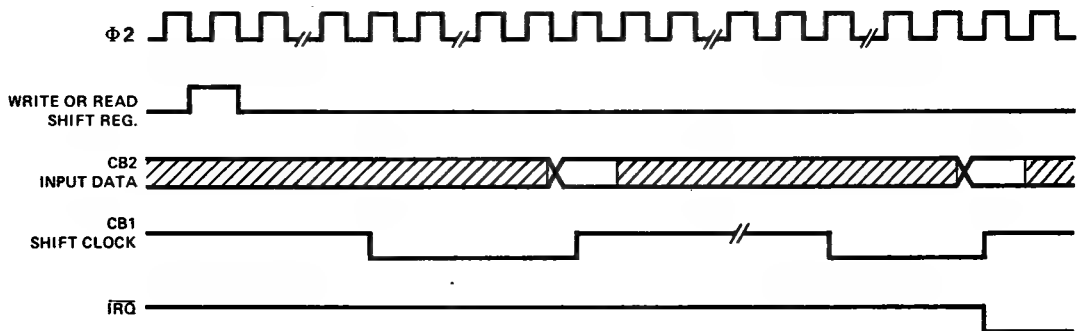
The 000 mode is used to disable the Shift Register. In this mode the microprocessor can write or read the SR, but the shifting operation is disabled and operation of CB1 and CB2 is controlled by the appropriate bits in the Peripheral Control Register (PCR). In this mode the SR Interrupt Flag is disabled (held to a logic 0).

#### Mode 001 - Shift in Under Control of Timer 2

In this mode the shifting rate is controlled by the low order 8 bits of T2. Shift pulses are generated on the CB1 pin to control shifting in external devices. The time between transitions of this output clock is a function of the system clock period and the contents of the low order T2 latch.

The shifting operation is triggered by writing or reading the shift register. Data is shifted first into the low order bit of SR and is then shifted into the next higher order bit or the shift register on the trailing edge of each clock pulse. As shown in Figure 11, the input data should change before the leading edge of the clock pulse. This data is loaded into the shift register during the system clock cycle following the trailing edge of the clock pulse. After 8 clock pulses, the shift register interrupt flag will be set and IRQ will go low.

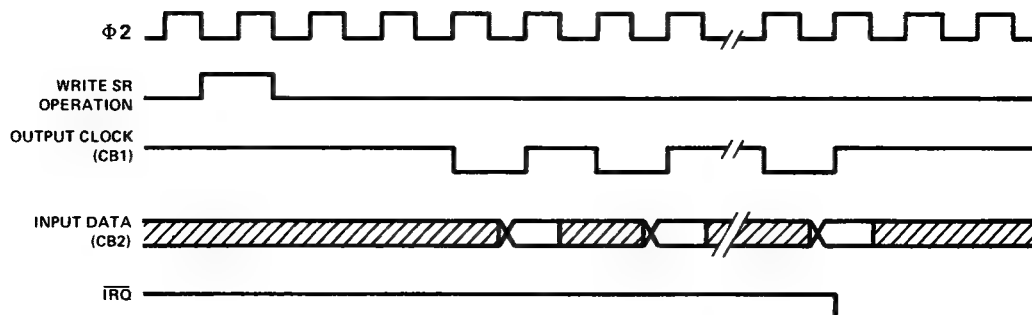
Figure 11. SHIFTING IN UNDER CONTROL OF T2



#### Mode 010 - Shift in at System Clock Rate

In this mode the shift rate is a direct function of the system clock frequency. CB1 becomes an output which generates shift pulses for controlling external devices. Timer 2 operates as an independent interval timer and has no effect on SR. The shifting operation is triggered by reading or writing the Shift Register. Data is shifted first into bit 0 and is then shifted into the next higher order bit of the shift register on the trailing edge of each clock pulse. After 8 clock pulses, the shift register interrupt flag will be set, and the output clock pulses on CB1 will stop. CB1 will stop.

**Figure 12. TIMING SEQUENCE FOR SHIFTING IN AT SYSTEM CLOCK RATE**

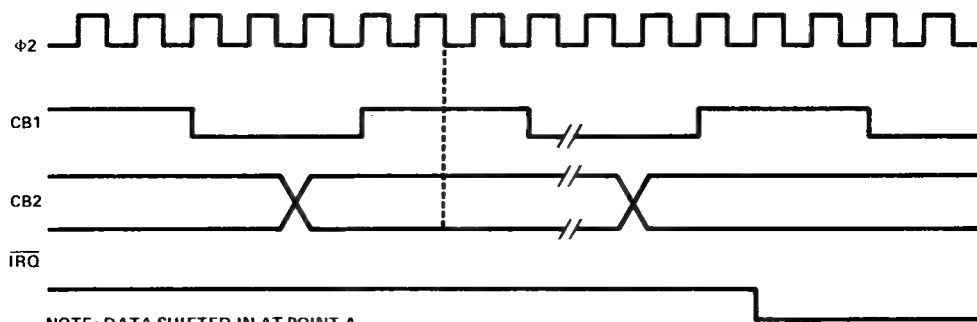


#### Mode 011 - Shift in Under Control of External Clock

In this mode CB1 becomes an input. This allows an external device to load the shift register at its own pace. The shift register counter will interrupt the processor each time 8 bits have been shifted in. However, the shift register counter does not stop the shifting operation; it acts simply as a pulse counter. Reading or writing the Shift Register resets the Interrupt flag and initializes the SR counter to count another 8 pulses.

Note that the data is shifted during the first system clock cycle following the leading edge of the CB1 shift pulse. For this reason, data must be held stable during the first full cycle following CB1 going high. Timing for this operation is shown in Figure 13.

**Figure 13. TIMING SEQUENCE FOR SHIFTING IN UNDER CONTROL OF EXTERNAL CLOCK**



### Shift Register Output Modes

The four Shift Register Output Modes are selected by setting the Input/Output Control Bit (ACR4) to a logic 1 and then selecting the specific output mode with ACR3 and ACR2. In each of these modes the Shift Register shifts data out of bit 7 to the CB2 pin. At the same time the contents of bit 7 are shifted back into bit 0. As in the input modes, CB1 is used either as an output to provide shifting pulses out or as an input to allow shifting from an external pulse. The four modes are as follows:

ACR4	ACR3	ACR2	Mode
1	0	0	Shift out - Free-running mode. Shift rate controlled by T2.
1	0	1	Shift out - Shift rate controlled by T2. Shift pulses generated on CB1.
1	1	0	Shift out at system clock rate.
1	1	1	Shift out under control of an external pulse.

#### Mode 100 Free-Running Output

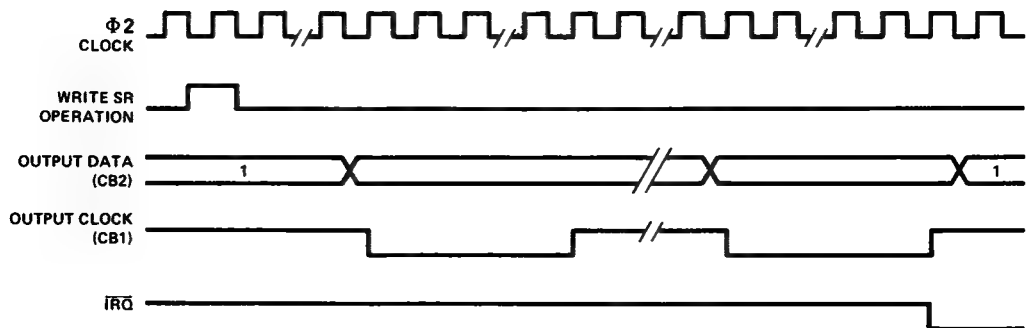
This mode is very similar to mode 101 in which the shifting rate is set by T2. However, in mode 100 the SR Counter does not stop the shifting operation. Since the Shift Register bit 7 (SR7) is recirculated back into bit 0, the 8 bits loaded into the shift register will be clocked onto CB2 repetitively. In this mode the shift register counter is disabled.

#### Mode 101 - Shift out Under Control of T2

In this mode the shift rate is controlled by T2 (as in the previous mode). However, with each read or write of the shift register the SR Counter is reset and 8 bits are shifted onto CB2. At the same time, 8 shift pulses are generated on CB1 to control shifting in External devices. After the 8 shift pulses, the shifting is disabled, the SR Interrupt Flag is set and CB2 goes to a state determined by the CB2 Control bit (PC5) in the Peripheral Control Register.

The CB2 Control bits (PC7, PC6, and PC5) must be used to set CB2 to a manual output selecting either a high or low polarity. If the shift register is reloaded before the last time-out, the shifting will continue. This sequence is illustrated in Figure 14.

Figure 14. SHIFTING OUT UNDER CONTROL OF T2



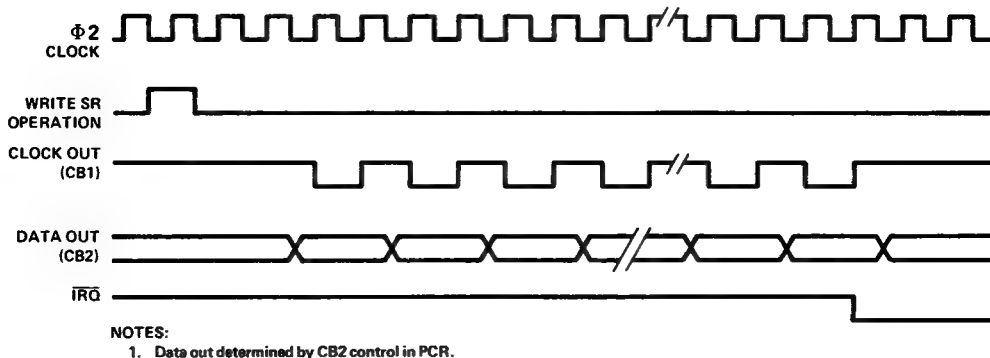
#### NOTES:

1. DATA OUT DETERMINED BY CB2 CONTROL IN PCR.

#### Mode 110 - Shifting out at System Clock Rate

In this mode the shift register operation is similar to that shown in Figure 11. However, the shifting rate is a function of the system clock on the chip enable pin ( $\Phi 2$ ) and is independent of T2. Timer 2 resumes its normal function as an independent interval timer. Figure 15 illustrates the timing sequence for mode 110.

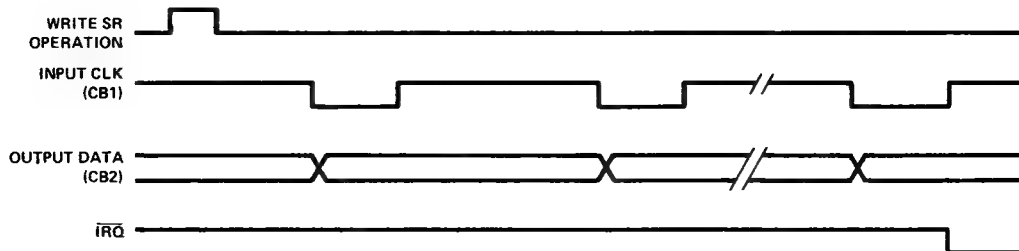
**Figure 15. SHIFTING OUT UNDER CONTROL OF SYSTEM CLOCK**



#### **Mode 111 - Shift out under Control of an External Pulse**

In this mode, shifting is controlled by pulses applied to the CB1 pin by an external device. The SR counter sets the SR Interrupt flag each time it counts 8 pulses but it does not disable the shifting function. Each time the microprocessor writes or reads the shift register, the SR Interrupt flag is reset and the SR counter is initialized to begin counting the next 8 shift pulses on pin CB1. After 8 shift pulses, the interrupt flag is set. The microprocessor can then load the shift register with the next byte of data.

**Figure 16. SHIFTING OUT UNDER CONTROL OF EXTERNAL CLOCK**



#### **H. Interrupt Control**

Controlling interrupts within the SY6522 involves three principal operations. These are flagging the interrupts, enabling interrupts and signalling to the processor that an active interrupt exists within the chip. Interrupt flags are set by interrupting conditions which exist within the chip or on inputs to the chip. These flags normally remain set until the interrupt has been serviced. To determine the source of an interrupt, the microprocessor must examine these flags in order from highest to lowest priority. This is accomplished by reading the flag register into the processor accumulator, shifting this register either right or left and then using conditional branch instructions to detect an active interrupt.

Associated with each interrupt flag is an interrupt enable bit. This bit can be set or cleared by the processor to enable interrupting the processor from the corresponding interrupt flag. If an interrupt flag is set to a logic 1 by an interrupting condition, and the corresponding interrupt enable bit is set to a 1, the Interrupt Request Output ( $\overline{\text{IRQ}}$ ) will go low.  $\overline{\text{IRQ}}$  is an "open-collector" output which can be "wire-or'ed" with other devices in the system to interrupt the processor.

In the SY6522, all the interrupt flags are contained in one register. In addition, bit 7 of this register will be read as a logic 1 when an interrupt exists within the chip. This allows very convenient polling of several devices within a system to locate the source of an interrupt.

REGISTER NAME	REGISTER BIT							
	7	6	5	4	3	2	1	0
Interrupt Flag Register (IFR)	IRQ	T1	T2	CB1	CB2	SR	CA1	CA2
Interrupt Enable Register (IER)	Set/clear control	T1	T2	CB1	CB2	SR	CA1	CA2

### Interrupt Flag Register

The IFR is a read/bit-clear register. When the proper chip select and register signals are applied to the chip, the contents of this register are placed on the data bus. Bit 7 indicates the status of the  $\overline{\text{IRQ}}$  output. This bit corresponds to the logic function:  $\text{IRQ} = \text{IFR6} \times \text{IER6} + \text{IFR5} \times \text{IER5} + \text{IFR4} \times \text{IER4} + \text{IFR3} \times \text{IER3} + \text{IFR2} \times \text{IER2} + \text{IFR1} \times \text{IER1} + \text{IFR0} \times \text{IER0}$ . Note: X = logic AND, + = Logic OR.

Bits six through zero are latches which are set and cleared as follows:

Bit #	Set by	Cleared By
0	Active transition of the signal on the CA2 pin.	Reading or writing the A port Output Register (ORA) using address 0001.
1	Active transition of the signal on the CA1 pin.	Reading or writing the A Port Output Register (ORA) using address 0001.
2	Completion of eight shifts.	Reading or writing the Shift Register.
3	Active transition of the signal on the CB2 pin.	Reading or writing the B Port Output Register.
4	Active transition of the signal on the CB1 pin.	Reading or writing the B Port Output Register.
5	Time-out of Timer 2.	Reading T2 low order counter. Writing T2 high order counter.
6	Time-out of Timer 1.	Reading T1 low order counter. Writing T1 high order counter.

The IFR bit 7 is not a flag. Therefore, this bit is not directly cleared by writing a logic 1 into it. It can only be cleared by clearing all the flags in the register or by disabling all the active interrupts as discussed in the next section.

### Interrupt Enable Register (IER)

For each interrupt flag in IFR, there is a corresponding bit in the Interrupt Enable Register. The system processor can set or clear selected bits in this register to facilitate controlling individual interrupts without affecting others. This is accomplished by writing to address 1110 (IER address). If bit 7 of the data placed on the system data bus during this write operation is a 0, each 1 in bits 6 through 0 clears the corresponding bit in the Interrupt Enable Register. For each zero in bits 6 through 0, the corresponding bit is unaffected.

Setting selected bits in the Interrupt Enable Register is accomplished by writing to the same address with bit 7 in the data word set to a logic 1. In this case, each 1 in bits 6 through 0 will set the corresponding bit. For each zero, the corresponding bit will be unaffected. This individual control of the setting and clearing operations allows very convenient control of the interrupts during system operation.

In addition to setting and clearing IER bits, the processor can read the contents of this register by placing the proper address on the register select and chip select inputs with the R/W line high. Bit 7 will be read as a logic 0.

## 1. Function Control

Control of the various functions and operating modes within the SY6522 is accomplished primarily through two registers, the Peripheral Control Register (PCR) and the Auxiliary Control Register (ACR). The PCR is used primarily to select the operating mode for the four peripheral control pins. The Auxiliary Control Register selects the operating mode for the interval timers (T1, T2), and the serial port (SR).

### Peripheral Control Register

The Peripheral Control Register is organized as follows:

Bit #	7	6	5	4	3	2	1	0
Function	CB2 Control			CB1 Control	CA2 Control			CA1 Control

Each of these functions is discussed in detail below.

### 1. CA1 Control

Bit 0 of the Peripheral Control Register selects the active transition of the input signal applied to the CA1 interrupt input pin. If this bit is a logic 0, the CA1 interrupt flag will be set by a negative transition (high to low) of the signal on the CA1 pin. If PCR0 is a logic 1, the CA1 interrupt flag will be set by a positive transition (low to high) of this signal.

### 2. CA2 Control

The CA2 pin can be programmed to act as an interrupt input or as a peripheral control output. As an input, CA2 operates in two modes, differing primarily in the methods available for resetting the interrupt flag. Each of these two input modes can operate with either a positive or a negative active transition as described above for CA1.

In the output mode, the CA2 pin combines the operations performed on the CA2 and CB2 pins of the SY6522. This added flexibility allows processor to perform a normal "write" handshaking in a system which uses CB1 and CB2 for the serial operations described above. The CA2 operating modes are selected as follows:

PCR3	PCR2	PCR1	Mode
0	0	0	Input mode—Set CA2 interrupt flag (IFR0) on a negative transition of the input signal. Clear IFR0 on a read or write of the Peripheral A Output Register.
0	0	1	Independent interrupt input mode—Set IFR0 on a negative transition of the CA2 input signal. Reading or writing ORA does not clear the CA2 Interrupt flag.
0	1	0	Input mode—Set CA2 interrupt flag on a positive transition of the CA2 input signal. Clear IFR0 with a read or write of the Peripheral A Output Register.
0	1	1	Independent Interrupt input mode—Set IFR0 on a positive transition of the CA2 input signal. Reading or writing ORA does not clear the CA2 interrupt flag.
1	0	0	Handshake output mode—Set CA2 output low on a read or write of the Peripheral A Output Register. Reset CA2 high with an active transition on CA1.
1	0	1	Pulse Output mode—CA2 goes low for one cycle following a read or write of the Peripheral A Output Register.
1	1	0	Manual output mode—The CA2 output is held low in this mode.
1	1	1	Manual output mode—The CA2 output is held high in this mode.

In the independent input mode, writing or reading the ORA register has no effect on the CA2 interrupt flag. This flag must be cleared by writing a logic 1 into the appropriate IFR bit. This mode allows the processor to handle interrupts which are independent of any operations taking place on the peripheral I/O ports.

The handshake and pulse output modes have been described previously. Note that the timing of the output signal varies slightly depending on whether the operation is initiated by a read or a write.



### 3. CB1 Control

Control of the active transition of the CB1 input signal operates in exactly the same manner as that described above for CA1. If PCR4 is a logic 0 the CB1 interrupt flag (IFR4) will be set by a negative transition of the CB1 input signal and cleared by a read or write of the ORB register. If PCR4 is a logic 1, IFR4 will be set by a positive transition of CB1.

If the Shift Register function has been enabled, CB1 will act as an input or output for the shift register clock signals. In this mode the CB1 interrupt flag will still respond to the selected transition of the signal on the CB1 pin.

### 4. CB2 Control

With the serial port disabled, operation of the CB2 pin is a function of the three high order bits of the PCR. The CB2 modes are very similar to those described previously for CA2. These modes are selected as follows:

PCR7	PCR6	PCR5	Mode
0	0	0	Interrupt input mode—Set CB2 interrupt flag (IFR3) on a negative transition of the CB2 input signal. Clear IFR3 on a read or write of the Peripheral B Output Register.
0	0	1	Independent interrupt input mode—Set IFR3 on a negative transition of the CB2 input signal. Reading or writing ORB does not clear the interrupt flag.
0	1	0	Input mode—Set CB2 interrupt flag on a positive transition of the CB2 input signal. Clear the CB2 interrupt flag on a read or write of ORB.
0	1	1	Independent input mode—Set IFR3 on a positive transition of the CB2 input signal. Reading or writing ORB does not clear the CB2 interrupt flag.
1	0	0	Handshake output mode—Set CB2 low on a write ORB operation. Reset CB2 high with an active transition of the CB1 input signal.
1	0	1	Pulse output mode—Set CB2 low for one cycle following a write ORB operation.
1	1	0	Manual output mode—The CB2 output is held low in this mode.
1	1	1	Manual output mode—The CB2 output is held high in this mode.

## AUXILIARY CONTROL REGISTER

Many of the functions in the Auxiliary Control Register have been discussed previously. However, a summary of this register is presented here as a convenient reference for the SY6522 user. The Auxiliary Control Register is organized as follows:

Bit #	7	6	5	4	3	2	1	0
Function	T1 Control		T2 Control	Shift Register Control			PB Latch Enable	PA Latch Enable

### 1. PA Latch Enable

The SY6522 provides input latching on both the PA and PB ports. In this mode, the data present on the peripheral A input pins will be latched within the chip when the CA1 interrupt flag is set. Reading the PA port will result in these latches being transferred into the processor. As long as the CA1 interrupt flag is set, the data on the peripheral pins can change without affecting the data in the latches. This input latching can be used with any of the CA2 input or output modes.

It is important to note that on the PA port, the processor always reads the data on the peripheral pins (as reflected in the latches). For output pins, the processor still reads the latches. This may or may not reflect the data currently in the ORA. Proper system operation requires careful planning on the part of the system designer if input latching is combined with output pins on the peripheral ports.

Input latching is enabled by setting bit 0 in the Auxiliary Control Register to a logic 1. As long as this bit is a 0, the latches will directly reflect the data on the pins.

## 2. PB Latch Enable

Input latching on the PB port is controlled in the same manner as that described for the PA port. However, with the peripheral B port the input latch will store either the voltage on the pin or the contents of the Output Register (ORB) depending on whether the pin is programmed to act as an input or an output. As with the PA port, the processor always reads the input latches.

## 3 Shift Register Control

The Shift Register operating mode is selected as follows:

ACR4	ACR3	ACR2	Mode
0	0	0	Shift Register Disabled.
0	0	1	Shift in under control of Timer 2.
0	1	0	Shift in under control of system clock.
0	1	1	Shift in under control of external clock pulses.
1	0	0	Free-running output at rate determined by Timer 2.
1	0	1	Shift out under control of Timer 2.
1	1	0	Shift out under control of the system clock.
1	1	1	Shift out under control of external clock pulses.

## 4. T2 Control

Timer 2 operates in two modes. If ACR5 = 0, T2 acts as an interval timer in the one-shot mode. If ACR5 = 1, Timer 2 acts to count a predetermined number of pulses on pin PB6.

## 5. T1 Control

Timer 1 operates in the one-shot or free-running mode with the PB7 output control enabled or disabled. These modes are selected as follows:

ACR7	ACR6	Mode
0	0	One-shot mode—Output to PB7 disabled
0	1	Free-running mode—Output to PB7 disabled.
1	0	One-shot mode—Output to PB7 enabled.
1	1	Free-running mode—Output to PB7 enabled.

## APPLICATION OF THE SY6522

The SY6522 represents a significant advance in general-purpose microprocessor I/O. Unfortunately, its many powerful features, coupled with a set of very flexible operating modes, cause this device to appear to be very complex at first glance. However, a detailed analysis will show that the VIA is organized to allow convenient control of these powerful features. This section seeks to assist the system designer in his understanding of the SY6522 by illustrating how the device can be used in microprocessor-based systems.

### A. Control of the SY6522 Interrupts

Organization of the SY6522 interrupt flags into a single register greatly facilitates the servicing of interrupts from this device. Since there is only one  $\overline{\text{IRQ}}$  output for the seven possible sources of interrupt within the chip, the processor must examine these flags to determine the cause of an interrupt. This is best accomplished by first transferring the contents of the flag register into the accumulator. At this time it may be necessary to mask off these flags which have been disabled in the Interrupt Enable Register. This is particularly important for the edge detecting inputs where the flags may be set whether or not the interrupting function has been enabled. Masking off these flags can be accomplished by performing an AND operation between the IER and the accumulator or by performing an "AND IMMEDIATE". The second byte of this AND # instruction should specify those flags which correspond to interrupt functions which are to be serviced.

If the N flag is set after these operations, an active interrupt exists within the chips. This interrupt can be detected with a series of shift and branch instructions.

Clearing interrupt flags is accomplished very conveniently by writing a logic 1 directly into the appropriate bit of the Interrupt Flag Register. This can be combined with an interrupt enable or disable operation as follows:

```
LDA #@10010000 ; initialize accumulator
STA IFR         ; clear interrupt flag
STA IER         ; set interrupt enable flag
```

or:

```
LDA #@00001000 ; initialize accumulator
STA IFR         ; clear interrupt flag
STA IER         ; disable interrupt
```

Another very useful technique for clearing interrupt flags is to simply transfer the contents of the flag register back into this register as follows:

```
LDA IFR         ; transfer IFR to accumulator
STA IFR         ; clear flags corresponding to active interrupts
```

After completion of this operation the accumulator will still contain the interrupt flag information. Most important, writing into the flag register clears only those flags which are already set. This eliminates the possibility of inadvertently clearing a flag while it is being set.

## B. Use of Timer 1

Timer 1 represents one of the most powerful features of the SY6522. The ability to generate very evenly spaced interrupts and the ability to control the voltage on PB7 makes this timer particularly valuable in various timing, data detection and waveform generation applications.

### Time-of-Day Clock Applications

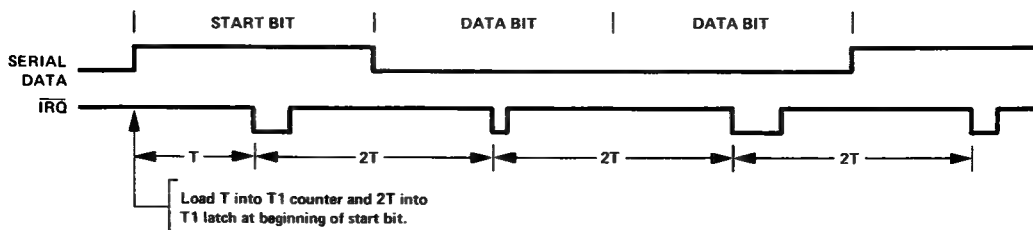
An important feature of many systems is the time-of-day clock. In microprocessor-based systems the time of day is usually maintained in memory and is updated in an interrupt service routine. A regular processor interrupt will then assure that this time of day will always be available when it is needed in the main program.

Generating very regular interrupts using previously available timers presented difficulties because of the need to re-load the timer for each interrupt. Unfortunately, the time between the interrupts will fluctuate due to variations in the interrupt response time. This problem is eliminated in the Timer 1 "free-running" mode. The accuracy of these "free-running" interrupts is only a function of the system clock and is not affected by interrupt response time.

### Asynchronous Data Detection

The extraction of clock and data information from serial asynchronous ASCII signals or from any single channel data recording device relies on the ability to establish accurate strobes. As discussed previously, the period of these strobes can be seriously affected by the interrupt response time using conventional timers. However, T1 again allows generation of very accurate interrupts. The processor responds to these interrupts by strobing the input data. The ability to reload the T1 latches without affecting the count-down in progress is very useful in this application. This allows the strobe time to be doubled or halved during data detection. This sequence of operation is as follows:

Figure 17. DETECTING ASYNCHRONOUS DATA USING TIMER 1



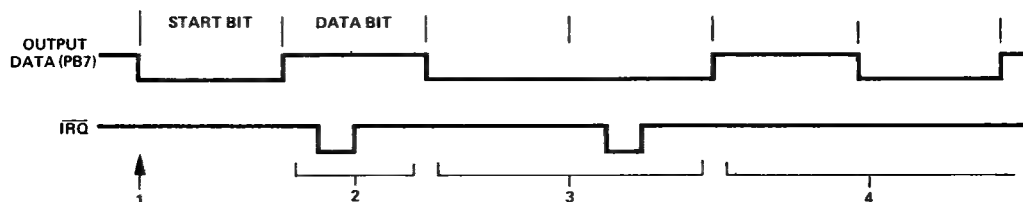
### Waveform Generation with Timer 1

In addition to generating processor interrupts, Timer 1 can be used to control the output voltage on peripheral pin PB7 (output mode). In this mode a single negative pulse can be generated on PB7 (one-shot mode) or, in the free-running mode, a continuous waveform can be generated. In this latter mode the voltage on PB7 will be inverted each time T1 times out.

A single solenoid can be triggered very conveniently in the one-shot mode if the PB7 signal is used to control the solenoid directly. With this configuration the solenoid can be triggered by simply writing to TIC-H.

Generating very complex waveforms can be a simple problem if T1 is used to control PB7 in the free-running mode. During any count-down process the latches can be loaded to determine the length of the next count-down period. Figure 18 shows this timing sequence for generating ASCII serial data.

**Figure 18. ASCII SERIAL DATA GENERATION USING T1**

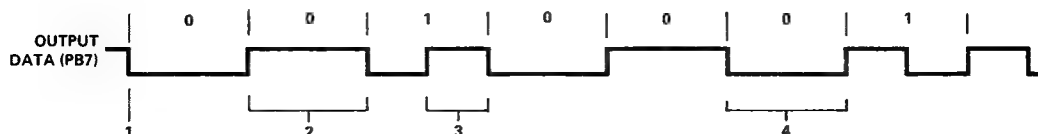


1. Load T into T1 counter and latch. Load T into T2 to trigger T1 latch reload.
2. Load 2T into T1 latch during this bit time. Load 2T into T2, as before.
3. Load T into T1 latch anytime during this period. Load NT into T2. N = number of 1's or 0's which follow.
4. A series of 1's and 0's will be generated until the T1 latch is again changed. Note that the use of T2 to control reloading the T1 latch eliminates the need to interrupt on each transition.

An application where this mode of operation is also very powerful is in the generation of bi-phase encoded data for tape or disk storage. This encoding technique and the sequence of operations which would take place are illustrated in Figure 19.

These applications represent only a tiny portion of the potential T1 applications. Some other possibilities are pulse width modulation waveforms, sound generation for video games, A/D techniques requiring very accurate pulse widths, and waveform synthesis in electronic games.

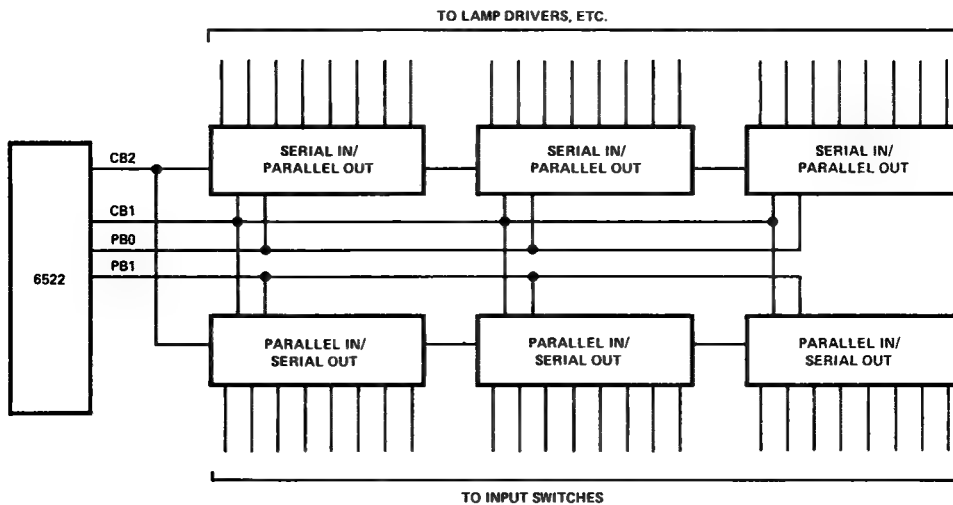
**Figure 19. GENERATING BI-PHASE ENCODED DATA**



1. Load T1 counter and latch.
2. Shift T1 latch one bit to the right during this period.
3. Shift T1 latch left during this period.
4. Shift T1 latch right during this period.

Note that T1 must be accessed only when the output data changes. A string of 1's or 0's can be generated without processor intervention.

**Figure 22. EXPANDING SYSTEM I/O USING SHIFT REGISTER**

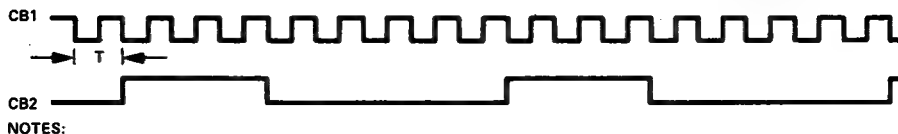


### Clock Generation Using the Shift Register

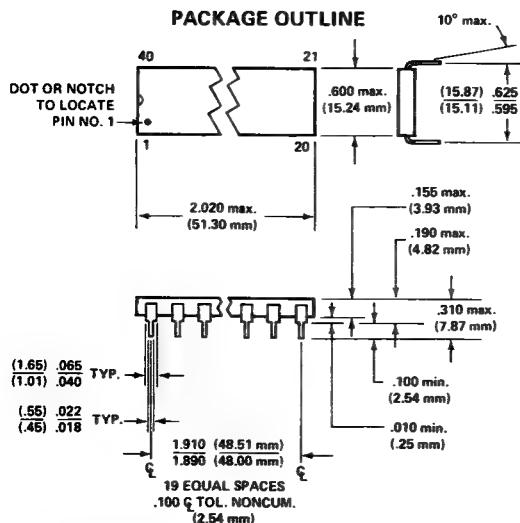
In all output modes the data shifted out of bit 7 will also be shifted into bit 0. For this reason the Shift Register need not be re-loaded if the same data is to be shifted out each time. A Shift Register read operation can be used to trigger the shifting operation.

This capability is very useful for generating peripheral clocks in the continuous output mode. This mode allows an 8-bit pattern to be shifted out continuously. This is illustrated in Figure 23. Note that in this mode the shifting operation is controlled by Timer 2. A single bit time can therefore be up to 256 clock cycles in length.

**Figure 23. CLOCK GENERATION USING SR FREE-RUNNING MODE**



1. Shift Register loaded with 1110 0000<sub>2</sub> initially.
2. T determined by Timer 2.



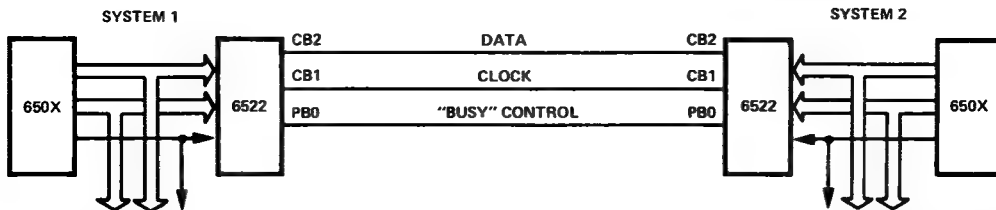
NOTE: Pin No. 1 is in lower left corner when symbolization is in normal orientation

VSS	1	40	CA1
PA0	2	39	CA2
PA1	3	38	RS0
PA2	4	37	RS1
PA3	5	36	RS2
PA4	6	35	RS3
PA5	7	34	RES
PA6	8	33	D0
PA7	9	32	D1
PB0	10	31	D2
PB1	11	30	D3
PB2	12	29	D4
PB3	13	28	D5
PB4	14	27	D6
PB5	15	26	D7
PB6	16	25	φ2
PB7	17	24	CS1
CB1	18	23	CS2
CB2	19	22	R/W
VCC	20	21	IRQ

### Using the SY6522 Shift Register

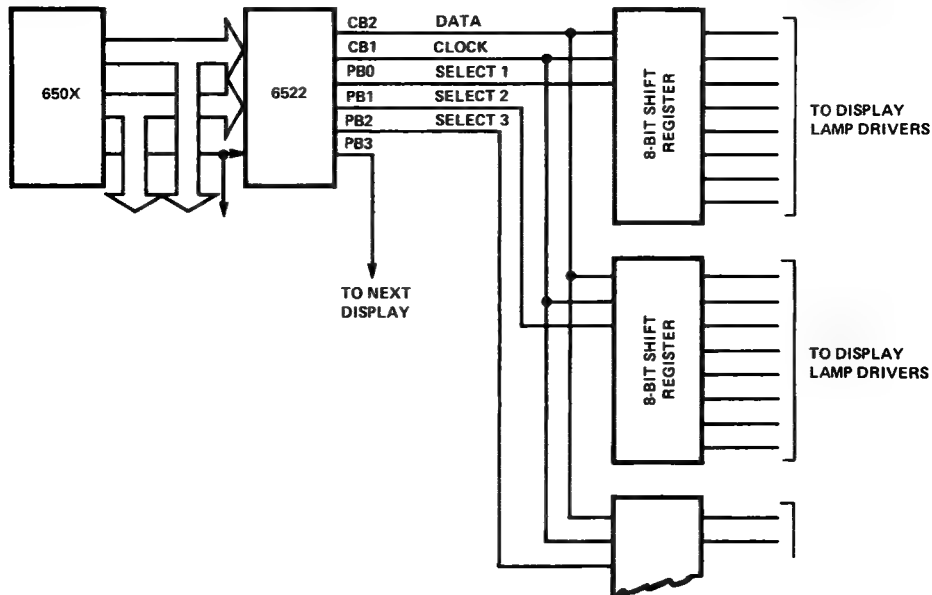
The Shift Register in the SY6522 is designed primarily as a synchronous serial communications port for distributed systems. These systems can be either single-processor with distributed peripheral controllers or distributed processor systems. The most important characteristic of the Shift Register in these applications is its ability to transfer information at relatively slow data rates to allow the use of R-C noise suppression techniques. This transfer can be accomplished while the processor is servicing other aspects of the system. An example of a simple 2-processor distributed system is shown in Figure 20. Use of the SY6522 Shift Register allows effective communication between the two systems without the use of relatively complex asynchronous communications techniques.

**Figure 20. USING SHIFT REGISTER FOR INTER-SYSTEM COMMUNICATION**



In a system with distributed peripherals, the Shift Register can be used to transfer data to the peripheral interface devices. This is illustrated in Figure 21 for a system with a number of distributed status displays. These displays are serviced by stand-alone controllers which actuate the lamps in the status displays with simple drivers. The data and clock lines are wired in parallel to each unit. In addition, a single SY6522 peripheral port allows selection of the display to be loaded. These select lines can be eliminated if all displays are to contain the same information. With the system shown, the status display can be updated at any time by simply selecting the desired display and then writing to the Shift Register.

**Figure 21. USING THE SHIFT REGISTER FOR SERVICING REMOTE STATUS DISPLAYS**



Remote input devices can be serviced in much the same manner by shifting data into the Shift Register under control of a peripheral port output as shown in Figure 21. Each set of input switches can be polled by first selecting the set to be polled and then triggering the shifting operation with a Shift Register read operation. A shift register interrupt can be used to cause the processor to read the resulting input information after shifting is complete.

The techniques described above can be utilized to expand I/O capability in a microprocessor based system. In a system with many status lamps or many input switches, simple TTL shift registers will provide the necessary I/O in a very cost effective manner. This is illustrated in Figure 22.

**APPENDIX I**  
**SY6532 DATA SHEET**





# Synertek®



3050 Coronado Drive, Santa Clara, CA. 95051  
(408) 984-8900 TWX 910-338-0135

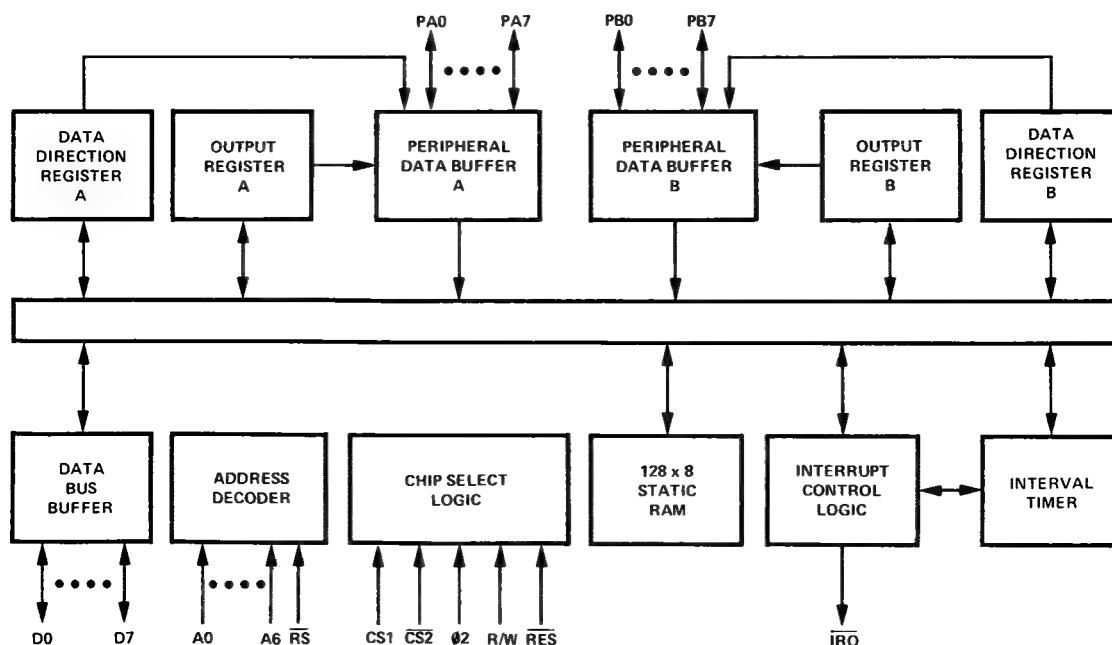
## SY6532

### SY6532 (RAM, I/O, TIMER ARRAY)

The SY6532 is designed to operate in conjunction with the SY6500 Microprocessor Family. It is comprised of a 128 x 8 static RAM, two software controlled 8 bit bi-directional data ports allowing direct interfacing between the microprocessor unit and peripheral devices, a software programmable interval timer with interrupt capable of timing in various intervals from 1 to 262,144 clock periods, and a programmable edge-detect interrupt circuit.

- 8 bit bi-directional Data Bus for direct communication with the microprocessor
- Programmable edge-sensitive interrupt
- 128 x 8 static RAM
- Two 8 bit bi-directional data ports for interface to peripherals
- Two programmable I/O Peripheral Data Direction Registers
- Programmable Interval Timer
- Programmable Interval Timer Interrupt
- TTL & CMOS compatible peripheral lines
- Peripheral pins with Direct Transistor Drive Capability
- High Impedance Three-State Data Pins

Figure 1. 6532 BLOCK DIAGRAM



## MAXIMUM RATINGS

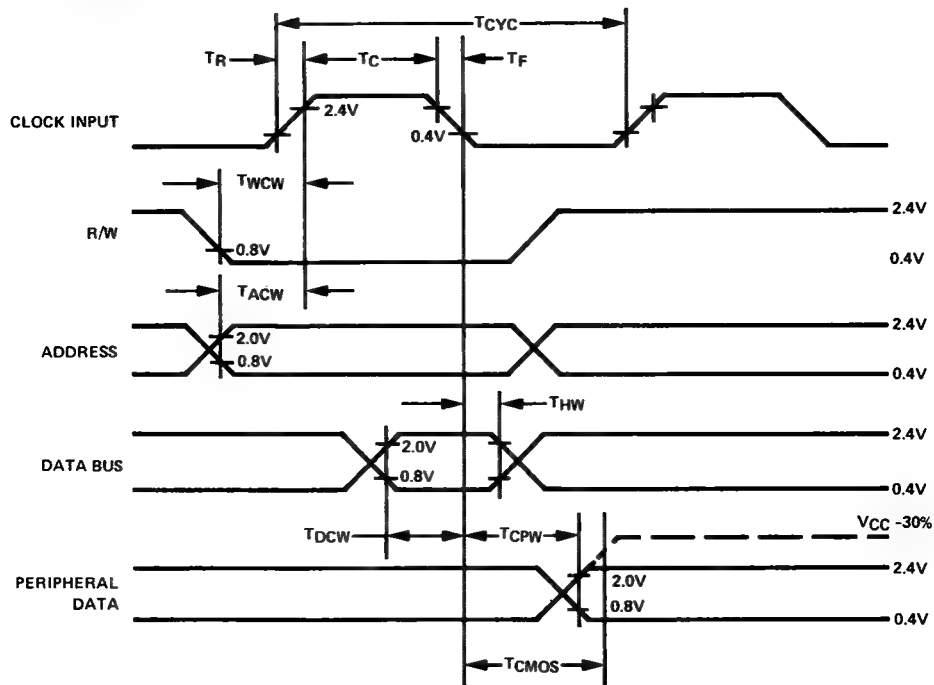
RATING	SYMBOL	VOLTAGE	UNIT
Supply Voltage	$V_{CC}$	-3 to +7.0	V
Input/Output Voltage	$V_{IN}$	-3 to +7.0	V
Operating Temperature Range	$T_{OP}$	0 to 70	°C
Storage Temperature Range	$T_{STG}$	-55 to +150	°C

## ELECTRICAL CHARACTERISTICS ( $V_{CC} = 5.0V \pm 5\%$ , $V_{SS} = 0V$ , $T_A = 25^\circ C$ )

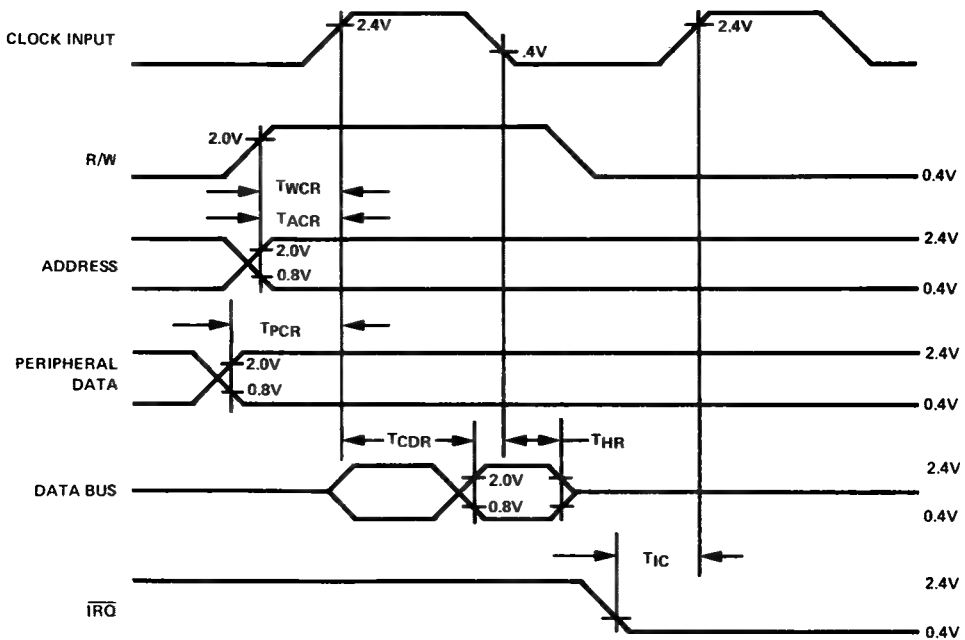
CHARACTERISTIC	SYMBOL	MIN.	TYP.	MAX.	UNIT
Input High Voltage	$V_{IH}$	$V_{SS} + 2.4$		$V_{CC}$	V
Input Low Voltage	$V_{IL}$	$V_{SS} - .3$		$V_{SS} + .4$	V
Input Leakage Current; $V_{IN} = V_{SS} + .5V$ A0-A6, RS, R/W, RES, Ø2, CS1, CS2	$I_{IN}$		1.0	2.5	$\mu A$
Input Leakage Current for High Impedance State (Three State); $V_{IN} = .4V$ to $2.4V$ ; D0-D7	$I_{TSI}$		$\pm 1.0$	$\pm 10.0$	$\mu A$
Input High Current; $V_{IN} = 2.4V$ PA0-PA7, PB0-PB7	$I_{IH}$	-100.	-300.		$\mu A$
Input Low Current; $V_{IN} = .4V$ PA0-PA7, PB0-PB7	$I_{IL}$		-1.0	-1.6	MA
Output High Voltage $V_{CC} = MIN$ , $I_{LOAD} \leq -100\mu A$ (PA0-PA7, PB0-PB7, D0-D7) $I_{LOAD} \leq 3 MA$ (PB0-PB7)	$V_{OH}$	$V_{SS} + 2.4$ $V_{SS} + 1.5$			V
Output Low Voltage $V_{CC} = MIN$ , $I_{LOAD} \leq 1.6MA$	$V_{OL}$			$V_{SS} + .4$	V
Output High Current (Sourcing); $V_{OH} \geq 2.4V$ (PA0-PA7, PB0-PB7, D0-D7) $\geq 1.5V$ Available for direct transistor drive (PB0-PB7)	$I_{OH}$	-100 3.0	-1000 5.0		$\mu A$ MA
Output Low Current (Sinking); $V_{OL} \leq .4V$	$I_{OL}$	1.6			MA
Clock Input Capacitance	$C_{Clk}$			30	pf
Input Capacitance	$C_{IN}$			10	pf
Output Capacitance	$C_{OUT}$			10	pf
Power Dissipation	$I_{CC}$		100	125	mA

All inputs contain protection circuitry to prevent damage due to high static charges. Care should be exercised to prevent unnecessary application of voltage outside the specification range.

## WRITE TIMING CHARACTERISTICS



## READ TIMING CHARACTERISTICS



## WRITE TIMING CHARACTERISTICS

CHARACTERISTIC	SYMBOL	MIN.	TYP.	MAX.	UNIT
Clock Period	TCYC	1			$\mu\text{S}$
Rise & Fall Times	TR, TF			25	NS
Clock Pulse Width	TC	470			NS
R/W valid before positive transition of clock	TWCW	180			NS
Address valid before positive transition of clock	TACW	180			NS
Data Bus valid before negative transition of clock	TDCW	300			NS
Data Bus Hold Time	THW	10			NS
Peripheral data valid after negative transition of clock	TCPW			1	$\mu\text{S}$
Peripheral data valid after negative transition of clock driving CMOS (Level = $V_{CC} = 30\%$ )	TCMOS			2	$\mu\text{S}$

## READ TIMING CHARACTERISTICS

CHARACTERISTIC	SYMBOL	MIN.	TYP.	MAX.	UNIT
R/W valid after positive transition of clock	TWCR	180			NS
Address valid before positive transition of clock	TACR	180			NS
Peripheral data valid before positive transition of clock	TPCR	300			NS
Data Bus valid after positive transition of clock	TCDR			395	NS
Data Bus Hold Time	THR	10			NS
$\overline{\text{IRQ}}$ (Interval Timer Interrupt) valid before positive transition of clock	TIC	200			NS

Loading = 30 pf + 1 TTL load for PA0-PA7, PB0-PB7  
 = 130 pf + 1 TTL load for D0-D7

## INTERFACE SIGNAL DESCRIPTION

### Reset ( $\overline{\text{RES}}$ )

During system initialization a Logic "0" on the  $\overline{\text{RES}}$  input will cause a zeroing of all four I/O registers. This in turn will cause all I/O buses to act as inputs thus protecting external components from possible damage and erroneous data while the system is being configured under software control. The Data Bus Buffers are put into an OFF-STATE during Reset. Interrupt capability is disabled with the  $\overline{\text{RES}}$  signal. The  $\overline{\text{RES}}$  signal must be held low for at least one clock period when reset is required.

### Input Clock

The input clock is a system Phase Two clock which can be either a low level clock ( $V_{IL} < 0.4$ ,  $V_{IH} > 2.4$ ) or high level clock ( $V_{IL} < 0.2$ ,  $V_{IH} = V_{CC}^{+3}_{-2}$ ).

### Read/Write (R/W)

The R/W signal is supplied by the microprocessor array and is used to control the transfer of data to and from the microprocessor array and the SY6532. A high on the R/W pin allows the processor to read (with proper addressing) the data supplied by the SY6532. A low on the R/W pin allows a write (with proper addressing) to the SY6532.

### Interrupt Request ( $\overline{\text{IRQ}}$ )

The  $\overline{\text{IRQ}}$  pin is an interrupt pin from the interrupt control logic. It will be normally high with a low indicating an interrupt from the SY6532.  $\overline{\text{IRQ}}$  is an open-drain output, permitting several units to be wire-or'ed to the common  $\overline{\text{IRQ}}$  microprocessor input pin. The  $\overline{\text{IRQ}}$  pin may be activated by a transition on PA7 or timeout of the interval timer.

### Data Bus (D0-D7)

The SY6532 has eight bi-directional data pins (D0-D7). These pins connect to the system's data lines and allow transfer of data to and from the microprocessor array. The output buffers remain in the off state except when a Read operation occurs.

## Peripheral Data Ports

The SY6532 has 16 pins available for peripheral I/O operations. Each pin is individually programmable to act as either an input or an output. The 16 pins are divided into two 8-bit ports, PA0-PA7 and PB0-PB7. PA7 may also function as an interrupt input pin. This feature is described in another section. The pins are set up as an input by writing a "0" into the corresponding bit of the data direction register. A "1" into the data direction register will cause its corresponding bit to be an output. When in the input mode, the peripheral output buffers are in the "1" state and a pull-up device acts as less than one TTL load to the peripheral data lines. On a Read operation, the microprocessor unit reads the peripheral pin. When the peripheral device gets information from the SY6532 it receives data stored in the data register. The microprocessor will read correct information if the peripheral lines are greater than 2.4 volts for a "1" and less than 0.4 volts for a "0" as the peripheral pins are all TTL compatible. Pins PB0-PB7 are also capable of sourcing 3 ma at 1.5 v thus making them capable of direct transistor drive.

## Address Lines (A0-A6)

There are 7 address pins. In addition to these, there is the  $\overline{RS}$  pin. The above pins, A0-A6 and  $\overline{RS}$ , are always used as addressing pins. There are 2 additional pins which are used as CHIP SELECTS. They are pins CS1 and CS2.

## INTERNAL ORGANIZATION

A block diagram of the internal architecture is shown in Figure 1. The SY6532 is divided into four basic sections: RAM, I/O, Timer, and Interrupt Control. The RAM interfaces directly with the microprocessor through the system data bus and address lines. The I/O section consists of two 8-bit halves. Each half contains a Data Direction Register (DDR) and an I/O register.

### RAM 128 Bytes (1024 Bits)

A 128 x 8 static RAM is contained on the SY6532. It is addressed by A0-A6 (Byte Select),  $\overline{RS}$ , CS1, and CS2.

### Internal Peripheral Registers

There are four 8-bit internal registers: two data direction registers and two output registers. The two data direction registers (A side and B side) control the direction of data into and out of the peripheral I/O pins. A logic zero in a bit of the data direction register (DDRA and DDRB) causes the corresponding pin of the I/O port to act as an input. A logic one causes the corresponding pin to act as an output. The voltage on any pin programmed as an output is determined by the corresponding bit in the output register (ORA and ORB).

Data is read directly from the PA pins during a peripheral read operation. Thus, for a PA pin programmed as an output, the data transferred into the processor will be the same as the data in the ORA only if the voltage on the pin is allowed to be  $\geq 2.4$  volts for a logic one and  $\leq 0.4$  volts for a zero. If the loading on the pin does not allow this, then the data resulting from the read operation may not match the contents of ORA.

The output buffers for the PB pins are somewhat different from the PA buffers. The PB buffers are push-pull devices which are capable of sourcing 3ma at 1.5 volts. This allows for these pins to directly drive transistor circuits. To assure that the processor will read the proper data when performing a peripheral read operation, logic is provided in the peripheral B port to permit the processor to read the contents of ORB, instead of the PB pins as is the case for the PA port.

### Interval Timer

The timer section of the SY6532 contains three basic parts: preliminary divide down register, programmable 8-bit register and interrupt logic. These are illustrated in Figure 2.

The interval timer can be programmed to count up to 256 time intervals. Each time interval can be either 1T, 8T, 64T or 1024T increments, where T is the system clock period. When a full count is reached, and interrupt flag is set to a logic "1." After the interrupt flag is set the internal clock begins counting down to a maximum of -255T. Thus, after the interrupt flag is set, a Read of the timer will tell how long since the flag was set up to a maximum of 255T.

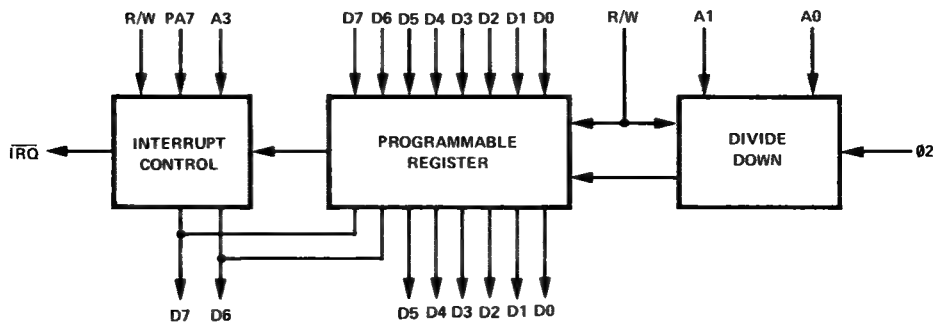
The 8-bit system Data Bus is used to transfer data to and from the Interval Timer. If a count of 52 time intervals were to be counted, the pattern 0 0 1 1 0 1 0 0 would be put on the Data Bus and written into the Interval Time register.

At the same time that data is being written to the Interval Timer, the counting intervals of 1, 8, 64, 1024T are decoded from address lines A0 and A1. During a Read or Write operation address line A3 controls the interrupt capability of  $\overline{IRQ}$ , i.e., A3 = 1 enables  $\overline{IRQ}$ , A3 = 0 disables  $\overline{IRQ}$ . In either case, when timeout occurs, bit 7 of the Interrupt Flag Register is set. This flag is cleared when the Timer register is either read from or written to by the processor. If  $\overline{IRQ}$  is enabled by A3 and an interrupt occurs  $\overline{IRQ}$  will go low. When the timer is read prior to the interrupt flag being set, the number of time intervals remaining will be read, i.e., 51, 50, 49, etc.

When the timer has counted down to 0 0 0 0 0 0 0 0 on the next count time an interrupt will occur and the counter will read 1 1 1 1 1 1 1. After interrupt, the timer register decrements at a divide by "1" rate of the system clock. If after interrupt, the timer is read and a value of 1 1 1 0 0 1 0 0 is read, the time since interrupt is 28T. The value read is in two's complement.

Value read	= 1 1 1 0 0 1 0 0
Complement	= 0 0 0 1 1 0 1 1
Add 1	= 0 0 0 1 1 1 0 0 = 28.

**Figure 2. BASIC ELEMENTS OF INTERVAL TIMER**

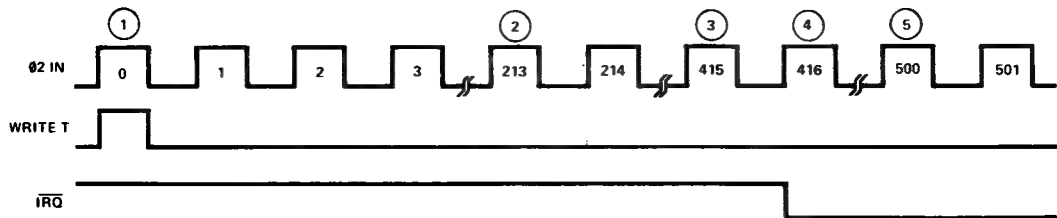


Thus, to arrive at the total elapsed time, merely do a two's complement add to the original time written into the timer. Again, assume time written as 0 0 1 1 0 1 0 0 (=52). With a divide by 8, total time to interrupt is  $(52 \times 8) + 1 = 417T$ . Total elapsed time would be  $416T + 28T = 444T$ , assuming the value read after interrupt was 1 1 1 0 0 1 0 0.

After interrupt, whenever the timer is written or read the interrupt is reset. However, the reading of the timer at the same time the interrupt occurs will not reset the interrupt flag.

Figure 3 illustrates an example of interrupt.

**Figure 3. TIMER INTERRUPT TIMING**



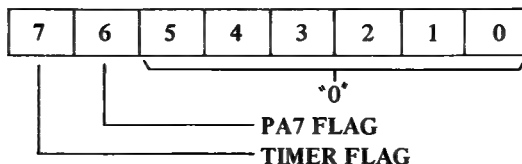
1. Data written into interval timers is  $00110100 = 52_{10}$
2. Data in Interval timer is  $00011001 = 25_{10}$   
 $52 - \frac{2^{13}}{8} - 1 = 52 - 26 - 1 = 25$
3. Data in Interval timer is  $00000000 = 0_{10}$   
 $52 - \frac{4^{15}}{8} - 1 = 52 - 51 - 1 = 0$
4. Interrupt has occurred at  $\emptyset 2$  pulse #416  
Data in Interval timer =  $11111111$
5. Data in Interval timer is  $10101100$   
two's complement is  $01010100 = 84_{10}$   
 $84 + (52 \times 8) = 500_{10}$

When reading the timer after an interrupt, A3 should be low so as to disable the  $\overline{\text{IRQ}}$  pin. This is done so as to avoid future interrupts until after another Write operation.

#### Interrupt Flag Register

The Interrupt Flag Register consists of two bits: the timer interrupt flag and the PA7 interrupt flag. When a read operation is performed on the Interrupt Flag Register, the bits are transferred to the processor on the data bus, as the diagram below, indicates.

Figure 4. INTERRUPT FLAG REGISTER



The PA7 flag is cleared when the Interrupt Flag Register is read. The timer flag is cleared when the timer register is either written or read.

#### ADDRESSING

Addressing of the SY6532 is accomplished by the 7 addressing pins, the  $\overline{\text{RS}}$  pin and the two chip select pins CS1 and  $\overline{\text{CS2}}$ . To address the RAM, CS1 must be high with  $\overline{\text{CS2}}$  and  $\overline{\text{RS}}$  low. To address the I/O and Interval timer CS1 and  $\overline{\text{RS}}$  must be high with  $\overline{\text{CS2}}$  low. As can be seen to access the chip CS1 is high and  $\overline{\text{CS2}}$  is low. To distinguish between RAM or I/O Timer the  $\overline{\text{RS}}$  pin is used. When this pin is low the RAM is addressed, when high the I/O Interval timer section is addressed. To distinguish between timer and I/O address line A2 is utilized. When A2 is high the interval timer is accessed. When A2 is low the I/O section is addressed. Table 1 illustrates the chip addressing.

#### Edge Sense Interrupt

In addition to its use as a peripheral I/O line, the PA7 pin can function as an edge sensitive input. In this mode, an active transition on PA7 will set the internal interrupt flag (bit 6 of the Interrupt Flag Register). When this occurs, and providing the PA7 interrupt is enabled, the  $\overline{\text{IRQ}}$  output will go low.

Control of the PA7 edge detecting logic is accomplished by performing a write operation to one of four addresses. The data lines for this operation are "don't care" and the addresses to be used are found in Figure 4.

The setting of the internal Interrupt flag by an active transition on PA7 is always enabled, no matter whether PA7 is set up as an input or an output.

The  $\overline{\text{RES}}$  signal disables the PA7 interrupt and sets the active transition to the negative edge-detect state. During the reset operation, the interrupt flag may be set by a negative transition. It may, therefore, be necessary to clear the flag before its normal use as an edge detecting input is enabled. This can be achieved by reading the Interrupt Flag Register, as defined by Figure 4 immediately after reset.

#### I/O Register - Timer Addressing

Table 1 illustrates the address decoding for the internal elements and timer programming. Address line A2 distinguishes I/O registers from the timer. When A2 is low and  $\overline{\text{RS}}$  is high, the I/O registers are addressed. Once the I/O registers are addressed, address lines A1 and A0 decode the desired register.

When the timer is selected A1 and A0 decode the "divide-by" matrix. This decoding is defined in Table 1. In addition, Address A3 is used to enable the interrupt flag to  $\overline{\text{IRQ}}$ .

**Table 1 ADDRESSING DECODE**

OPERATION	$\overline{RS}$	R/W	A4	A3	A2	A1	A0
Write RAM	0	0	—	—	—	—	—
Read RAM	0	1	—	—	—	—	—
Write DDRA	1	0	—	—	0	0	1
Read DDRA	1	1	—	—	0	0	1
Write DDRB	1	0	—	—	0	1	1
Read DDRB	1	1	—	—	0	1	1
Write Output Reg A	1	0	—	—	0	0	0
Read Output Reg A	1	1	—	—	0	0	0
Write Output Reg B	1	0	—	—	0	1	0
Read Output Reg B	1	1	—	—	0	1	0
Write Timer							
÷ 1T	1	0	1	(a)	1	0	0
÷ 8T	1	0	1	(a)	1	0	1
÷ 64T	1	0	1	(a)	1	1	0
÷ 1024T	1	0	1	(a)	1	1	1
Read Timer	1	1	—	(a)	1	—	0
Read Interrupt Flag	1	1	—	—	1	—	1
Write Edge Detect Control	1	0	0	—	1	(b)	(c)

NOTES: — = Don't Care, "1" = High level ( $\geq 2.4V$ ), "0" = Low level ( $\leq 0.4V$ )

(a) A3 = 0 to disable interrupt from timer to  $\overline{IRQ}$

(c) A0 = 0 for negative edge-detect

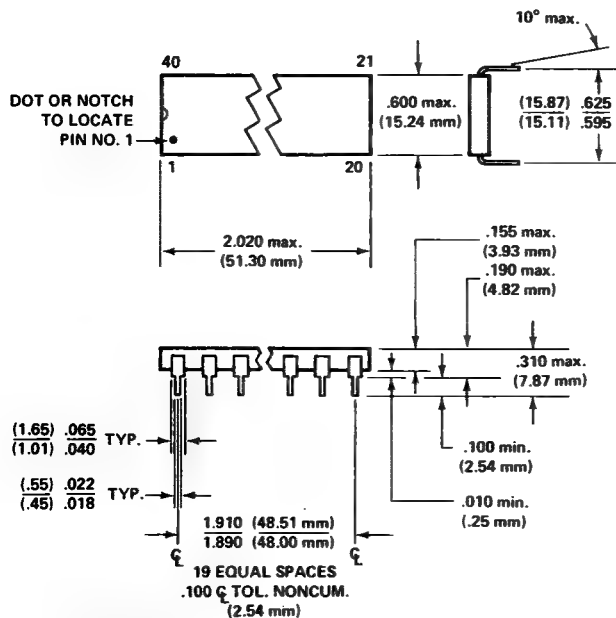
A3 = 1 to enable interrupt from timer to  $\overline{IRQ}$

A0 = 1 for positive edge-detect

(b) A1 = 0 to disable interrupt from PA7 to  $\overline{IRQ}$

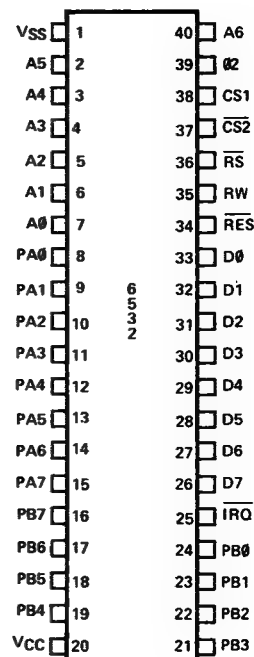
A1 = 1 to enable interrupt from PA7 to  $\overline{IRQ}$

## PACKAGE OUTLINE



NOTE: Pin No. 1 is in lower left corner when symbolization is in normal orientation

## PIN DESIGNATION





**APPENDIX J**  
**SY2114 RAM DATA SHEET**





# 1024x4 Static Random Access Memory

**SY2114**  
**MEMORY PRODUCTS**

- 300 ns Maximum Access
- Low Operating Power Dissipation  
0.1 mW/Bit
- No Clocks or Strokes Required
- Identical Cycle and Access Times
- Single +5V Supply

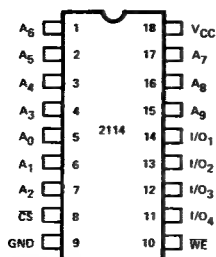
- Totally TTL Compatible:  
All Inputs, Outputs, and Power Supply
- Common Data I/O
- 400 mv Noise Immunity
- High Density 18 Pin Package

The SY2114 is a 4096-Bit static Random Access Memory organized 1024 words by 4-bits and is fabricated using Synertek's N-channel Silicon-Gate MOS technology. It is designed using fully DC stable (static) circuitry in both the memory array and the decoding and therefore requires no clock or refreshing to operate. Address setup times are not required and the data is read out nondestructively with the same polarity as the input data. Common Input/Output pins are provided to simplify design of the bus oriented systems, and can drive 2 TTL loads.

The SY2114 is designed for memory applications where high performance, low cost, large bit storage, and simple interfacing are important design objectives. It is totally TTL compatible in all respects: inputs, outputs, and the single +5V supply. A separate Chip Select ( $\overline{CS}$ ) input allows easy selection of an individual device when outputs are or-tied.

The SY2114 is packaged in an 18-pin DIP for the highest possible density and is fabricated with N-channel, Ion Implanted, Silicon-Gate technology — a technology providing excellent performance characteristics as well as protection against contamination allowing the use of low cost packaging techniques.

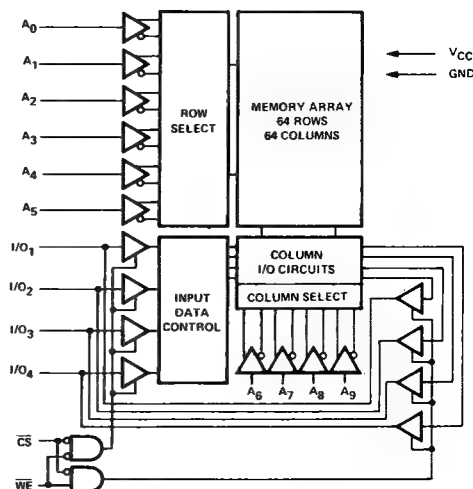
## PIN CONFIGURATION



## ORDERING INFORMATION

Order Number	Package Type	Access Time	Supply Current (Max)	Temperature Range
SYC2114	Ceramic	450nsec	100mamp	0°C to 70°C
SYP2114	Molded	450nsec	100mamp	0°C to 70°C
SYC2114-3	Ceramic	300nsec	100mamp	0°C to 70°C
SYP2114-3	Molded	300nsec	100mamp	0°C to 70°C
SYC2114L	Ceramic	450nsec	70mamp	0°C to 70°C
SYP2114L	Molded	450nsec	70mamp	0°C to 70°C
SYC2114L-3	Ceramic	300nsec	70mamp	0°C to 70°C
SYP2114L-3	Molded	300nsec	70mamp	0°C to 70°C

## BLOCK DIAGRAM



Synertek®

• P.O. Box 552

• Santa Clara, CA 95052

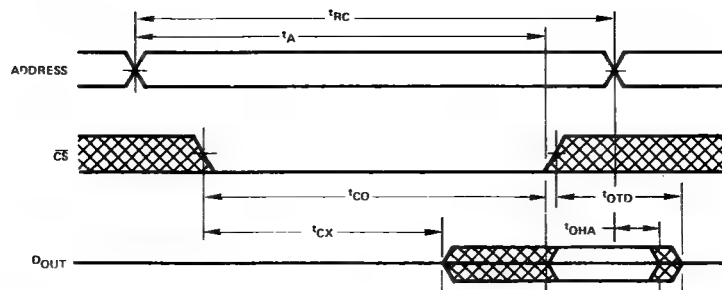
• Telephone (408) 984-8900

• TWX: 910-338-0135

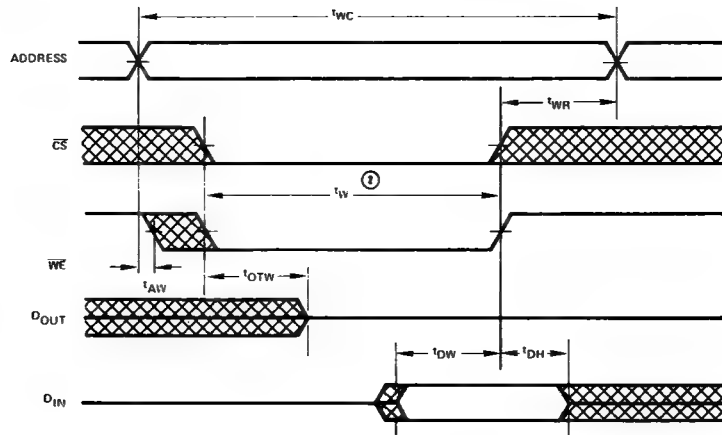


## TIMING DIAGRAMS

### Read Cycle ①



### Write Cycle



#### NOTES:

①  $\overline{WE}$  is high for a Read Cycle

②  $t_W$  is measured from the latter of  $\overline{CS}$  or  $\overline{WE}$  going low to the earlier of  $\overline{CS}$  or  $\overline{WE}$  going high.

## DATA STORAGE

When  $\overline{WE}$  is high, the data input buffers are inhibited to prevent erroneous data from being written into the array. As long as  $\overline{WE}$  remains high, the data stored cannot be affected by the Address, Chip Select, or Data I/O logic levels or timing transitions.

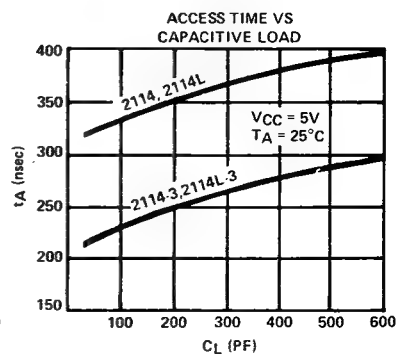
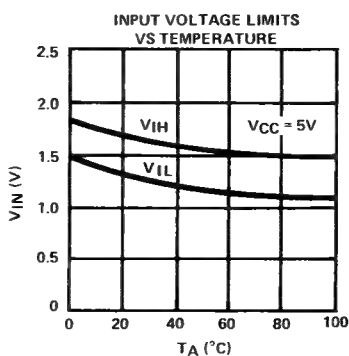
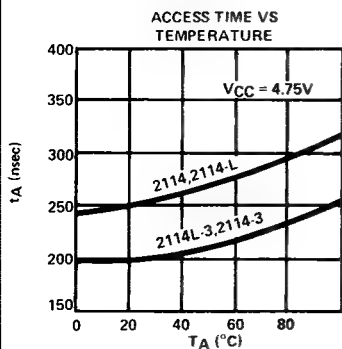
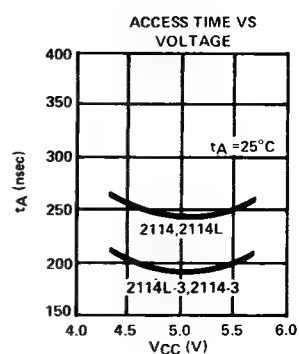
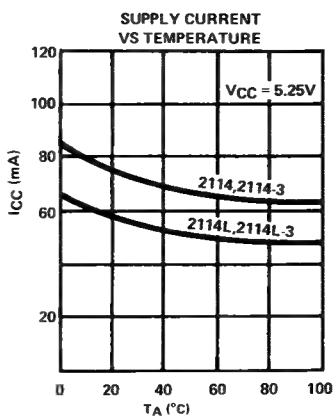
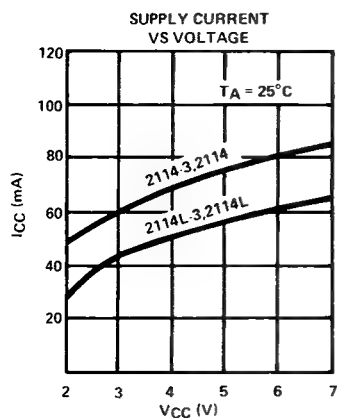
Data storage also cannot be affected by  $\overline{WE}$ , Addresses, or the I/O ports as long as  $\overline{CS}$  is high. Either  $\overline{CS}$  or  $\overline{WE}$  or both can prevent extraneous writing due to signal transitions.

Data within the array can only be changed during Write time — defined as the overlap of  $\overline{CS}$  low and

$\overline{WE}$  low. The addresses must be properly established during the entire Write time plus  $t_{WR}$ .

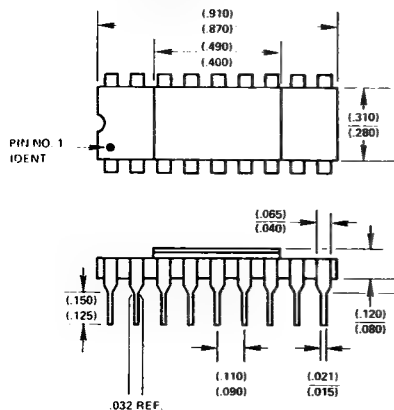
Internal delays are such that address decoding propagates ahead of data inputs and therefore no address setup time is required. If the Write time precedes the addresses, the data in previously addressed locations, or some other location, may be changed. Addresses must remain stable for the entire Write cycle but the Data Inputs may change. The data which is stable for  $t_{DW}$  at the end of the Write time will be written into the addressed location.

## TYPICAL CHARACTERISTICS

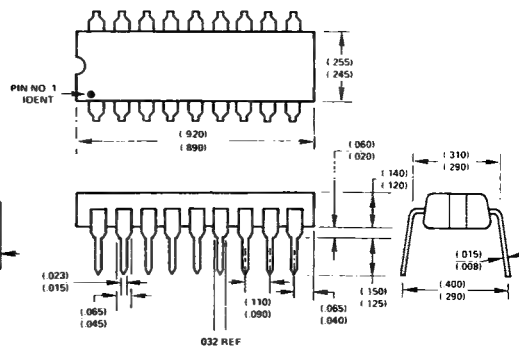


## PACKAGE DIAGRAM

## CERAMIC PACKAGE



## MOLDED PACKAGE



LINE #	LOC	CODE	LINE
0002	0000		;
0003	0000		*****
0004	0000		***** COPYRIGHT 1978 SYNERTEK SYSTEMS CORPORATION
0005	0000		*****
0006	0000		*=\$A600 ;SYS RAM (ECHOED AT TOP OF MEM)
0007	A600	SCPBUF	*=**+\$20 ;SCOPE BUFFER LAST 32 CHRS
0008	A620	RAM	=* ;DEFAULT BLK FILLS STARTING HERE
0009	A620	JTABLE	*=**+\$10 ; SJUMPS - ABS ADDR, LO HI ORDER
0010	A630	SCR0	*=**+1 ;RAM SCRATCH LOCS 0-F
0011	A631	SCR1	*=**+1
0012	A632	SCR2	*=**+1
0013	A633	SCR3	*=**+1
0014	A634	SCR4	*=**+1
0015	A635	SCR5	*=**+1
0016	A636	SCR6	*=**+1
0017	A637	SCR7	*=**+1
0018	A638	SCR8	*=**+1
0019	A639	SCR9	*=**+1
0020	A63A	SCRA	*=**+1
0021	A63B	SCRB	*=**+1
0022	A63C	SCRC	*=**+1
0023	A63D	SCRD	*=**+1
0024	A63E	RC	=SCRD
0025	A63E	SCRE	*=**+1
0026	A63F	SCRF	*=**+1
0027	A640	DISBUF	*=**+5 ;DISPLAY BUFFER
0028	A645	RDIG	*=**+1 ;RIGHT MOST DIGIT OF DISPLAY
0029	A646		*=**+3 ;NOT USED
0030	A649	PARNR	*=**+1 ;NUMBER OF PARMS RECEIVED
0031	A64A		;
0032	A64A		; 3 16 BIT PARMS, LO HI ORDER
0033	A64A		; PASSED TO EXECUTE BLOCKS
0034	A64A		;
0035	A64A	P3L	*=**+1
0036	A64B	P3H	*=**+1
0037	A64C	P2L	*=**+1
0038	A64D	P2H	*=**+1
0039	A64E	P1L	*=**+1
0040	A64F	P1H	*=**+1
0041	A650	PADBIT	*=**+1 ;PAD BITS FOR CARRIAGE RETURN
0042	A651	SDBYT	*=**+1 ;SPEED BYTE FOR TERMINAL I/O
0043	A652	ERCNT	*=**+1 ; ERROR COUNT (MAX \$FF)
0044	A653		; BIT 7 ECHO /NO ECHO, BIT 6 = CTL 0 TOGGLE SW
0045	A653	TECHO	*=**+1 ;TERMINAL ECHO FLAG
0046	A654		; BIT7 =CRT IN, 8 =TTY IN, 5 = TTY OUT, 4 = CRT OUT
0047	A654	TOUTFL	*=**+1 ;OUTPUT FLAGS
0048	A655	KSHFL	*=**+1 ;KEYBOARD SHIFT FLAG
0049	A656	TV	*=**+1 ;TRACE VELOCITY (0=SINGLE STEP)
0050	A657	LSTCOM	*=**+1 ;STORE LAST MONITOR COMMAND
0051	A658	MAXRC	*=**+1 ;MAX REC LENGTH FOR MEM DUMP
0052	A659		;
0053	A659		; USER REG'S FOLLOW
0054	A659		;
0055	A659	PCLR	*=**+1 ;PROG CTR
0056	A65A	PCHR	*=**+1

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LINE #	LOC	CODE	LINE	
0057	A65B		SR	*=#+1 ;STACK
0058	A65C		FR	*=#+1 ;FLAGS
0059	A65D		AR	*=#+1 ;AREG
0060	A65E		XR	*=#+1 ;XREG
0061	A65F		YR	*=#+1 ;YREG
0062	A660			;
0063	A660			; I/O VECTORS FOLLOW
0064	A660			;
0065	A660		INVEC	*=#+3 ;IN CHAR
0066	A663		OUTVEC	*=#+3 ;OUT CHAR
0067	A666		INSVEC	*=#+3 ;IN STATUS
0068	A669			*=#+3 ;NOT USED
0069	A66C		URCVEC	*=#+3 ;UNRECOGNIZED CMD/ERROR VECTOR
0070	A66F		SCNVEC	*=#+3 ;SCAN ON-BOARD DISPLAY
0071	A672			;
0072	A672			; TRACE, INTERRUPT VECTORS
0073	A672			;
0074	A672		EXEVEC	*=#+2 ; EXEC CMD ALTERNATE INVEC
0075	A674		TRCVEC	*=#+2 ;TRACE
0076	A676		UBRKVC	*=#+2 ;USER BRK AFTER MONITOR
0077	A678		UBRKV	=UBRKVC
0078	A678		UIRQVC	*=#+2 ;USER NON-BRK IRQ AFTER MONITOR
0079	A67A		UIRQV	=UIRQVC
0080	A67A		NMIVEC	*=#+2 ;NMI
0081	A67C		RSTVEC	*=#+2 ;RESET
0082	A67E		IRQVEC	*=#+2 ;IRQ
0083	A680			;
0084	A680			;
0085	A680			;I/O REG DEFINITIONS
0086	A680		PADA	=\$A400 ;KEYBOARD/DISPLAY
0087	A680		PBDA	=\$A402 ;DATA DIRECTION FOR SAME
0088	A680		OR3A	=AC01 ;WP, DBON, DBOFF
0089	A680		DDR3A	=OR3A+2 ;DATA DIRECTION FOR SAME
0090	A680		OR1B	=\$A000
0091	A680		DDR1B	=\$A002
0092	A680		PCR1	=\$A00C ; PQR/TAPE REMOTE
0093	A680			;
0094	A680			; MONITOR MAINLINE
0095	A680			;
0096	A680			*=\$8000
0097	8000	4C 7C 8B	MONITR	JMP MONENT ;INIT S, CLD, GET ACCESS
0098	8003	20 FF 80	WARM	JSR GETCOM ;GET COMMAND + PARMS (0-3)
0099	8006	20 4A 81		JSR DISPATCH ;DISPATCH CMD,PARMS TO EXEC BLKS
0100	8009	20 71 81		JSR ERMSG ;DISP ER MSG IF CARRY SET
0101	800C	4C 03 80		JMP WARM ;AND CONTINUE
0102	800F			;
0103	800F			; TRACE AND INTERRUPT ROUTINES
0104	800F			;
0105	800F	08	IRQBRK	PHP ;IRQ OR BRK ?
0106	8010	48		PHA
0107	8011	8A		TXA
0108	8012	48		PHA
0109	8013	BA		TSX
0110	8014	BD 04 01		LDA \$104,X ;PICK UP FLAGS
0111	8017	29 10		AND #\$10



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LINE #	LOC	CODE	LINE
0112	8019	F0 07	BEQ DETIRQ
0113	801B	68	DETBK PLA ;BRK
0114	801C	AA	TAX
0115	801D	68	PLA
0116	801E	28	PLP
0117	801F	6C F6 FF	JMP (\$FFF6)
0118	8022	68	DETIRQ PLA ;IRQ (NON BRK)
0119	8023	AA	TAX
0120	8024	68	PLA
0121	8025	28	PLP
0122	8026	6C F8 FF	JMP (\$FFF8)
0123	8029	20 86 8B	SVIRQ JSR ACCESS ;SAVE REGS AND DISPLAY CODE
0124	802C	38	SEC
0125	802D	20 64 80	JSR SAVINT
0126	8030	A9 31	LDA #'1
0127	8032	4C 53 80	JMP IDISP
0128	8035	08	USRENT PHP ;USER ENTRY
0129	8036	20 86 8B	JSR ACCESS
0130	8039	38	SEC
0131	803A	20 64 80	JSR SAVINT
0132	803D	EE 59 A6	INC PCLR
0133	8040	D0 03	BNE #+5
0134	8042	EE 5A A6	INC PCHR
0135	8045	A9 33	LDA #'3
0136	8047	4C 53 80	JMP IDISP
0137	804A	20 86 8B	SVBRK JSR ACCESS
0138	804D	18	CLC
0139	804E	20 64 80	JSR SAVINT
0140	8051	A9 30	LDA #'0
0141	8053		; INTRPT CODES ;0 = BRK
0142	8053		; 1 = IRQ
0143	8053		; 2 = NMI
0144	8053		; 3 = USER ENTRY
0145	8053	48	IDISP PHA ;OUT PC, INTRPT CODE (FROM A
0146	8054	20 D3 80	JSR DBOFF ;STOP NMIS
0147	8057	20 4D 83	JSR CRLF
0148	805A	20 37 83	JSR OPCCOM
0149	805D	68	PLA
0150	805E	20 47 8A	JSR OUTCHR
0151	8061	4C 03 80	JMP WARM
0152	8064	8D 5D A6	SAVINT STA AR ;SAVE USER REGS AFTER INTRPT
0153	8067	8E 5E A6	STX XR
0154	806A	8C 5F A6	STY YR
0155	806D	BA	TSX
0156	806E	D8	CLD
0157	806F	BD 04 01	LDA \$104,X
0158	8072	69 FF	ADC #\$FF
0159	8074	8D 59 A6	STA PCLR
0160	8077	BD 05 01	LDA \$105,X
0161	807A	69 FF	ADC #\$FF
0162	807C	8D 5A A6	STA PCHR
0163	807F	BD 03 01	LDA \$103,X
0164	8082	8D 5C A6	STA FR
0165	8085	BD 02 01	LDA \$102,X
0166	8088	9D 05 01	STA \$105,X

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LINE	#	LOC	CODE	LINE		
0167	808B	BD 01 01		LDA	\$101,X	
0168	808E	9D 04 01		STA	\$104,X	
0169	8091	E8		INX		
0170	8092	E8		INX		
0171	8093	E8		INX		
0172	8094	9A		TXS		
0173	8095	E8		INX		
0174	8096	E8		INX		
0175	8097	8E 5B A6		STX	SR	
0176	809A	60		RTS		
0177	809B	20 86 8B	SUNMI	JSR	ACCESS	#TRACE IF TV NE 0
0178	809E	38		SEC		
0179	809F	20 64 80		JSR	SAVINT	
0180	80A2	20 D3 80		JSR	DBOFF	#STOP NMI'S
0181	80A5	AD 56 A6		LDA	TV	
0182	80A8	D0 05		BNE	TVNZ	
0183	80AA	A9 32		LDA	#'2	
0184	80AC	4C 53 80		JMP	IDISP	
0185	80AF	20 37 83	TUNZ	JSR	OPCCOM	#TRACE WITH DELAY
0186	80B2	AD 5D A6		LDA	AR	
0187	80B5	20 4A 83		JSR	OBCRLF	#DISPLAY ACC
0188	80B8	20 5A 83		JSR	DELAY	
0189	80BB	90 10		BCC	TRACON	#STOP IF KEY ENTERED
0190	80BD	4C 03 80		JMP	WARM	
0191	80C0	20 86 8B	TRCOFF	JSR	ACCESS	#DISABLE NMIS
0192	80C3	38		SEC		
0193	80C4	20 64 80		JSR	SAVINT	
0194	80C7	20 D3 80		JSR	DBOFF	
0195	80CA	6C 74 A6		JMP	(TRCVEC) AND GO TO SPECIAL TRACE	
0196	80CD	20 E4 80	TRACON	JSR	DBON	#ENABLE NMI'S
0197	80D0	4C FA 83		JMP	GOIENT	#AND RESUME
0198	80D3	AD 01 AC	DBOFF	LDA	OR3A	#PULSE DEBUG OFF
0199	80D6	29 DF		AND	##DF	
0200	80D8	09 10		ORA	##10	
0201	80DA	8D 01 AC		STA	OR3A	
0202	80DD	AD 03 AC		LDA	DDR3A	
0203	80E0	09 30		ORA	##30	
0204	80E2	D0 0F		BNE	DBNEW-3	#RELEASE FLIP FLOP SO KEY WORKS
0205	80E4	AD 01 AC	DBON	LDA	OR3A	#PULSE DEBUG ON
0206	80E7	29 EF		AND	##EF	
0207	80E9	09 20		ORA	##20	
0208	80EB	8D 01 AC		STA	OR3A	
0209	80EE	AD 03 AC		LDA	DDR3A	
0210	80F1	09 30		ORA	##30	
0211	80F3	8D 03 AC		STA	DDR3A	
0212	80F6	AD 03 AC	DBNEW	LDA	DDR3A	#RELEASE FLIP FLOP
0213	80F9	29 CF		AND	##CF	
0214	80FB	8D 03 AC		STA	DDR3A	
0215	80FE	60		RTS		
0216	80FF					
0217	80FF					
0218	80FF					
0219	80FF	20 4D 83	GETCOM	JSR	CRLF	
0220	8102	A9 2E		LDA	#'	#PROMPT
0221	8104	20 47 8A		JSR	OUTCHR	

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LINE #	LOC	CODE	LINE
0222	8107	20 1B 8A	GETC1 JSR INCHR
0223	810A	F0 F3	BEQ GETCOM ;CARRIAGE RETURN?
0224	810C	C9 7F	CMP ##7F ;DELETE?
0225	810E	F0 F7	BEQ GETC1
0226	8110	C9 00	CMP #0 ;NULL?
0227	8112	F0 F3	BEQ GETC1
0228	8114		; L,S,U NEED TO BE HASHED 2 BYTES TO ONE
0229	8114	C9 53	CMP #'S
0230	8116	F0 1B	BEQ HASHUS
0231	8118	C9 55	CMP #'U
0232	811A	F0 17	BEQ HASHUS
0233	811C	C9 4C	CMP #'L
0234	811E	F0 0F	BEQ HASHL
0235	8120	8D 57 A6	STOCOM STA LSTCOM
0236	8123	20 42 83	JSR SPACE
0237	8126	20 08 82	JSR PSHOVE ;ZERO PARMS
0238	8129	20 08 82	JSR PSHOVE
0239	812C	4C 20 82	JMP FARM ;AND GO GET PARMS
0240	812F	A9 01	HASHL LDA ##01 ;HASH LOAD CMDS TO ONE BYTE
0241	8131	10 02	BPL HASHUS+2
0242	8133	0A	HASHUS ASL A ;HASH 'USER' CMDS TO ONE BYTE A
0243	8134	0A	ASL A ;U0 = \$14 THRU U7 = \$1B
0244	8135	8D 57 A6	STA LSTCOM
0245	8138	20 1B 8A	JSR INCHR ;GET SECOND
0246	813B	F0 C2	BEQ GETCOM ;CARRIAGE RETURN?
0247	813D	18	CLC
0248	813E	6D 57 A6	ADC LSTCOM
0249	8141	29 0F	AND ##0F
0250	8143	09 10	ORA ##10
0251	8145	10 D9	BPL STOCOM
0252	8147	20 1B 8A	JSR INCHR
0253	814A		; DISPATCH TO EXEC BLK 0FARM, 1FARM, 2FARM, OR 3FARM
0254	814A		; DISPATCH CMP ##0D ;C/R IF OK ELSE URCVEC
0255	814A		; BNE HIPN
0256	814A	C9 0D	DISPAT CMP ##0D ;C/R IF OK ELSE URCVEC
0257	814C	D0 20	BNE HIPN
0258	814E	AD 57 A6	LDA LSTCOM
0259	8151	AE 49 A6	LDX FARMR
0260	8154	D0 03	BNE M12
0261	8156	4C 95 83	JMP BZPARM ;0 PARM BLOCK
0262	8159	E0 01	M12 CPX ##01
0263	815B	D0 03	BNE M13
0264	815D	4C DA 84	JMP B1PARM ;1 PARM BLOCK
0265	8160	E0 02	M13 CPX ##02
0266	8162	D0 03	BNE M14
0267	8164	4C 19 86	JMP B2PARM ;2 PARM BLOCK
0268	8167	E0 03	M14 CPX ##03
0269	8169	D0 03	BNE HIPN
0270	816B	4C 14 87	JMP B3PARM ;3 PARM BLOCK
0271	816E	6C 6D A6	HIPN JMP (URCVEC+1) ;ELSE UNREC COMMAND VECTOR
0272	8171		; ERMSG - PRINT ACC IN HEX IF CARRY SET
0273	8171		; ERMSG BCC M15
0274	8171		; PHA
0275	8171	90 44	
0276	8173	48	

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LINE	#	LOC	CODE	LINE
0277	8174	20	4D 83	JSR CRLF
0278	8177	A9	45	LDA #'E
0279	8179	20	47 8A	JSR OUTCHR
0280	817C	A9	52	LDA #'R
0281	817E	20	47 8A	JSR OUTCHR
0282	8181	20	42 83	JSR SPACE
0283	8184		68	PLA
0284	8185	4C	FA 82	JMP OUTBYT
0285	8188			;
0286	8188			; SAVER - SAVE ALL REG'S + FLAGS ON STACK
0287	8188			; RETURN WITH F,A,X,Y UNCHANGED
0288	8188			; STACK HAS FLAGS,A,X,Y PUSHED
0289	8188	08		SAVER PHP ;
0290	8189	48		PHA ;
0291	818A	48		PHA ;
0292	818B	48		PHA
0293	818C	08		PHP
0294	818D	48		PHA
0295	818E	8A		TXA
0296	818F	48		PHA
0297	8190	BA		TSX
0298	8191	BD	09 01	LDA \$0109,X
0299	8194	9D	05 01	STA \$0105,X
0300	8197	BD	07 01	LDA \$0107,X
0301	819A	9D	09 01	STA \$0109,X
0302	819D	BD	01 01	LDA \$0101,X
0303	81A0	9D	07 01	STA \$0107,X
0304	81A3	BD	08 01	LDA \$0108,X
0305	81A6	9D	04 01	STA \$0104,X
0306	81A9	BD	06 01	LDA \$0106,X
0307	81AC	9D	08 01	STA \$0108,X
0308	81AF	98		TYA
0309	81B0	9D	06 01	STA \$0106,X
0310	81B3	68		PLA
0311	81B4	AA		TAX
0312	81B5	68		PLA
0313	81B6	28		PLP
0314	81B7	60		M15 RTS
0315	81B8			; RESTORE EXCEPT A,F
0316	81B8	08		RESXAF PHP
0317	81B9	BA		TSX
0318	81BA	9D	04 01	STA \$0104,X
0319	81BD	28		PLP
0320	81BE			; RESTORE EXCEPT F
0321	81BE	08		RESXF PHP
0322	81BF	68		PLA
0323	81C0	BA		TSX
0324	81C1	9D	04 01	STA \$0104,X
0325	81C4			; RESTORE ALL 100%
0326	81C4	68		RESALL PLA
0327	81C5	AB		TAY
0328	81C6	68		PLA
0329	81C7	AA		TAX
0330	81C8	68		PLA
0331	81C9	28		PLP

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LINE #	LOC	CODE	LINE
0332	81CA	60	RTS
0333	81CB		#
0334	81CB		# MONITOR UTILITIES
0335	81CB		#
0336	81CB	C9 20	ADVCK CMP ##20 #SPACE?
0337	81CD	F0 02	BEQ M1
0338	81CF	C9 3E	CMP #'> #FWD ARROW?
0339	81D1	38	M1 SEC
0340	81D2	60	RTS
0341	81D3	20 FA 82	OBCMIN JSR OUTBYT #OUT BYTE, OUT COMMA, IN BYTE
0342	81D6	20 3A 83	COMINB JSR COMMA #OUT, COMMA, IN BYTE
0343	81D9	20 1B 8A	INBYTE JSR INCHR
0344	81DC	20 75 82	JSR ASCNIB
0345	81DF	B0 14	BCS OUT4
0346	81E1	0A	ASL A
0347	81E2	0A	ASL A
0348	81E3	0A	ASL A
0349	81E4	0A	ASL A
0350	81E5	8D 33 A6	STA SCR3
0351	81E8	20 1B 8A	JSR INCHR
0352	81EB	20 75 82	JSR ASCNIB
0353	81EE	B0 11	BCS OUT2
0354	81F0	0D 33 A6	ORA SCR3
0355	81F3	1B	GOOD CLC
0356	81F4	60	RTS
0357	81F5	C9 27	OUT4 CMP ##27 #SINGLE TIC ?
0358	81F7	D0 05	BNE OUT1
0359	81F9	20 1B 8A	JSR INCHR
0360	81FC	D0 F5	BNE GOOD #CARRIAGE RETURN?
0361	81FE	B8	OUT1 CLV
0362	81FF	50 03	BVC CRCHK
0363	8201	2C 04 82	OUT2 BIT CRCHK
0364	8204	C9 0D	CRCHK CMP ##0D #CHECK FOR C/R
0365	8206	38	SEC
0366	8207	60	RTS
0367	8208	A2 10	PSHOVE LDX ##10 #PUSH PARMS DOWN
0368	820A	0E 4A A6	PRM10 ASL P3L
0369	820D	2E 4B A6	ROL P3H
0370	8210	2E 4C A6	ROL P2L
0371	8213	2E 4D A6	ROL P2H
0372	8216	2E 4E A6	ROL P1L
0373	8219	2E 4F A6	ROL P1H
0374	821C	CA	DEX
0375	821D	D0 EB	BNE PRM10
0376	821F	60	RTS
0377	8220	20 88 81	PARM JSR SAVER #GET PARMS - RETURN ON C/R OR ERR
0378	8223	A9 00	LDA #0
0379	8225	8D 49 A6	STA PARNR
0380	8228	8D 33 A6	STA SCR3
0381	822B	20 08 82	PM1 JSR PSHOVE
0382	822E	20 1B 8A	PARFIL JSR INCHR
0383	8231	C9 2C	CMP #', #VALID DELIMITERS - ,
0384	8233	F0 04	BEQ M21
0385	8235	C9 2D	CMP #'-
0386	8237	D0 11	BNE M22

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LINE #	LOC	CODE	LINE		
0387	8239	A2 FF	M21	LDX #\$FF	
0388	823B	8E 33 A6		STX SCR3	
0389	823E	EE 49 A6		INC PARNR	
0390	8241	AE 49 A6		LDX PARNR	
0391	8244	E0 03		CPX #\$03	
0392	8246	D0 E3		BNE PM1	
0393	8248	F0 1D		BEQ M24	
0394	824A	20 75 82	M22	JSR ASCNIB	
0395	824D	B0 18		BCS M24	
0396	824F	A2 04		LDX #4	
0397	8251	0E 4A A6	M23	ASL P3L	
0398	8254	2E 4B A6		ROL P3H	
0399	8257	CA		DEX	
0400	8258	D0 F7		BNE M23	
0401	825A	0D 4A A6		ORA P3L	
0402	825D	8D 4A A6		STA P3L	
0403	8260	A9 FF		LDA #\$FF	
0404	8262	8D 33 A6		STA SCR3	
0405	8265	D0 C7		BNE PARFIL	
0406	8267	2C 33 A6	M24	BIT SCR3	
0407	826A	F0 03		BEQ M25	
0408	826C	EE 49 A6		INC PARNR	
0409	826F	C9 0D	M2	CMP #\$0D	
0410	8271	18		CLC	
0411	8272	4C B8 B1		JMP RESXAF	
0412	8275	C9 0D	ASCNIB	CMP #\$0D	;C/R?
0413	8277	F0 19		BEQ M29	
0414	8279	C9 30		CMP #10	
0415	827B	90 0C		BCC M26	
0416	827D	C9 47		CMP #16	
0417	827F	B0 08		BCS M26	
0418	8281	C9 41		CMP #1A	
0419	8283	B0 08		BCS M27	
0420	8285	C9 3A		CMP #1A	
0421	8287	90 06		BCC M28	
0422	8289	C9 30	M26	CMP #10	
0423	828B	38		SEC	;CARRY SET -> NON-HEX
0424	828C	60		RTS	
0425	828D	E9 37	M27	SBC #\$37	
0426	828F	29 0F	M28	AND #\$0F	
0427	8291	18		CLC	
0428	8292	60	M29	RTS	
0429	8293	EE 4A A6	INCP3	INC P3L	;INCREMENT P3 (16 BITS)
0430	8296	D0 03		BNE *+5	
0431	8298	EE 4B A6		INC P3H	
0432	829B	40		RTS	
0433	829C	AE 4D A6	P2SCR	LDX P2H	;MOVE P2 TO FE,FF
0434	829F	86 FF		STX \$FF	
0435	82A1	AE 4C A6		LDX P2L	
0436	82A4	86 FE		STX \$FE	
0437	82A6	60		RTS	
0438	82A7	AE 4B A6	P3SCR	LDX P3H	;MOVE P3 TO FE,FF
0439	82AA	86 FF		STX \$FF	
0440	82AC	AE 4A A6		LDX P3L	
0441	82AF	86 FE		STX \$FE	

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LINE #	LOC	CODE	LINE		
0442	82B1	60		RTS	
0443	82B2	E6 FE	INCCMP	INC \$FE	#INCREM FE,FE, COMPARE TO P3
0444	82B4	D0 14		BNE COMPAR	
0445	82B6	E6 FF		INC \$FF	
0446	82B8	D0 10	WRAP	BNE COMPAR	#TEST FOR WRAP AROUND
0447	82BA	2C BD 82		BIT EXWRAP	
0448	82BD	60	EXWRAP	RTS	
0449	82BE	A5 FE	DECCMP	LDA \$FE	#DECREM FE,FE AND COMPARE TO P3
0450	82C0	D0 06		BNE M32	
0451	82C2	A5 FF		LDA \$FF	
0452	82C4	F0 F2		BEQ WRAP	
0453	82C6	C6 FF		DEC \$FF	
0454	82C8	C6 FE	M32	DEC \$FE	
0455	82CA	20 88 81	COMPAR	JSR SAVER	#COMPARE FE,FE TO P3
0456	82CD	A5 FF		LDA \$FF	
0457	82CF	CD 4B A6		CMP P3H	
0458	82D2	D0 05		BNE EXITCP	
0459	82D4	A5 FE		LDA \$FE	
0460	82D6	CD 4A A6		CMP P3L	
0461	82D9	B8	EXITCP	CLV	
0462	82DA	4C BE 81		JMP RESXF	
0463	82DD	08	CHKSAD	PHP	#16 BIT CKSUM IN SCR6,7
0464	82DE	48		PHA	
0465	82DF	18		CLC	
0466	82E0	6D 36 A6		ADC SCR6	
0467	82E3	8D 36 A6		STA SCR6	
0468	82E6	90 03		BCC M33	
0469	82E8	EE 37 A6		INC SCR7	
0470	82EB	68	M33	PLA	
0471	82EC	28		PLP	
0472	82ED	60		RTS	
0473	82EE	AD 59 A6	OUTPC	LDA PCLR	#OUTPUT PC
0474	82F1	AE 5A A6		LDX PCHR	
0475	82F4	48	OUTXAH	PHA	
0476	82F5	8A		TXA	
0477	82F6	20 FA 82		JSR OUTBYT	
0478	82F9	68		PLA	
0479	82FA	48	OUTBYT	PHA	#OUTPUT 2-HEX DIGS FROM A
0480	82FB	48		PHA	
0481	82FC	4A		LSR A	
0482	82FD	4A		LSR A	
0483	82FE	4A		LSR A	
0484	82FF	4A		LSR A	
0485	8300	20 44 8A		JSR NBASOC	
0486	8303	68		PLA	
0487	8304	20 44 8A		JSR NBASOC	
0488	8307	68		PLA	
0489	8308	60		RTS	
0490	8309	29 0F	NIBASC	AND #\$0F	#NIBBLE IN A TO ASCII IN A
0491	830B	C9 0A		CMP #\$0A	
0492	830D	B0 04		BCC NIBALF	
0493	830F	69 30		ADC #\$30	
0494	8311	90 02		BCC EXITNB	
0495	8313	69 36	NIBALF	ADC #\$36	
0496	8315	60	EXITNB	RTS	

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LINE	#	LOC	CODE	LINE	
0497	8316	20	4D 83	CRLFSZ	JSR CRLF ;PRINT CRLF, FF, FE
0498	8319	A6	FF	OUTSZ	LDX \$FF
0499	831B	A5	FE		LDA \$FE
0500	831D	4C	F4 82		JMP OUTXAH
0501	8320	A9	3F	OUTQM	LDA #'?
0502	8322	4C	47 8A		JMP OUTCHR
0503	8325	20	3A 83	OCMCK	JSR COMMA ;OUT COMMA, CKSUM LO
0504	8328	AD	36 A6		LDA SCR6
0505	832B	4C	FA 82		JMP OUTBYT
0506	832E	A9	00	ZERCK	LDA #0 ;INIT CHECKSUM
0507	8330	8D	36 A6		STA SCR6
0508	8333	8D	37 A6		STA SCR7
0509	8336	60			RTS
0510	8337	20	EE 82	OPCCOM	JSR OUTPC ;PC OUT, COMMA OUT
0511	833A	48		COMMA	PHA ;COMMA OUT
0512	833B	A9	2C		LDA #',
0513	833D	D0	06		BNE SPCP3
0514	833F	20	42 83	SPC2	JSR SPACE ;2 SPACES OUT
0515	8342	48		SPACE	PHA ;1 SPACE OUT
0516	8343	A9	20		LDA ##20
0517	8345	20	47 8A	SPCP3	JSR OUTCHR
0518	8348	68			PLA
0519	8349	60			RTS
0520	834A	20	FA 82	OBCRLF	JSR OUTBYT ;BYTE OUT, CRLF OUT
0521	834D	48		CRLF	PHA
0522	834E	A9	0D		LDA ##0D
0523	8350	20	47 8A		JSR OUTCHR
0524	8353	A9	0A		LDA ##0A ;LINE FEED
0525	8355	20	47 8A		JSR OUTCHR
0526	8358	68			PLA
0527	8359	60			RTS
0528	835A	AE	56 A6	DELAY	LDX TV ;DELAY DEPENDS ON TV
0529	835D	20	88 81	DL1	JSR SAVER
0530	8360	A9	FF		LDA ##FF
0531	8362	8D	39 A6		STA SCR9
0532	8365	8D	38 A6		STA SCR8
0533	8368	0E	38 A6	DLY1	ASL SCR8
0534	836B	2E	39 A6		ROL SCR9
0535	836E	CA			DEX
0536	836F	D0	F7		BNE DLY1
0537	8371	20	03 89	DLY2	JSR IJSCNV ;SCAN DISPLAY
0538	8374	20	86 83		JSR INSTAT ;SEE IF KEY DOWN
0539	8377	B0	0A		BCS DLY0
0540	8379	EE	38 A6		INC SCR8
0541	837C	D0	03		BNE *+5
0542	837E	EE	39 A6		INC SCR9
0543	8381	D0	EE		BNE DLY2
0544	8383	4C	BE 81	DLY0	JMP RESXF
0545	8386				INSTAT - SEE IF KEY DOWN, RESULT IN CARRY
0546	8386				KEYSTAT, TSTAT RETURN IMMEDIATELY W/STATUS
0547	8386				INSTAT WAITS FOR RELEASE
0548	8386	20	92 83	INSTAT	JSR INJISV
0549	8389	90	06		BCC INST2
0550	838B	20	92 83	INST1	JSR INJISV
0551	838E	B0	FB		BCS INST1



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LINE	#	LOC	CODE	LINE
0552	8390	38		SEC
0553	8391	60		INST2 RTS
0554	8392	6C 67 A6		INJISV JMP (INSVEC+1)
0555	8395			;
0556	8395			;
0557	8395			; *** EXECUTE BLOCKS BEGIN HERE
0558	8395			;
0559	8395			BZPARM=*
0560	8395			; ZERO PARM COMMANDS
0561	8395			;
0562	8395	C9 52		REGZ CMP #'R ;DISP REGISTERS
0563	8397	D0 5A		BNE GOZ ;PC,S,F,A,X,Y
0564	8399	20 4D 83		RGBACK JSR CRLF
0565	839C	A9 50		LDA #'P
0566	839E	20 47 8A		JSR OUTCHR
0567	83A1	20 42 83		JSR SPACE
0568	83A4	20 EE 82		JSR OUTPC
0569	83A7	20 D6 81		JSR COMINB
0570	83AA	B0 13		BCS NH3
0571	83AC	8D 34 A6		STA SCR4
0572	83AF	20 D9 81		JSR INBYTE
0573	83B2	B0 0B		BCS NH3
0574	83B4	8D 59 A6		STA PCLR
0575	83B7	AD 34 A6		LDA SCR4
0576	83BA	8D 5A A6		STA PCHR
0577	83BD	90 09		BCC M34
0578	83BF	D0 02	NH3	BNE NOTCR
0579	83C1	18	EXITRG	CLC
0580	83C2	60	EXRGP1	RTS
0581	83C3	20 CB 81	NOTCR	JSR ADVCK
0582	83C6	D0 FA		BNE EXRGP1
0583	83C8	A0 00	M34	LDY #0
0584	83CA	C8	M35	INY
0585	83CB	C0 06		CPY #6
0586	83CD	F0 CA		BEQ RGBACK
0587	83CF	20 4D 83		JSR CRLF
0588	83D2	A9 52	NXTRG	LDA #'R
0589	83D4	20 47 8A		JSR OUTCHR
0590	83D7	98		TYA
0591	83D8	20 44 8A		JSR NBASOC
0592	83DB	20 3F 83		JSR SPC2
0593	83DE	B9 5A A6		LDA PCHR,Y
0594	83E1	20 D3 81		JSR OBCMIN
0595	83E4	B0 05		BCS M36
0596	83E6	99 5A A6		STA PCHR,Y
0597	83E9	90 DF		BCC M35
0598	83EB	F0 D4	M36	BEQ EXITRG
0599	83ED	20 CB 81		JSR ADVCK
0600	83F0	F0 D8		BEQ M35
0601	83F2	60		RTS
0602	83F3	C9 47	GOZ	CMP ##47
0603	83F5	D0 20		BNE LPZB
0604	83F7	20 4D 83	GO2	JSR CRLF
0605	83FA	20 9C 8B	GO1ENT	JSR NACCES ;WRITE PROT MONITR RAM
0606	83FD	AE 5B A6		LDX SR ;RESTORE REGS

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LINE	* LOC	CODE	LINE
0607	8400	9A	TXS
0608	8401	AD 5A A6	LDA PCHR
0609	8404	48	PHA
0610	8405	AD 59 A6	LDA PCLR
0611	8408	48	PHA
0612	8409	AD 5C A6	LDA FR
0613	840C	48	PHA
0614	840D	AC 5F A6	LDY YR
0615	8410	AE 5E A6	LDX XR
0616	8413	AD 5D A6	LDA AR
0617	8416	40	RTI
0618	8417	C9 11	LPZB CMP ##11
0619	8419	F0 03	BEQ *+5
0620	841B	4C A7 84	JMP DEPZ
0621	841E	20 88 81	JSR SAVER
0622	8421	20 4D 83	JSR CRLF
0623	8424	A9 00	LDA #0
0624	8426	8D 52 A6	STA ERCNT
0625	8429	20 2E 83	LPZ JSR ZERCK
0626	842C	20 1B 8A	LP1 JSR INCHR
0627	842F	C9 3B	CMP ##3B
0628	8431	D0 F9	BNE LP1
0629	8433	20 A1 84	JSR LDBYTE
0630	8436	B0 56	BCS TAPERR
0631	8438	D0 09	BNE NUREC
0632	843A	AD 52 A6	LDA ERCNT
0633	843D	F0 01	BEQ *+3
0634	843F	38	EXITLP SEC
0635	8440	4C BE 81	JMP RESXF
0636	8443	8D 3D A6	NUREC STA RC
0637	8446	20 A1 84	JSR LDBYTE
0638	8449	B0 43	BCS TAPERR
0639	844B	85 FF	STA \$FF
0640	844D	20 A1 84	JSR LDBYTE
0641	8450	B0 D7	BCS LPZ
0642	8452	85 FE	STA \$FE
0643	8454	20 A1 84	MORED JSR LDBYTE
0644	8457	B0 35	BCS TAPERR
0645	8459	A0 00	LDY #0
0646	845B	91 FE	STA (\$FE),Y
0647	845D	D1 FE	CMP (\$FE),Y
0648	845F	F0 0C	BEQ LPGD
0649	8461	AD 52 A6	LDA ERCNT
0650	8464	29 0F	AND ##0F
0651	8466	C9 0F	CMP ##0F
0652	8468	F0 03	BEQ *+5
0653	846A	EE 52 A6	INC ERCNT
0654	846D	20 B2 82	LPGD JSR INCCMP
0655	8470	CE 3D A6	DEC RC
0656	8473	D0 DF	BNE MORED
0657	8475	20 D9 81	JSR INBYTE
0658	8478	B0 14	BCS TAPERR
0659	847A	CD 37 A6	CMP SCR7
0660	847D	D0 0C	BNE BADDY
0661	847F	20 D9 81	JSR INBYTE

LOAD PAPER TAPE

ERRORS ?

LINE #	LOC	CODE	LINE
0662	8482	B0 0A	BCS TAPERR
0663	8484	CD 36 A6	CMF SCR6
0664	8487	F0 A0	BEQ LPZ
0665	8489	D0 03	BNE TAPERR
0666	848B	20 D9 81	BADDY JSR INBYTE
0667	848E	AD 52 A6	TAPERR LDA ERCNT
0668	8491	29 F0	AND ##F0
0669	8493	C9 F0	CMF ##F0
0670	8495	F0 92	BEQ LPZ
0671	8497	AD 52 A6	LDA ERCNT
0672	849A	69 10	ADC ##10
0673	849C	8D 52 A6	STA ERCNT
0674	849F	D0 88	BNE LPZ
0675	84A1	20 D9 81	LDBYTE JSR INBYTE
0676	84A4	4C DD 82	JMP CHKSAD
0677	84A7	C9 44	DEPZ CMP #'D
0678	84A9	D0 03	BNE MEMZ
0679	84AB	4C E1 84	JMP NEWLN
0680	84AE	C9 4D	MEMZ CMP #'M
0681	84B0	D0 03	BNE VERZ
0682	84B2	4C 17 85	JMP NEWLOC
0683	84B5	C9 56	VERZ CMP #'V
0684	84B7	D0 0D	BNE L1ZB
0685	84B9	A5 FE	LDA #FE
0686	84BB	8D 4A A6	STA P3L
0687	84BE	A5 FF	LDA #FF
0688	84C0	8D 4B A6	STA P3H
0689	84C3	4C 9A 85	JMP VER1+4
0690	84C6	C9 12	L1ZB CMP ##12
0691	84C8	D0 05	BNE L2ZB
0692	84CA	A0 00	LDY #0
0693	84CC	4C 78 8C	L1J JMP LENTRY
0694	84CF	C9 13	L2ZB CMP ##13
0695	84D1	D0 04	BNE EZPARM
0696	84D3	A0 80	LDY ##80
0697	84D5	D0 F5	BNE L1J
0698	84D7	6C 6D A6	EZPARM JMP (URCVEC+1)
0699	84DA		B1PARM=*
0700	84DA		;
0701	84DA		; 1 PARAMETER COMMAND EXEC BLOCKS
0702	84DA		;
0703	84DA	C9 44	DEP1 CMP #'D
0704	84DC	D0 32	BNE MEM1
0705	84DE	20 A7 82	JSR P3SCR
0706	84E1	20 16 83	NEWLN JSR CRLFSZ
0707	84E4	A0 00	LDY #0
0708	84E6	A2 08	LDX ##8
0709	84E8	20 42 83	DEPBYT JSR SPACE
0710	84EB	20 D9 81	JSR INBYTE
0711	84EE	B0 11	BCS NH41
0712	84F0	91 FE	STA (\$FE),Y
0713	84F2	D1 FE	CMF (\$FE),Y
0714	84F4	F0 03	BEQ DEPN
0715	84F6	20 20 83	JSR OUTQM
0716	84F9	20 B2 82	DEPN JSR INCCMP

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LINE	#	LOC	CODE	LINE	
0717	84FC	CA		DEX	
0718	84FD	D0 E9		BNE DEPBYT	
0719	84FF	F0 E0		BEQ NEWLN	
0720	8501	F0 0B	NH41	BEQ DEPEC	
0721	8503	C9 20		CMP ##20	;SPACE = FWD
0722	8505	D0 4C		BNE DEPES	
0723	8507	70 F0		BVS DEPN	
0724	8509	20 42 83		JSR SPACE	
0725	850C	10 EB		BPL DEPN	
0726	850E	18	DEPEC	CLC	
0727	850F	60		RTS	
0728	8510	C9 4D	MEM1	CMP #'M	;MEMORY, 1 PARM
0729	8512	D0 65		BNE G01	
0730	8514	20 A7 82		JSR P3SCR	
0731	8517	20 16 83	NEWLOC	JSR CRLF SZ	
0732	851A	20 3A 83		JSR COMMA	
0733	851D	A0 00		LDY #0	
0734	851F	B1 FE		LDA (\$FE),Y	
0735	8521	20 D3 81		JSR OBCMIN	
0736	8524	B0 11		BCS NH42	
0737	8526	A0 00		LDY #0	
0738	8528	91 FE		STA (\$FE),Y	
0739	852A	D1 FE		CMP (\$FE),Y	;VERIFY MEM
0740	852C	F0 03		BEQ NXTLOC	
0741	852E	20 20 83		JSR OUTQM	;TYPE ? AND CONTINUE
0742	8531	20 B2 82	NXTLOC	JSR INCCMP	
0743	8534	18		CLC	
0744	8535	90 E0		BCC NEWLOC	
0745	8537	F0 3E	NH42	BEQ EXITM1	
0746	8539	50 04		BVC #+6	
0747	853B	C9 3C		CMP #'<	
0748	853D	F0 D8		BEQ NEWLOC	
0749	853F	C9 20		CMP ##20	;SPACE ?
0750	8541	F0 EE		BEQ NXTLOC	
0751	8543	C9 3E		CMP #'>	
0752	8545	F0 EA		BEQ NXTLOC	
0753	8547	C9 2B		CMP #'+	
0754	8549	F0 10		BEQ LOCP8	
0755	854B	C9 3C		CMP #'<	
0756	854D	F0 06		BEQ PRVLOC	
0757	854F	C9 2D		CMP #'-	
0758	8551	F0 16		BEQ LOCM8	
0759	8553	38	DEPES	SEC	
0760	8554	60		RTS	
0761	8555	20 BE 82	PRVLOC	JSR DECCMP	;BACK ONE BYT
0762	8558	18		CLC	
0763	8559	90 BC		BCC NEWLOC	
0764	855B	A5 FE	LOCP8	LDA \$FE	;GO FWD 8 BYTES
0765	855D	18		CLC	
0766	855E	69 08		ADC #\$08	
0767	8560	85 FE		STA \$FE	
0768	8562	90 02		BCC M42	
0769	8564	E6 FF		INC \$FF	
0770	8566	18	M42	CLC	
0771	8567	90 AE		BCC NEWLOC	

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LINE #	LOC	CODE	LINE		
0772	8569	A5 FE	LOCMB	LDA \$FE	; GO BACKWD 8 BYTE
0773	856B	38		SEC	
0774	856C	E9 08		SBC ##08	
0775	856E	85 FE		STA \$FE	
0776	8570	B0 02		BCS M43	
0777	8572	C6 FF		DEC \$FF	
0778	8574	18	M43	CLC	
0779	8575	90 A0		BCC NEWLOC	
0780	8577	18	EXITM1	CLC	
0781	8578	60		RTS	
0782	8579	C9 47	G01	CMF #'G	; GO+ 1 PARM (RTRN ADDR ON STK)
0783	857B	D0 19		BNE VER1	... PARM IS ADDR TO GO TO
0784	857D	20 4D 83		JSR CRLF	
0785	8580	20 9C 8B		JSR NACCES	;WRITE PROT MONITR RAM
0786	8583	A2 FF		LDX ##FF	;PUSH RETURN ADDR
0787	8585	9A		TXS	
0788	8586	A9 7F		LDA ##7F	
0789	8588	48		PHA	
0790	8589	A9 FF		LDA ##FF	
0791	858B	48		PHA	
0792	858C	AD 4B A6		LDA P3H	
0793	858F	48		PHA	
0794	8590	AD 4A A6		LDA P3L	
0795	8593	4C 08 84		JMP NR10	
0796	8596	C9 56	VER1	CMF #'V	;VERIFY, 1 PARM (8 BYTES, CKSUM)
0797	8598	D0 1A		BNE JUMP1	
0798	859A	AD 4A A6		LDA P3L	
0799	859D	8D 4C A6		STA P2L	
0800	85A0	18		CLC	
0801	85A1	69 07		ADC ##07	
0802	85A3	8D 4A A6		STA P3L	
0803	85A6	AD 4B A6		LDA P3H	
0804	85A9	8D 4D A6		STA P2H	
0805	85AC	69 00		ADC #0	
0806	85AE	8D 4B A6		STA P3H	
0807	85B1	4C 40 86		JMP VER2+4	
0808	85B4	C9 4A	JUMP1	CMF #'J	;JUMP (JUMP TABLE IN SYS RAM)
0809	85B6	D0 1F		BNE L11B	
0810	85B8	AD 4A A6		LDA P3L	
0811	85BB	C9 08		CMF ##8	; 0-7 ONLY VALID
0812	85BD	B0 26		BCS JUM2	
0813	85BF	20 9C 8B		JSR NACCES	;WRITE PROT SYS RAM
0814	85C2	0A		ASL A	
0815	85C3	A8		TAY	
0816	85C4	A2 FF		LDX ##FF	;INIT STK PTR
0817	85C6	9A		TXS	
0818	85C7	A9 7F		LDA ##7F	;PUSH COLD RETURN
0819	85C9	48		PHA	
0820	85CA	A9 FF		LDA ##FF	
0821	85CC	48		PHA	
0822	85CD	B9 21 A6		LDA JTABLE+1,Y	;GET ADDR FROM TABLE
0823	85D0	48		PHA	;PUSH ON STACK
0824	85D1	B9 20 A6		LDA JTABLE,Y	
0825	85D4	4C 08 84		JMP NR10	;LOAD UP USER REG'S AND RTI
0826	85D7	C9 12	L11B	CMF ##12	;LOAD KIM FMT, 1 PARM

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LINE	#	LOC	CODE	LINE	
0827	85D9	D0 14		BNE L21B	
0828	85DB	A0 00		LDY #0	#MODE KIM
0829	85DD	AD 4A A6	L11C	LDA P3L	
0830	85E0	C9 FF		CMP ##FF	# ID MUST NOT BE FF
0831	85E2	D0 02		BNE *+4	
0832	85E4	38		SEC	
0833	85E5	60	JUM2	RTS	
0834	85E6	20 08 82		JSR PSHOVE	#FIX PARM POSITION
0835	85E9	20 08 82	L11D	JSR PSHOVE	
0836	85EC	4C 78 8C		JMP LENTRY	
0837	85EF	C9 13	L21B	CMP ##13	#LOAD TAPE, HS FMT, 1 PARM
0838	85F1	D0 04		BNE WPR1B	
0839	85F3	A0 80		LDY ##80	#MODE = HS
0840	85F5	D0 E6		BNE L11C	
0841	85F7	C9 57	WPR1B	CMP #'W	#WRITE PROT USER RAM
0842	85F9	D0 1B		BNE E1PARM	
0843	85FB	AD 4A A6		LDA P3L	# FIRST DIG IS 1K ABOVE 0,
0844	85FE	29 11		AND ##11	# SECOND IS 2K ABOVE 0
0845	8600	C9 08		CMP #8	# THIRD IS 3K ABOVE 0.
0846	8602	2A		ROL A	
0847	8603	4E 4B A6		LSR P3H	
0848	8606	2A		ROL A	
0849	8607	0A		ASL A	
0850	8608	29 0F		AND ##0F	
0851	860A	49 0F		EOR ##0F	#0 IS PROTECT
0852	860C	8D 01 AC		STA OR3A	
0853	860F	A9 0F		LDA ##0F	
0854	8611	8D 03 AC		STA DDR3A	
0855	8614	18		CLC	
0856	8615	60		RTS	
0857	8616	4C 27 88		E1PARM JMP CALC3	
0858	8619			B2PARM=*	
0859	8619			#	
0860	8619			# 2 PARAMETER EXEC BLOCKS	
0861	8619			#	
0862	8619	C9 10	STD2	CMP ##10	#STORE DOUBLE BYTE
0863	861B	D0 12		BNE MEM2	
0864	861D	20 A7 82		JSR P35CR	
0865	8620	AD 4D A6		LDA P2H	
0866	8623	A0 01		LDY #1	
0867	8625	91 FE		STA (\$FE),Y	
0868	8627	88		DEY	
0869	8628	AD 4C A6		LDA P2L	
0870	862B	91 FE		STA (\$FE),Y	
0871	862D	18		CLC	
0872	862E	60		RTS	
0873	862F	C9 4D	MEM2	CMP #'M	#CONTINUE MEM SEARCH W/OLD PTR
0874	8631	D0 09		BNE VER2	
0875	8633	AD 4C A6		LDA P2L	
0876	8636	8D 4E A6		STA P1L	
0877	8639	4C 08 88		JMP MEM3C	
0878	863C	C9 56	VER2	CMP #'V	#VERIFY MEM W/CHKSUMS, 2 PARM
0879	863E	D0 48		BNE L12B	
0880	8640	20 9C 82		JSR P25CR	
0881	8643	20 2E 83		JSR ZERCK	

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LINE #	LOC	CODE	LINE	
0882	8646	20 16 83	VADDR	JSR CRLFSZ
0883	8649	A2 08		LDX #8
0884	864B	20 42 83	V2	JSR SPACE
0885	864E	A0 00		LDY #0
0886	8650	B1 FE		LDA (\$FE),Y
0887	8652	20 DD 82		JSR CHKSAD
0888	8655	20 FA 82		JSR OUTBYT
0889	8658	20 B2 82		JSR INCCMP
0890	865B	70 10		BVS V1
0891	865D	F0 02		BEQ #+4
0892	865F	B0 0C		BCS V1
0893	8661	CA		DEX
0894	8662	D0 E7		BNE V2
0895	8664	20 25 83	VOCK	JSR OCMCK
0896	8667	20 86 83		JSR INSTAT
0897	866A	90 DA		BCC VADDR
0898	866C	60		RTS
0899	866D	20 BE 82	V1	JSR DECCMP
0900	8670	E0 08		CPX #8
0901	8672	F0 03		BEQ #+5
0902	8674	E8		INX
0903	8675	10 F6		BPL V1
0904	8677	20 25 83		JSR OCMCK
0905	867A	20 4D 83		JSR CRLF
0906	867D	20 42 83		JSR SPACE
0907	8680	AE 37 A6		LDX SCR7
0908	8683	20 F4 82		JSR OUTXAH
0909	8686	18		CLC
0910	8687	60		RTS
0911	8688	C9 12	L12B	CMP ##12
0912	868A	D0 0C		BNE SP2B
0913	868C	AD 4C A6	L12C	LDA P2L
0914	868F	C9 FF		CMP ##FF
0915	8691	D0 F4		BNE L12B-1
0916	8693	A0 00		LDY #0
0917	8695	4C E9 85		JMP L11D
0918	8698	C9 1C	SP2B	CMP ##1C
0919	869A	D0 75		BNE E2PARM
0920	869C	18		CLC
0921	869D	20 88 81		JSR SAVER
0922	86A0	20 9C 82		JSR P2SCR
0923	86A3	20 FA 86	SP2C	JSR DIFFZ
0924	86A6	B0 03		BCS SP2D
0925	86A8	4C C4 81	SPEXIT	JMP RESALL
0926	86AB	20 4D 83	SP2D	JSR CRLF
0927	86AE	CD 58 A6		CMP MAXRC
0928	86B1	90 05		BCC SP2E
0929	86B3	AD 58 A6		LDA MAXRC
0930	86B6	B0 02		BCS SP2F
0931	86B8	69 01	SP2E	ADC #1
0932	86BA	8D 3D A6	SP2F	STA RC
0933	86BD	A9 3B		LDA ##3B
0934	86BF	20 47 8A		JSR OUTCHR
0935	86C2	AD 3D A6		LDA RC
0936	86C5	20 F4 86		JSR SVBYTE

#LOAD KIM FMT TAPE, 2 PARMS

#ID MUST BE FF

#ERR

#MODE = HS

#SAVE PAPER TAPE, 2 PARMS

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LINE #	LOC	CODE	LINE
0937	86C8	A5 FF	LDA \$FF
0938	86CA	20 F4 86	JSR SVBYTE
0939	86CD	A5 FE	LDA \$FE
0940	86CF	20 F4 86	JSR SVBYTE
0941	86D2	A0 00	MORED2 LDY ##00
0942	86D4	B1 FE	LDA (\$FE),Y
0943	86D6	20 F4 86	JSR SVBYTE
0944	86D9	20 86 83	JSR INSTAT
0945	86DC	B0 CA	BCS SPEXIT
0946	86DE	20 B2 82	JSR INCCMP
0947	86E1	70 C5	BVS SPEXIT
0948	86E3	CE 3D A6	DEC RC
0949	86E6	D0 EA	BNE MORED2
0950	86E8	AE 37 A6	LDX SCR7
0951	86EB	AD 36 A6	LDA SCR6
0952	86EE	20 F4 82	JSR OUTXAH
0953	86F1	18	CLC
0954	86F2	90 AF	BCC SP2C
0955	86F4	20 DD 82	SVBYTE JSR CHKSAD
0956	86F7	4C FA 82	JMP OUTBYT
0957	86FA	20 2E 83	DIFFZ JSR ZERCK
0958	86FD	AD 4A A6	DIFFL LDA P3L
0959	8700	38	SEC
0960	8701	E5 FE	SBC \$FE
0961	8703	48	PHA
0962	8704	AD 4B A6	LDA P3H
0963	8707	E5 FF	SBC \$FF
0964	8709	F0 04	BEQ DIFF1
0965	870B	68	PLA
0966	870C	A9 FF	LDA ##FF
0967	870E	60	RTS
0968	870F	68	DIFF1 PLA
0969	8710	60	DIFFL2 RTS
0970	8711	4C 27 88	E2PARM JMP CALC3
0971	8714		B3PARM=*
0972	8714		;
0973	8714		; 3 PARAMETER COMMAND EXECUTE BLOCKS
0974	8714		;
0975	8714	C9 46	FILL3 CMP #'F
0976	8716	D0 21	BNE BLK3
0977	8718	20 9C 82	JSR P2SCR
0978	871B	A9 00	LDA #0
0979	871D	8D 52 A6	STA ERCNT
0980	8720	AD 4E A6	LDA P3L
0981	8723	A0 00	F1 LDY #0
0982	8725	91 FE	STA (\$FE),Y
0983	8727	D1 FE	CMP (\$FE),Y
0984	8729	F0 03	BEQ F3
0985	872B	20 C1 87	JSR BRIT
0986	872E	20 B2 82	F3 JSR INCCMP
0987	8731	70 7C	BVS B1
0988	8733	F0 EE	BEQ F1
0989	8735	90 EC	BCC F1
0990	8737	B0 76	F2 BCS B1
0991	8739	C9 42	BLK3 CMP #'B

#STOP IF KEY DEPRESSED

#MAY BE CALC OR EXEC

#FILL MEM

#ZERO ERROR COUNT

#VERIFY

#INC ERCNT (UP TO FF)

;(ALWAYS)

#BLOCK MOVE (OVERLAP OK)



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LINE	#	LOC	CODE	LINE
0992	873B	F0 03		BEQ *+5
0993	873D	4C CD 87		JMP S13B
0994	8740	A9 00		LDA #0
0995	8742	8D 52 A6		STA ERCNT
0996	8745	20 9C 82		JSR P2SCR
0997	8748	AD 4E A6		LDA P1L
0998	874B	85 FC		STA \$FC
0999	874D	AD 4F A6		LDA P1H
1000	8750	85 FD		STA \$FD
1001	8752	C5 FF		CMP \$FF
1002	8754	D0 06		BNE *+8
1003	8756	A5 FC		LDA \$FC
1004	8758	C5 FE		CMP \$FE
1005	875A	F0 53		BEQ B1
1006	875C	B0 14		BCS B2
1007	875E	20 B7 87	BLP	JSR BMOVE
1008	8761	E6 FC		INC \$FC
1009	8763	D0 02		BNE *+4
1010	8765	E6 FD		INC \$FD
1011	8767	20 B2 82		JSR INCCMP
1012	876A	70 43		BVS B1
1013	876C	F0 F0		BEQ BLP
1014	876E	90 EE		BCC BLP
1015	8770	B0 3D		BCS B1
1016	8772	A5 FC	B2	LDA \$FC
1017	8774	18		CLC
1018	8775	6D 4A A6		ADC P3L
1019	8778	85 FC		STA \$FC
1020	877A	A5 FD		LDA \$FD
1021	877C	6D 4B A6		ADC P3H
1022	877F	85 FD		STA \$FD
1023	8781	38		SEC
1024	8782	A5 FC		LDA \$FC
1025	8784	E5 FE		SBC \$FE
1026	8786	85 FC		STA \$FC
1027	8788	A5 FD		LDA \$FD
1028	878A	E5 FF		SBC \$FF
1029	878C	85 FD		STA \$FD
1030	878E	20 A7 82		JSR P3SCR
1031	8791	AD 4C A6		LDA P2L
1032	8794	8D 4A A6		STA P3L
1033	8797	AD 4D A6		LDA P2H
1034	879A	8D 4B A6		STA P3H
1035	879D	20 B7 87	BLP1	JSR BMOVE
1036	87A0	A5 FC		LDA \$FC
1037	87A2	D0 02		BNE *+4
1038	87A4	C6 FD		DEC \$FD
1039	87A6	C6 FC		DEC \$FC
1040	87A8	20 BE 82		JSR DECCMP
1041	87AB	70 02		BVS B1
1042	87AD	B0 EE		BCS BLP1
1043	87AF	AD 52 A6	B1	LDA ERCNT
1044	87B2	38		SEC
1045	87B3	D0 01		BNE *+3
1046	87B5	18		CLC

#WHICH DIRECTION TO MOVE?

#16 BITS EQUAL THEN FINISHED

#MOVE DEC'NG

#MOVE INC'NG

#CALC VALS FOR MOVE DEC'NG

#MOVE DEC'NG

#FINISHED, TEST ERCNT

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LINE #	LOC	CODE	LINE	
1047	87B6	60	RTS	
1048	87B7	A0 00	BMOVE LDY #0	#MOVE 1 BYTE + VER
1049	87B9	B1 FE	LDA (\$FE),Y	
1050	87BB	91 FC	STA (\$FC),Y	
1051	87BD	D1 FC	CMP (\$FC),Y	
1052	87BF	F0 0B	BEQ BRT	
1053	87C1	AC 52 A6	BRTT LDY ERCNT	#INC ERCNT, DONT PASS FF
1054	87C4	C0 FF	CPY \$FF	
1055	87C6	F0 04	BEQ *+6	
1056	87C8	C8	INY	
1057	87C9	8C 52 A6	STY ERCNT	
1058	87CC	60	BRT RTS	
1059	87CD	C9 1D	S13B CMP \$1D	#SAVE KIM FMT TAPE, 3 PARMS
1060	87CF	D0 15	BNE S23B	
1061	87D1	A0 00	LDY \$0	#MODE KIM
1062	87D3	AD 4E A6	S13C LDA P1L	
1063	87D6	D0 02	BNE *+4	#ID MUST NOT 0
1064	87D8	38	SEC	
1065	87D9	60	RTS	
1066	87DA	C9 FF	CMP \$FF	#ID MUST NOT = FF
1067	87DC	D0 02	BNE *+4	
1068	87DE	38	S1NG SEC	
1069	87DF	60	RTS	
1070	87E0	20 93 82	JSR INCP3	#USE END ADDR + 1
1071	87E3	4C 87 8E	JMP SENTRY	
1072	87E6	C9 1E	S23B CMP \$1E	#SAVE HS FMT TAPE, 3 PARMS
1073	87E8	D0 04	BNE L23P	
1074	87EA	A0 80	LDY \$80	#MODE = HS
1075	87EC	D0 E5	BNE S13C	#(ALWAYS)
1076	87EE	C9 13	L23P CMP \$13	#LOAD HS, 3 PARMS
1077	87F0	D0 0F	BNE MEM3	
1078	87F2	AD 4E A6	LDA P1L	
1079	87F5	C9 FF	CMP \$FF	#ID MUST BE FF
1080	87F7	D0 E5	BNE S1NG	#ERR RETURN
1081	87F9	20 93 82	JSR INCP3	#USE END ADDR + 1
1082	87FC	A0 80	LDY \$80	#MODE = HS
1083	87FE	4C 78 8C	JMP LENTRY	
1084	8801	C9 4D	MEM3 CMP \$'M	#MEM 3 SEARCH BYTE
1085	8803	D0 22	BNE CALC3	
1086	8805	20 9C 82	JSR P2SCR	
1087	8808	AD 4E A6	MEM3C LDA P1L	
1088	880B	A0 00	LDY #0	
1089	880D	D1 FE	CMP (\$FE),Y	
1090	880F	F0 0B	BEQ MEM3E	#FOUND SEARCH BYTE?
1091	8811	20 B2 82	MEM3D JSR INCCMP	#NO, INC BUFFER ADDR
1092	8814	70 04	BVS MEM3EX	#WRAP AROUND?
1093	8816	F0 F0	BEQ MEM3C	
1094	8818	90 EE	BCC MEM3C	
1095	881A	18	MEM3EX CLC	
1096	881B	60	RTS	#SEARCHED TO BOUND
1097	881C	20 17 85	MEM3E JSR NEWLOC	#FOUND SEARCH BYTE
1098	881F	90 05	BCC MEM3F	
1099	8821	C9 47	CMP \$'G	#ENTERED G?
1100	8823	F0 EC	BEQ MEM3D	
1101	8825	38	SEC	

LINE #	LOC	CODE	LINE
1102	8826	60	MEM3F RTS
1103	8827	C9 43	CALC3 CMP #'C CLACULATE, 1, 2 OR 3 PARMS
1104	8829	D0 26	BNE EXE3 ;RESULT = P1+P2+P3
1105	882B	20 4D 83	C1 JSR CRLF
1106	882E	20 42 83	JSR SPACE
1107	8831	18	CLC
1108	8832	AD 4E A6	LDA P1L
1109	8835	6D 4C A6	ADC P2L
1110	8838	A8	TAY
1111	8839	AD 4F A6	LDA P1H
1112	883C	6D 4D A6	ADC P2H
1113	883F	AA	TAX
1114	8840	38	SEC
1115	8841	98	TYA
1116	8842	ED 4A A6	SBC P3L
1117	8845	A8	TAY
1118	8846	8A	TXA
1119	8847	ED 4B A6	SBC P3H
1120	884A	AA	TAX
1121	884B	98	TYA
1122	884C	20 F4 82	JSR OUTXAH
1123	884F	18	CLC
1124	8850	60	RTS
1125	8851	C9 45	EXE3 CMP #'E ;EXECUTE FROM RAM, 1-3 PARMS
1126	8853	D0 57	BNE E3PARM
1127	8855		; SEE IF VECTOR ALREADY MOVED
1128	8855	AD 62 A6	LDA INVEC+2 ;INVEC MOVED TO SCRA, SCRB
1129	8858		; HI BYTE OF EXEVEC MUST BE DIFFERENT FROM INVEC
1130	8858	CD 73 A6	CMP EXEVEC+1 ;\$FA, \$FB USED AS RAM PTR
1131	885B	F0 15	BEQ PTRIN
1132	885D	8D 3B A6	STA SCRA+1 ;SAVE INVEC IN SCRA+1
1133	8860	AD 61 A6	LDA INVEC+1
1134	8863	8D 3A A6	STA SCRA
1135	8866	AD 72 A6	LDA EXEVEC ;PUT ADDR OF RIN IN INVEC
1136	8869	8D 61 A6	STA INVEC+1
1137	886C	AD 73 A6	LDA EXEVEC+1
1138	886F	8D 62 A6	STA INVEC+2
1139	8872	AD 4B A6	PTRIN LDA P3H ;INIT RAM PTR IN \$FA, \$FB
1140	8875	85 FB	STA \$FB
1141	8877	AD 4A A6	LDA P3L
1142	887A	85 FA	STA \$FA
1143	887C	18	CLC
1144	887D	60	RTS
1145	887E	20 88 81	RIN JSR SAVER ;GET INPUT FROM RAM
1146	8881	A0 00	LDY #\$0 ;RAM PTR IN \$FA, \$FB
1147	8883	B1 FA	LDA (\$FA),Y
1148	8885	F0 12	BEQ RESTIV ;IF 00 BYTE, RESTORE INVEC
1149	8887	E6 FA	INC \$FA
1150	8889	D0 02	BNE *+4
1151	888B	E6 FB	INC \$FB
1152	888D	2C 53 A6	BIT TECHD ;ECHO CHARS IN ?
1153	8890	10 03	BPL *+5
1154	8892	20 47 8A	JSR OUTCHR
1155	8895	18	CLC
1156	8896	4C B8 81	JMP RESXAF

LINE #	LOC	CODE	LINE		
1157	8899	AD 3A A6	RESTIV	LDA SCRA	#RESTORE INVEC
1158	889C	8D 61 A6		STA INVEC+1	
1159	889F	AD 3B A6		LDA SCRA+1	
1160	88A2	8D 62 A6		STA INVEC+2	
1161	88A5	18		CLC	
1162	88A6	20 1B 8A		JSR INCHR	
1163	88A9	4C B8 B1		JMP RESXAF	
1164	88AC	6C 6D A6	E3PARM	JMP (URCVEC+1)	#... ELSE UNREC'D CMD
1165	88AF			# ***	
1166	88AF			# *** HEX KEYBOARD I/O	
1167	88AF			# ***	
1168	88AF	20 88 81	GETKEY	JSR SAVER	#FIND KEY
1169	88B2	20 CF 88		JSR GK	
1170	88B5	C9 FE		CMP #FE	
1171	88B7	D0 13		BNE EXITGK	
1172	88B9	20 CF 88		JSR GK	
1173	88BC	8A		TXA	
1174	88BD	0A		ASL A	
1175	88BE	0A		ASL A	
1176	88BF	0A		ASL A	
1177	88C0	0A		ASL A	
1178	88C1	8D 3E A6		STA SCRE	
1179	88C4	20 CF 88		JSR GK	
1180	88C7	8A		TXA	
1181	88C8	18		CLC	
1182	88C9	6D 3E A6		ADC SCRE	
1183	88CC	4C B8 81	EXITGK	JMP RESXAF	
1184	88CF	A9 00	GK	LDA #0	
1185	88D1	8D 55 A6		STA KSHFL	
1186	88D4	20 03 89	GK1	JSR IJSCNV	#SCAN KB
1187	88D7	F0 FB		BEQ GK1	
1188	88D9	20 2C 89		JSR LRNKEY	#WHAT KEY IS IT?
1189	88DC	F0 F6		BEQ GK1	
1190	88DE	48		PHA	
1191	88DF	8A		TXA	
1192	88E0	48		PHA	
1193	88E1	20 72 89		JSR BEEP	
1194	88E4	20 23 89	GK2	JSR KEYQ	
1195	88E7	D0 FB		BNE GK2	#Z=0 IF KEY DOWN
1196	88E9	20 9B 89		JSR NOBEEP	#DELAY (DEBOUNCE) W/O BEEP
1197	88EC	20 23 89		JSR KEYQ	
1198	88EF	D0 F3		BNE GK2	
1199	88F1	68		PLA	
1200	88F2	AA		TAX	
1201	88F3	68		PLA	
1202	88F4	C9 FF		CMP #FF	#IF SHIFT, SET FLAG, + GET NEXT KEY
1203	88F6	D0 07		BNE EXITG	
1204	88F8	A9 19		LDA #19	
1205	88FA	8D 55 A6		STA KSHFL	
1206	88FD	D0 D5		BNE GK1	
1207	88FF	60	EXITG	RTS	
1208	8900	20 C1 89	HDOUT	JSR OUTDSP	#CHAR OUT, SCAN KB
1209	8903	6C 70 A6	IJSCNV	JMP (SCNVEC+1)	
1210	8906	A9 09	SCAND	LDA #9	#SCAN DISPLAY FROM DISBUF
1211	8908	20 A5 89		JSR CONFIG	

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LINE #	LOC	CODE	LINE	
1212	890B	A2 05		LDX #5
1213	890D	A0 00	SC1	LDY #0
1214	890F	BD 40 A6		LDA DISBUF,X
1215	8912	8C 00 A4		STY PADA
1216	8915	8E 02 A4		STX PBDA
1217	8918	8D 00 A4		STA PADA
1218	891B	A0 10		LDY ##10
1219	891D	88	SC2	DEY
1220	891E	D0 FD		BNE SC2
1221	8920	CA		DEX
1222	8921	10 EA		BPL SC1
1223	8923	20 A3 89	KEYQ	JSR KSCONF ; KEY DOWN? (YES THEN Z=0)
1224	8926	AD 00 A4		LDA PADA
1225	8929	49 7F		EOR ##7F
1226	892B	60		RTS
1227	892C	29 3F	LRNKEY	AND ##3F ; DETERMINE WHAT KEY IS DOWN
1228	892E	8D 3F A6		STA SCRF
1229	8931	A9 05		LDA ##05
1230	8933	20 A5 89		JSR CONFIG
1231	8936	AD 02 A4		LDA PBDA
1232	8939	29 07		AND ##07
1233	893B	49 07		EOR ##07
1234	893D	D0 05		BNE LK1
1235	893F	2C 00 A4		BIT PADA
1236	8942	30 1A		BMI NOKEY
1237	8944	C9 04	LK1	CMP ##04
1238	8946	90 02		BCC LK2
1239	8948	A9 03		LDA ##03
1240	894A	0A	LK2	ASL A
1241	894B	0A		ASL A
1242	894C	0A		ASL A
1243	894D	0A		ASL A
1244	894E	0A		ASL A
1245	894F	0A		ASL A
1246	8950	18		CLC
1247	8951	6D 3F A6		ADC SCRF
1248	8954	A2 19		LDX ##19
1249	8956	DD D6 8B	LK3	CMP SYM,X
1250	8959	F0 05		BEQ FOUND
1251	895B	CA		DEX
1252	895C	10 F8		BPL LK3
1253	895E	E8	NOKEY	INX
1254	895F	60		RTS
1255	8960	8A	FOUND	TXA
1256	8961	18		CLC
1257	8962	6D 55 A6		ADC KSHFL
1258	8965	AA		TAX
1259	8966	BD EF 8B		LDA ASCII,X
1260	8969	60		RTS
1261	896A	20 23 89	KYSTAT	JSR KEYQ ; KEY DOWN? RETURN IN CARRY
1262	896D	18		CLC
1263	896E	F0 01		BEQ #+3
1264	8970	38		SEC
1265	8971	60		RTS
1266	8972	20 88 81	BEEP	JSR SAVER ; DELAY (BOUNCE) W/BEEP

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LINE	#	LOC	CODE	LINE		
1267	8975	A9	0D	BEEPP3	LDA	##0D
1268	8977	20	A5 89	BEEPP5	JSR	CONFIG
1269	897A	A2	40		LDX	##40
1270	897C	A9	08	BE1	LDA	##8
1271	897E	8D	02 A4		STA	PBDA
1272	8981	20	95 89		JSR	BE2
1273	8984	A9	06		LDA	##6
1274	8986	8D	02 A4		STA	PBDA
1275	8989	20	95 89		JSR	BE2
1276	898C	CA			DEX	
1277	898D	D0	ED		BNE	BE1
1278	898F	20	A3 89		JSR	KSCONF
1279	8992	4C	C4 81		JMP	RESALL
1280	8995	A0	28	BE2	LDY	##28
1281	8997	88		BE3	DEY	
1282	8998	D0	FD		BNE	BE3
1283	899A	60			RTS	
1284	899B	20	88 81	NOBEEP	JSR	SAVER
1285	899E	A9	01		LDA	##01
1286	89A0	4C	77 89		JMP	BEEPP5
1287	89A3	A9	01	KSCONF	LDA	##1
1288	89A5	20	88 81	CONFIG	JSR	SAVER
1289	89A8	A0	01		LDY	##01
1290	89AA	AA			TAX	
1291	89AB	8D	C8 8B	CON1	LDA	VALSP2,X
1292	89AE	99	02 A4		STA	PBDA,Y
1293	89B1	8D	C6 8B		LDA	VALS,X
1294	89B4	99	00 A4		STA	PADA,Y
1295	89B7	CA			DEX	
1296	89B8	88			DEY	
1297	89B9	10	F0		BPL	CON1
1298	89BB	4C	C4 81		JMP	RESALL
1299	89BE	20	AF 88	HKEY	JSR	GETKEY
1300	89C1	20	88 81	OUTDSP	JSR	SAVER
1301	89C4	29	7F		AND	##7F
1302	89C6	C9	07		CMP	##07
1303	89C8	D0	03		BNE	NBELL
1304	89CA	4C	75 89		JMP	BEEPP3
1305	89CD	20	06 8A	NBELL	JSR	TEXT
1306	89D0	C9	2C		CMP	##2C
1307	89D2	D0	0A		BNE	QUD1
1308	89D4	AD	45 A6		LDA	RDIG
1309	89D7	09	80		ORA	##80
1310	89D9	8D	45 A6		STA	RDIG
1311	89DC	D0	25		BNE	EXITOD
1312	89DE	A2	3A	QUD1	LDX	##3A
1313	89E0	8D	EE 8B	QUD2	CMP	ASCIM1,X
1314	89E3	F0	05		BEQ	GETSGS
1315	89E5	CA			DEX	
1316	89E6	D0	F8		BNE	QUD2
1317	89E8	F0	19		BEQ	EXITOD
1318	89EA	8D	28 8C	GETSGS	LDA	SEGS1,X
1319	89ED	C9	F0		CMP	##F0
1320	89EF	F0	12		BEQ	EXITOD
1321	89F1	A2	00		LDX	##0

#DURATION CONSTANT

#DELAY W/O BEEP

#CONFIGURE FOR KEYBOARD

#CONFIGURE I/O FROM TABLE VAL

#GET KEY FROM KB AND ECHO ON KB

#DISPLAY OUT

#PUSH INTO SCOPE BUFFER

#SINGLE QUOTE?

#GET CORR SEG CODE FROM TABLE

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LINE	#	LOC	CODE	LINE		
1322	89F3	4B			PHA	
1323	89F4	BD 41 A6		00D3	LDA DISBUF+1,X	#SHOVE DOWN DISPLAY BUFFER
1324	89F7	9D 40 A6			STA DISBUF,X	
1325	89FA	EB			INX	
1326	89FB	E0 05			CPX #5	
1327	89FD	D0 F5			BNE 00D3	
1328	89FF	6B			PLA	
1329	8A00	8D 45 A6			STA RDIG	
1330	8A03	4C C4 81		EXIT0D	JMP RESALL	
1331	8A06	4B		TEXT	PHA	#UPDATE SCOPE BUFFER
1332	8A07	8A			TXA	
1333	8A08	4B			PHA	
1334	8A09	A2 1E			LDX ##1E	
1335	8A0B	BD 00 A6		TXTMOV	LDA SCPBUF,X	
1336	8A0E	9D 01 A6			STA SCPBUF+1,X	
1337	8A11	CA			DEX	
1338	8A12	10 F7			BPL TXTMOV	
1339	8A14	6B			PLA	
1340	8A15	AA			TAX	
1341	8A16	6B			PLA	
1342	8A17	8D 00 A6			STA SCPBUF	
1343	8A1A	60			RTS	
1344	8A1B					
1345	8A1B				;	
1346	8A1B				****	
1347	8A1B				**** TERMINAL I/O	
1348	8A1B	20 88 81		INCHR	JSR SAVER	#INPUT CHAR
1349	8A1E	20 41 8A			JSR INJINV	
1350	8A21	29 7F			AND ##7F	
1351	8A23	C9 61			CMP ##61	
1352	8A25	90 06			BCC INRT1	
1353	8A27	C9 7B			CMP ##7B	
1354	8A29	B0 02			BCS INRT1	
1355	8A2B	29 DF			AND ##DF	
1356	8A2D	C9 0F		INRT1	CMP ##0F	#CTL 0 ?
1357	8A2F	D0 0B			BNE INRT2	
1358	8A31	AD 53 A6			LDA TECH0	
1359	8A34	49 40			EOR ##40	#TOGGLE CTL 0 BIT
1360	8A36	8D 53 A6			STA TECH0	
1361	8A39	1B			CLC	
1362	8A3A	90 E2			BCC INCHR+3	#GO GET ANOTHER CHAR
1363	8A3C	C9 0D		INRT2	CMP ##0D	#CARRIAGE RETURN?
1364	8A3E	4C B8 81			JMP RESXAF	
1365	8A41	6C 61 A6		INJINV	JMP (INVEC+1)	
1366	8A44	20 09 83		NBASOC	JSR NIBASC	
1367	8A47	20 88 81		OUTCHR	JSR SAVER	
1368	8A4A	2C 53 A6			BIT TECH0	#LOOK AT CTL 0 FLAG
1369	8A4D	70 03			BVS *+5	
1370	8A4F	20 55 8A			JSR INJOUV	
1371	8A52	4C C4 81			JMP RESALL	
1372	8A55	6C 64 A6		INJOUV	JMP (OUTVEC+1)	
1373	8A58	20 88 81		INTCHR	JSR SAVER	#IN TERMINAL CHAR
1374	8A5B	A9 00			LDA #0	
1375	8A5D	85 F9			STA \$F9	
1376	8A5F	AD 02 A4		LOOK	LDA PBDA	#FIND LEADING EDGE

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LINE #	LOC	CODE	LINE	
1377	8A62	2D 54 A6		AND TOUTFL
1378	8A65	38		SEC
1379	8A66	E9 40		SBC ##40
1380	8A68	90 F5		BCC LOOK
1381	8A6A	20 E9 8A	TIN	JSR DLYH #TERMINAL BIT
1382	8A6D	AD 02 A4		LDA PBDA
1383	8A70	2D 54 A6		AND TOUTFL
1384	8A73	38		SEC
1385	8A74	E9 40		SBC ##40 #OR BITS 6,7 (TTY,CRT)
1386	8A76	2C 53 A6		BIT TECHO #ECHO BIT?
1387	8A79	10 06		BPL DMY1
1388	8A7B	20 D4 8A		JSR OUT
1389	8A7E	4C 87 8A		JMP SAVE
1390	8A81	A0 07	DMY1	LDY #7
1391	8A83	88	TLP1	DEY
1392	8A84	D0 FD		BNE TLP1
1393	8A86	EA		NOP
1394	8A87	66 F9	SAVE	ROR \$F9
1395	8A89	20 E9 8A		JSR DLYH
1396	8A8C	48		PHA #TIMING
1397	8A8D	B5 00		LDA 0,X
1398	8A8F	68		PLA
1399	8A90	90 D8		BCC TIN
1400	8A92	20 E9 8A		JSR DLYH
1401	8A95	18		CLC
1402	8A96	20 D4 8A		JSR OUT
1403	8A99	A5 F9		LDA \$F9
1404	8A9B	49 FF		EOR ##FF
1405	8A9D	4C B8 81		JMP RESXAF
1406	8AA0	85 F9	TOUT	STA \$F9 #TERMINAL CHR OUT
1407	8AA2	20 88 81		JSR SAVER
1408	8AA5	20 E9 8A		JSR DLYH
1409	8AA8	A9 30		LDA ##30
1410	8AAA	8D 03 A4		STA PBDA+1
1411	8AAD	A5 F9		LDA \$F9
1412	8AAF	A2 0B		LDX ##0B
1413	8AB1	49 FF		EOR ##FF
1414	8AB3	38		SEC
1415	8AB4	20 D4 8A	OUTC	JSR OUT
1416	8AB7	20 E6 8A		JSR DLYF
1417	8ABA	A0 06		LDY ##06
1418	8ABC	88	PHAKE	DEY
1419	8ABD	D0 FD		BNE PHAKE
1420	8ABF	EA		NOP
1421	8AC0	4A		LSR A
1422	8AC1	CA		DEX
1423	8AC2	D0 F0		BNE OUTC
1424	8AC4	A5 F9		LDA \$F9
1425	8AC6	C9 0D		CMP ##0D
1426	8AC8	F0 04		BEQ GOPAD
1427	8ACA	C9 0A		CMP ##0A
1428	8ACC	D0 03		BNE LEAVE
1429	8ACE	20 32 8B	GOPAD	JSR PAD
1430	8AD1	4C C4 81	LEAVE	JMP RESALL
1431	8AD4	48	OUT	PHA #TERMINAL BIT OUT



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LINE	#	LOC	CODE	LINE		
1432	8AD5	AD 02 A4		LDA	PBDA	
1433	8AD8	29 0F		AND	##0F	
1434	8ADA	90 02		BCC	OUTONE	
1435	8ADC	09 30		ORA	##30	
1436	8ADE	2D 54 A6	OUTONE	AND	TOUTFL	#MASK OUTPUT
1437	8AE1	8D 02 A4		STA	PBDA	
1438	8AE4	68		PLA		
1439	8AE5	60		RTS		
1440	8AE6					
1441	8AE6	20 E9 8A	DLYF	JSR	DLYH	#DELAY FULL
1442	8AE9	08	DLYH	PHP		#DELAY HALF
1443	8AEA	48		PHA		
1444	8AEB	8A		TXA		
1445	8AEC	48		PHA		
1446	8AED	98		TYA		
1447	8AEE	AE 51 A6		LDX	SDBYT	
1448	8AF1	A0 03	DLYX	LDY	#3	
1449	8AF3	88	DLYY	DEY		
1450	8AF4	D0 FD		BNE	DLYY	
1451	8AF6	CA		DEX		
1452	8AF7	D0 F8		BNE	DLYX	
1453	8AF9	A8		TAY		
1454	8AFA	68		PLA		
1455	8AFB	AA		TAX		
1456	8AFC	68		PLA		
1457	8AFD	28		PLP		
1458	8AFE	60		RTS		
1459	8AFF	A9 00	BAUD	LDA	#0	#DETERMINE BAUD RATE ON PB7
1460	8B01	A8		TAY		
1461	8B02	AD 02 A4	SEEK	LDA	PBDA	
1462	8B05	0A		ASL	A	
1463	8B06	B0 FA		BCS	SEEK	
1464	8B08	20 27 8B	CLEAR	JSR	INK	
1465	8B0B	90 FB		BCC	CLEAR	
1466	8B0D	20 27 8B	SET	JSR	INK	
1467	8B10	B0 FB		BCS	SET	
1468	8B12	8C 51 A6		STY	SDBYT	
1469	8B15	BD 63 8C	DEAF	LDA	DECPTS,X	
1470	8B18	CD 51 A6		CMP	SDBYT	
1471	8B1B	B0 07		BCS	AGAIN	
1472	8B1D	BD 69 8C		LDA	STDVAL,X	#LOAD CLOSEST STD VALUE
1473	8B20	8D 51 A6		STA	SDBYT	
1474	8B23	60		RTS		
1475	8B24	E8	AGAIN	INX		
1476	8B25	10 EE		BPL	DEAF	
1477	8B27	C8	INK	INY		
1478	8B28	A2 1C		LDX	##10	
1479	8B2A	CA	INK1	DEX		
1480	8B2B	D0 FD		BNE	INK1	
1481	8B2D	AD 02 A4		LDA	PBDA	
1482	8B30	0A		ASL	A	
1483	8B31	60		RTS		
1484	8B32	AE 50 A6	PAD	LDX	PADBIT	#PAD CARRIAGE RETURN
1485	8B35	20 E6 8A	PAD1	JSR	DLYF	
1486	8B38	CA		DEX		

LINE	#	LOC	CODE	LINE		
1487	8B39	D0	FA		BNE	PAD1
1488	8B3B	60			RTS	
1489	8B3C	20	A3 89	TSTAT	JSR	KSCONF ;SEE IF BREAK KEY DOWN
1490	8B3F	2C	02 A4		BIT	PBDA
1491	8B42	18			CLC	
1492	8B43	10	01		BPL	*+3
1493	8B45	38			SEC	
1494	8B46	60			RTS	
1495	8B47	20	0F 87		JSR	DIFF1
1496	8B4A				; ***	
1497	8B4A				; ***	RESET - TURN OFF POR, INIT SYS RAM, ENTER MONITOR
1498	8B4A				; ***	
1499	8B4A					
1500	8B4A	A2	FF	RESET	LDX	##FF
1501	8B4C	9A			TXS	
1502	8B4D	A9	CC	POR	LDA	##CC ;INIT STACK PTR
1503	8B4F	8D	0C A0		STA	PCR1 ;DISABLE POR, TAPE OFF
1504	8B52	A9	04		LDA	#4
1505	8B54	48			PHA	
1506	8B55	28			PLP	
1507	8B56	20	86 8B		JSR	ACCESS ;INIT F, DISABLE IRQ DURING DFTXFR
1508	8B59	A2	5F	DFTXFR	LDX	##5F ;UN WRITE PROT SYS RAM
1509	8B5B	8D	A0 8F		LDA	DFTBLK,X ;INIT SYS RAM (EXCPT SCPBUF)
1510	8B5E	9D	20 A6		STA	RAM,X
1511	8B61	CA			DEX	
1512	8B62	10	F7		BPL	DFTXFR+2
1513	8B64	A9	07	NEWDEV	LDA	#7 ;CHANGE DEVC/BAUD RATE
1514	8B66	20	47 8A		JSR	OUTCHR ;BEEP
1515	8B69	20	A3 89	SWITCH	JSR	KSCONF ;KEYBOARD OR TERMINAL?
1516	8B6C	20	26 89	SWLP	JSR	KEYQ+3
1517	8B6F	D0	0B		BNE	MONENT
1518	8B71	2C	02 A4		BIT	PBDA
1519	8B74	10	F6		BPL	SWLP
1520	8B76	20	B7 8B		JSR	VECSW ;SWITCH VECTORS
1521	8B79	20	FF 8A		JSR	BAUD
1522	8B7C	A2	FF	MONENT	LDX	##FF ;MONITOR ENTRY
1523	8B7E	9A			TXS	
1524	8B7F	D8			CLD	
1525	8B80	20	86 8B		JSR	ACCESS ;UNWRITE PROT MONITOR RAM
1526	8B83	4C	03 80		JMP	WARM
1527	8B86	20	88 81	ACCESS	JSR	SAVER ;UN WRITE PROT SYS RAM
1528	8B89	AD	01 AC		LDA	OR3A
1529	8B8C	09	01		ORA	#1
1530	8B8E	8D	01 AC	ACC1	STA	OR3A
1531	8B91	AD	03 AC		LDA	DDR3A
1532	8B94	09	01		ORA	#1
1533	8B96	8D	03 AC		STA	DDR3A
1534	8B99	4C	C4 81		JMP	RESALL
1535	8B9C	20	88 81	NACCES	JSR	SAVER ;WRITE PROT SYS RAM
1536	8B9F	AD	01 AC		LDA	OR3A
1537	8BA2	29	FE		AND	##FE
1538	8BA4	18			CLC	
1539	8BA5	90	E7		BCC	ACC1
1540	8BA7	20	86 8B	TTY	JSR	ACCESS ;UN WRITE PROT RAM
1541	8BAA	A9	D5		LDA	##D5 ;110 BAUD

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LINE #	LOC	CODE	LINE
1542	8BAC	8D 51 A6	STA SDBYT
1543	8BAF	AD 54 A6	LDA TOUTFL
1544	8BB2	09 40	ORA #\$40
1545	8BB4	8D 54 A6	STA TOUTFL
1546	8BB7	20 86 8B	VECSW JSR ACCESS ;UN WRITE PROT RAM
1547	8BBA	A2 08	LDX #\$8
1548	8BBC	BD 6F 8C	SWLP2 LDA TRMTBL,X
1549	8BBF	9D 60 A6	STA INVEC,X
1550	8BC2	CA	DEX
1551	8BC3	10 F7	BPL SWLP2
1552	8BC5	60	RTS
1553	8BC6		;
1554	8BC6		***
1555	8BC6		*** TABLES (I/O CONFIGURATIONS, KEY CODES, ASCII CODES)
1556	8BC6		***
1557	8BC6	00	VALS .BYT \$00,\$80,\$08,\$37 ;KB SENSE, A=1
1557	8BC7	80	
1557	8BC8	08	
1557	8BC9	37	
1558	8BCA	00	.BYT \$00,\$7F,\$00,\$30 ;KB LRN, A=5
1558	8BCB	7F	
1558	8BCC	00	
1558	8BCD	30	
1559	8BCE	00	.BYT \$00,\$FF,\$00,\$3F ;SCAN DSP, A=9
1559	8BCF	FF	
1559	8BD0	00	
1559	8BD1	3F	
1560	8BD2	00	.BYT \$00,\$00,\$07,\$3F ;BEEP, A=D
1560	8BD3	00	
1560	8BD4	07	
1560	8BD5	3F	
1561	8BD6		VALSP2 =VALS+2
1562	8BD6		SYM =* ;KEY CODES RETURNED BY LRNKEY
1563	8BD6		TABLE=*
1564	8BD6	01	.BYT \$01 ;0/U0
1565	8BD7	41	.BYT \$41 ;1/U1
1566	8BD8	81	.BYT \$81 ;2/U2
1567	8BD9	C1	.BYT \$C1 ;3/U3
1568	8BDA	02	.BYT \$02 ;4/U4
1569	8BDB	42	.BYT \$42 ;5/U5
1570	8BDC	82	.BYT \$82 ;6/U6
1571	8BDD	C2	.BYT \$C2 ;7/U7
1572	8BDE	04	.BYT \$04 ;8/JMP
1573	8BDF	44	.BYT \$44 ;9/VER
1574	8BE0	84	.BYT \$84 ;A/ASCII
1575	8BE1	C4	.BYT \$C4 ;B/BLK MOV
1576	8BE2	08	.BYT \$08 ;C/CALC
1577	8BE3	48	.BYT \$48 ;D/DEP
1578	8BE4	88	.BYT \$88 ;E/EXEC
1579	8BE5	C8	.BYT \$C8 ;F/FILL
1580	8BE6	10	.BYT \$10 ;CR/SD
1581	8BE7	50	.BYT \$50 ;-/+
1582	8BE8	90	.BYT \$90 ;>/<
1583	8BE9	D0	.BYT \$D0 ;SHIFT
1584	8BEA	20	.BYT \$20 ;GO/LP

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LINE #	LOC	CODE	LINE	
1585	8BEB	60	.BYT \$60	#REG/SP
1586	8BEC	A0	.BYT \$A0	#MEM/WP
1587	8BED	00	.BYT \$00	#L2/L1
1588	8BEE	40	.BYT \$40	#S2/S1
1589	8BEF		ASCII1 =*-1	
1590	8BEF		ASCII =*	#ASCII CODES AND HASH CODES
1591	8BEF	30	.BYT \$30	#ZERO
1592	8BF0	31	.BYT \$31	#ONE
1593	8BF1	32	.BYT \$32	#TWO
1594	8BF2	33	.BYT \$33	#THREE
1595	8BF3	34	.BYT \$34	#FOUR
1596	8BF4	35	.BYT \$35	#FIVE
1597	8BF5	36	.BYT \$36	#SIX
1598	8BF6	37	.BYT \$37	#SEVEN
1599	8BF7	38	.BYT \$38	#EIGHT
1600	8BF8	39	.BYT \$39	#NINE
1601	8BF9	41	.BYT \$41	#A
1602	8BFA	42	.BYT \$42	#B
1603	8BFB	43	.BYT \$43	#C
1604	8BFC	44	.BYT \$44	#D
1605	8BFD	45	.BYT \$45	#E
1606	8BFE	46	.BYT \$46	#F
1607	8BFF	0D	.BYT \$0D	#CR
1608	8C00	2D	.BYT \$2D	#DASH
1609	8C01	3E	.BYT \$3E	#>
1610	8C02	FF	.BYT \$FF	#SHIFT
1611	8C03	47	.BYT \$47	#G
1612	8C04	52	.BYT \$52	#R
1613	8C05	4D	.BYT \$4D	#H
1614	8C06	13	.BYT \$13	#L2
1615	8C07	1E	.BYT \$1E	#S2
1616	8C08		# KB UPPER CASE	
1617	8C08	14	.BYT \$14	#U0
1618	8C09	15	.BYT \$15	#U1
1619	8C0A	16	.BYT \$16	#U2
1620	8C0B	17	.BYT \$17	#U3
1621	8C0C	18	.BYT \$18	#U4
1622	8C0D	19	.BYT \$19	#U5
1623	8C0E	1A	.BYT \$1A	#U6
1624	8C0F	1B	.BYT \$1B	#U7
1625	8C10	4A	.BYT \$4A	#J
1626	8C11	56	.BYT \$56	#V
1627	8C12	FE	.BYT \$FE	#ASCII
1628	8C13	42	.BYT \$42	#B
1629	8C14	43	.BYT \$43	#C
1630	8C15	44	.BYT \$44	#D
1631	8C16	45	.BYT \$45	#E
1632	8C17	46	.BYT \$46	#F
1633	8C18	10	.BYT \$10	#SD
1634	8C19	2B	.BYT \$2B	#+
1635	8C1A	3C	.BYT \$3C	#<
1636	8C1B	00	.BYT \$00	#SHIFT
1637	8C1C	11	.BYT \$11	#LP
1638	8C1D	1C	.BYT \$1C	#SP
1639	8C1E	57	.BYT \$57	#W

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LINE #	LOC	CODE	LINE
1640	8C1F	12	.BYT \$12 ;L1
1641	8C20	1D	.BYT \$1D ;S1
1642	8C21	2E	.BYT \$2E ;.
1643	8C22	20	.BYT \$20 ;BLANK
1644	8C23	3F	.BYT \$3F ;?
1645	8C24	50	.BYT \$50 ;P
1646	8C25	07	.BYT \$07 ;BELL
1647	8C26	63	.BYT \$63 ;SMALL C
1648	8C27	2F	.BYT \$2F ;/
1649	8C28	2A	.BYT \$2A ;*
1650	8C29		;
1651	8C29		SEGMENT CODES FOR ON-BOARD DISPLAY
1652	8C29	3F	SEGSM1 =*-1 .BYT \$3F ;ZERO
1653	8C2A	06	.BYT \$06 ;ONE
1654	8C2B	5B	.BYT \$5B ;TWO
1655	8C2C	4F	.BYT \$4F ;THREE
1656	8C2D	66	.BYT \$66 ;FOUR
1657	8C2E	6D	.BYT \$6D ;FIVE
1658	8C2F	7D	.BYT \$7D ;SIX
1659	8C30	07	.BYT \$07 ;SEVEN
1660	8C31	7F	.BYT \$7F ;EIGHT
1661	8C32	67	.BYT \$67 ;NINE
1662	8C33	77	.BYT \$77 ;A
1663	8C34	7C	.BYT \$7C ;B
1664	8C35	39	.BYT \$39 ;C
1665	8C36	5E	.BYT \$5E ;D
1666	8C37	79	.BYT \$79 ;E
1667	8C38	71	.BYT \$71 ;F
1668	8C39	F0	.BYT \$F0 ;CR
1669	8C3A	40	.BYT \$40 ;DASH
1670	8C3B	70	.BYT \$70 ;>
1671	8C3C	00	.BYT \$00 ;SHIFT
1672	8C3D	6F	.BYT \$6F ;G
1673	8C3E	50	.BYT \$50 ;R
1674	8C3F	54	.BYT \$54 ;M
1675	8C40	38	.BYT \$38 ;L2
1676	8C41	6D	.BYT \$6D ;S2
1677	8C42	01	.BYT \$01 ;U0
1678	8C43	08	.BYT \$08 ;U1
1679	8C44	09	.BYT \$09 ;U2
1680	8C45	30	.BYT \$30 ;U3
1681	8C46	36	.BYT \$36 ;U4
1682	8C47	5C	.BYT \$5C ;U5
1683	8C48	63	.BYT \$63 ;U6
1684	8C49	03	.BYT \$03 ;U7
1685	8C4A	1E	.BYT \$1E ;J
1686	8C4B	72	.BYT \$72 ;V
1687	8C4C	77	.BYT \$77 ;A
1688	8C4D	7C	.BYT \$7C ;B
1689	8C4E	39	.BYT \$39 ;C
1690	8C4F	5E	.BYT \$5E ;D
1691	8C50	79	.BYT \$79 ;E
1692	8C51	71	.BYT \$71 ;F
1693	8C52	6D	.BYT \$6D ;SD
1694	8C53	76	.BYT \$76 ;+

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LINE #	LOC	CODE	LINE
1695	8C54	46	.BYT \$46 ;<
1696	8C55	00	.BYT \$00 ;SHIFT
1697	8C56	38	.BYT \$38 ;LP
1698	8C57	6D	.BYT \$6D ;SP
1699	8C58	1C	.BYT \$1C ;W
1700	8C59	38	.BYT \$38 ;L1
1701	8C5A	6D	.BYT \$6D ;S1
1702	8C5B	80	.BYT \$80 ;.
1703	8C5C	00	.BYT \$00 ;SPACE
1704	8C5D	53	.BYT \$53 ;?
1705	8C5E	73	.BYT \$73 ;P
1706	8C5F	49	.BYT \$49 ;BELL
1707	8C60	5C	.BYT \$5C ;SMALL C
1708	8C61	52	.BYT \$52 ;/
1709	8C62	63	.BYT \$63 ;
1710	8C63	97	DECPTS .BYT \$97,\$3D,\$1F,\$10,\$08,\$00 ; TO DETERMINE BAUD I
1710	8C64	3D	
1710	8C65	1F	
1710	8C66	10	
1710	8C67	08	
1710	8C68	00	
1711	8C69	D5 4C	STDVAL .DBY \$D54C,\$2410,\$0601 ;STD VALS FOR BAUD RATES
1711	8C6B	24 10	
1711	8C6D	06 01	
1712	8C6F		; 110,300,600,1200,2400,4800 BAUD
1713	8C6F	4C 58 8A	TRMTBL JMP INTCHR ;ALTERNATE VCTRS FOR TIO
1714	8C72	4C A0 8A	JMP TOUT
1715	8C75	4C 3C 8B	JMP TSTAT
1716	8C78		LENTY =* ;LINK TO AUDIO CASSETTE
1717	8C78		SENTRY =*+\$20F
1718	8C78		****
1719	8C78		**** DEFAULT TABLE
1720	8C78		****
1721	8C78		*=\$8FA0
1722	8FA0		DFTBLK=*
1723	8FA0	00 C0	.WORD \$C000 ;BASIC *** JUMP TABLE
1724	8FA2	A7 8B	.WORD TTY
1725	8FA4	64 8B	.WORD NEWDEV
1726	8FA6	00 00	.WORD \$0000 ;PAGE ZERO
1727	8FA8	00 02	.WORD \$0200
1728	8FAA	00 03	.WORD \$0300
1729	8FAC	00 C8	.WORD \$C800
1730	8FAE	00 D0	.WORD \$D000
1731	8FB0	00 00	.DBY \$0000,\$0000,\$0000,\$0000 ;SCR0 - SCR7
1731	8FB2	00 00	
1731	8FB4	00 00	
1731	8FB6	00 00	
1732	8FB8	00 00	.DBY \$0000,\$0000,\$0000,\$0000 ;SCR8 - SCR15
1732	8FBA	00 00	
1732	8FBC	00 00	
1732	8FBE	00 00	
1733	8FC0	00	.BYT \$00,\$00,\$6D,\$6E,\$86,\$3F ;DISP BUFFER (SY1.0)
1733	8FC1	00	
1733	8FC2	6D	
1733	8FC3	6E	

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LINE #	LOC	CODE	LINE
1733	8FC4	86	
1733	8FC5	3F	
1734	8FC6	00	.BYT \$00,\$00,\$00 ;NOT USED
1734	8FC7	00	
1734	8FC8	00	
1735	8FC9	00	.BYT \$00 ;PARNR
1736	8FCA	00 00	.DBYT \$0000,\$0000,\$0000 ;PARMS
1736	8FCC	00 00	
1736	8FCE	00 00	
1737	8FD0	01	.BYT \$01 ;PADBIT
1738	8FD1	4C	.BYT \$4C ;SDBYT
1739	8FD2	00	.BYT \$00 ;ERCNT
1740	8FD3	80	.BYT \$80 ;TECHO
1741	8FD4	B0	.BYT \$B0 ;TOUTFL
1742	8FD5	00	.BYT \$00 ;KSHFL
1743	8FD6	00	.BYT \$00 ;TV
1744	8FD7	00	.BYT \$00 ;LSTCOM
1745	8FD8	10	.BYT \$10 ;MAXRC
1746	8FD9	4A 8B	.WORD RESET ;USER REG'S
1747	8FDB	FF	.BYT \$FF ;STACK
1748	8FDC	00	.BYT \$00 ;FLAGS
1749	8FDD	00	.BYT \$00 ;A
1750	8FDE	00	.BYT \$00 ;X
1751	8FDF	00	.BYT \$00 ;Y
1752	8FE0		; VECTORS
1753	8FE0	4C BE 89	JMP HKEY ;INVEC
1754	8FE3	4C 00 89	JMP HDOUT ;OUTVEC
1755	8FE6	4C 6A 89	JMP KYSTAT ;INSVEC
1756	8FE9	00	.BYT \$00,\$00,\$00 ;NOT USED
1756	8FEA	00	
1756	8FEB	00	
1757	8FEC	4C D1 81	JMP M1 ;UNRECOGNIZED CHAR (ERR RTN)
1758	8FEF	4C 06 89	JMP SCAND ;SCNVEC
1759	8FF2	7E 88	.WORD RIN ;IN PTR FOR EXEC FROM RAM
1760	8FF4	C0 80	.WORD TRCOFF ;USER TRACE VECTOR
1761	8FF6	4A 80	.WORD SVBRK ;BRK
1762	8FF8	29 80	.WORD SVIRQ ;USER IRQ
1763	8FFA	9B 80	.WORD SUNMI ;NMI
1764	8FFC	4A 8B	.WORD RESET ;RESET
1765	8FFE	0F 80	.WORD IRQBRK ;IRQ
1766	9000		.END

ERRORS = 0000 <0000>





SYMBOL	VALUE	LINE	DEFINED	CROSS-REFERENCES									
ACCESS	8B86	1527	123	129	137	177	191	1507	1525	1540	1546		
ACC1	8B8E	1530	1539										
ADVCK	81CB	336	581	599									
AGAIN	8B24	1475	1471										
AR	A65D	59	152	186	616								
ASCII	8BEF	1590	1259										
ASCIM1	8BEE	1589	1313										
ASCNIB	8275	412	344	352	394								
BADDDY	848B	666	660										
BAUD	8AFF	1459	1521										
BEEP	8972	1266	1193										
BEEPP3	8975	1267	1304										
BEEPP5	8977	1268	1286										
BE1	897C	1270	1277										
BE2	8995	1280	1272	1275									
BE3	8997	1281	1282										
BLK3	8739	991	976										
BLP	875E	1007	1013	1014									
BLP1	879D	1035	1042										
BMOVE	87B7	1048	1007	1035									
BRT	87CC	1058	1052										
BRTT	87C1	1053	985										
BZPARM	8395	559	261										
B1	87AF	1043	987	990	1005	1012	1015	1041					
B1PARM	84DA	699	264										
B2	8772	1016	1006										
B2PARM	8619	858	267										
B3PARM	8714	971	270										
CALC3	8827	1103	857	970	1085								
CHKSAD	82DD	463	676	887	955								
CLEAR	8B08	1464	1465										
COMINB	81D6	342	569										
COMMA	833A	511	342	503	732								
COMPAR	82CA	455	444	446									
CONFIG	89A5	1288	1211	1230	1268								
CON1	89AB	1291	1297										
CRCHK	8204	364	362	363									
CRLF	834D	521	147	219	277	497	564	587	604	622	784	905	
			926	1105									
CRLFSZ	8316	497	706	731	882								
C1	882B	1105	****										
DBNEW	80F6	212	204										
DBOFF	80D3	198	146	180	194								
DBON	80E4	205	196										
DDR1B	A002	91	****										
DDR3A	AC03	89	202	209	211	212	214	854	1531	1533			
DEAF	8B15	1469	1476										
DECCMP	82BE	449	761	899	1040								
DECPYS	8C63	1710	1469										
DELAY	835A	528	188										
DEPBYT	84E8	709	718										
DEPEC	850E	726	720										
DEPES	8553	759	722										
DEPN	84F9	716	714	723	725								

SYMBOL	VALUE	LINE	DEFINED	CROSS-REFERENCES
DEPZ	84A7	677	620	
DEP1	84DA	703	****	
DETRK	801B	113	****	
DETIRQ	8022	118	112	
DFTBLK	8FA0	1722	1509	
DFTXFR	8B59	1508	1512	
DIFFL	86FD	958	****	
DIFFL2	8710	969	****	
DIFFZ	86FA	957	923	
DIFF1	870F	968	964 1495	
DISBUF	A640	27	1214 1323 1324	
DISPAT	814A	256	99	
DLYF	8AE6	1441	1416 1485	
DLYH	8AE9	1442	1381 1395 1400 1408 1441	
DLYO	8383	544	539	
DLYX	8AF1	1448	1452	
DLYY	8AF3	1449	1450	
DLY1	8368	533	536	
DLY2	8371	537	543	
DL1	835D	529	****	
DMY1	8A81	1390	1387	
ERCNT	A652	43	624 632 649 653 667 671 673 979 995 1043	
			1053 1057	
ERMSG	8171	275	100	
EXEVEC	A672	74	1130 1135 1137	
EXE3	8851	1125	1104	
EXITCP	82D9	461	458	
EXITG	88FF	1207	1203	
EXITGK	88CC	1183	1171	
EXITLP	843F	634	****	
EXITM1	8577	780	745	
EXITNB	8315	496	494	
EXITOD	8A03	1330	1311 1317 1320	
EXITRG	83C1	579	598	
EXRGP1	83C2	580	582	
EXWRAP	82BD	448	447	
EZPARM	84D7	698	695	
E1PARM	8616	857	842	
E2PARM	8711	970	919	
E3PARM	88AC	1164	1126	
FILL3	8714	975	****	
FOUND	8960	1255	1250	
FR	A65C	58	164 612	
F1	8723	981	988 989	
F2	8737	990	****	
F3	872E	986	984	
GETCOM	80FF	219	98 223 246	
GETC1	8107	222	225 227	
GETKEY	88AF	1168	1299	
GETSGS	89EA	1318	1314	
GK	88CF	1184	1169 1172 1179	
GK1	88D4	1186	1187 1189 1206	
GK2	88E4	1194	1195 1198	
GOOD	81F3	355	360	
GOPAD	8ACE	1429	1426	
G02	83F7	604	****	
G0Z	83F3	602	563	

SYMBOL	VALUE	LINE	DEFINED	CROSS-REFERENCES											
G01	8579	782	729												
G01ENT	83FA	605	197												
HASHL	812F	240	234												
HASHUS	8133	242	230	232	241										
HDOUT	8900	1208	1754												
HIPN	816E	271	257	269											
HKEY	89BE	1299	1753												
IDISP	8053	145	127	136	184										
IJSCNV	8903	1209	537	1186											
INBYTE	81D9	343	572	657	661	666	675	710							
INCCMP	82B2	443	654	716	742	889	946	986	1011	1091					
INCHR	8A1B	1348	222	245	252	343	351	359	382	626	1162	1362			
INCP3	8293	429	1070	1081											
INJINV	8A41	1365	1349												
INJISV	8392	554	548	550											
INJOUV	8A55	1372	1370												
INK	8B27	1477	1464	1466											
INK1	8B2A	1479	1480												
INRT1	8A2D	1356	1352	1354											
INRT2	8A3C	1363	1357												
INSTAT	8386	548	538	896	944										
INST1	838B	550	551												
INST2	8391	553	549												
INSVEC	A666	67	554												
INTCHR	8A58	1373	1713												
INVEC	A660	65	1128	1133	1136	1138	1158	1160	1365	1549					
IRQBRK	800F	105	1765												
IRQVEC	A67E	82	****												
JTABLE	A620	9	822	824											
JUMP1	85B4	808	797												
JUM2	85E5	833	812												
KEYQ	8923	1223	1194	1197	1261	1516									
KSCONF	89A3	1287	1223	1278	1489	1515									
KSHFL	A655	48	1185	1205	1257										
KYSTAT	896A	1261	1755												
LDBYTE	84A1	675	629	637	640	643									
LEAVE	8AD1	1430	1428												
LENTY	8C78	1716	693	836	1083										
LK1	8944	1237	1234												
LK2	894A	1240	1238												
LK3	8956	1249	1252												
LOCM8	8569	772	758												
LOCP8	855B	764	754												
LOOK	8A5F	1376	1380												
LP6D	846D	654	648												
LPZ	8429	625	641	664	670	674									
LPZB	8417	618	603												
LP1	842C	626	628												
LRNKEY	892C	1227	1188												
LSTCOM	A657	50	235	244	248	258									
L1J	84CC	693	697												
L1ZB	84C6	690	684												
L11B	85D7	826	809												
L11C	85DD	829	840												
L11D	85E9	835	917												
L12B	8688	911	879	915											
L12C	868C	913	****												

SYMBOL	VALUE	LINE	DEFINED	CROSS-REFERENCES
L2ZB	84CF	694	691	
L21B	95EF	837	827	
L23P	87EE	1076	1073	
MAXRC	A65B	51	927	929
MEMZ	84AE	680	678	
MEM1	8510	728	704	
MEM2	862F	873	863	
MEM3	8801	1084	1077	
MEM3C	8808	1087	877	1093 1094
MEM3D	8811	1091	1100	
MEM3E	881C	1097	1090	
MEM3EX	881A	1095	1092	
MEM3F	8826	1102	1098	
MONENT	8B7C	1522	97	1517
MONITR	8000	97	****	
MORED	8454	643	656	
MORED2	86D2	941	949	
M1	81D1	339	337	1757
M12	8159	262	260	
M13	8160	265	263	
M14	8167	268	266	
M15	81B7	314	275	
M21	8239	387	384	
M22	824A	394	386	
M23	8251	397	400	
M24	8267	406	393	395
M25	826F	409	407	
M26	8289	422	415	417
M27	828D	425	419	
M28	828F	426	421	
M29	8292	428	413	
M32	82C8	454	450	
M33	82EB	470	468	
M34	83C8	583	577	
M35	83CA	584	597	600
M36	83EB	598	595	
M42	8566	770	768	
M43	8574	778	776	
NACCES	8B9C	1535	605	785 813
NBASOC	8A44	1366	485	487 591
NBELL	89CD	1305	1303	
NEWDEV	8B64	1513	1725	
NEWLN	84E1	706	679	719
NEWLOC	8517	731	682	748 763 771 779 1097
NH3	83BF	578	570	573
NH41	8501	720	711	
NH42	8537	745	736	
NIBALF	8313	495	492	
NIBASC	8309	490	1366	
NMIVEC	A67A	80	****	
NOBEEP	899B	1284	1196	
NOKEY	895E	1253	1236	
NOTCR	83C3	581	578	
NR10	8408	611	795	825
NUREC	8443	636	631	
NXTLOC	8531	742	740	750 752
NXTRG	83D2	588	****	

SYMBOL	VALUE	LINE	DEFINED	CROSS-REFERENCES
OBCMIN	81D3	341	594	735
OBCRLF	834A	520	187	
OCMCK	8325	503	895	904
OPCCOM	8337	510	148	185
OR1B	A000	90	****	
OR3A	AC01	88	89	198 201 205 208 852 1528 1530 1536
OUTD1	89DE	1312	1307	
OUTD2	89E0	1313	1316	
OUTD3	89F4	1323	1327	
OUT	8AD4	1431	1388	1402 1415
OUTBYT	82FA	479	284	341 477 505 520 888 956
OUTC	8AB4	1415	1423	
OUTCHR	8A47	1367	150	221 279 281 502 517 523 525 566 589
			934	1154 1514
OUTDSP	89C1	1300	1208	
OUTONE	8ADE	1436	1434	
OUTPC	82EE	473	510	568
OUTQM	8320	501	715	741
OUTSZ	8319	498	****	
OUTVEC	A663	66	1372	
OUTXAH	82F4	475	500	908 952 1122
OUT1	81FE	361	358	
OUT2	8201	363	353	
OUT4	81F5	357	345	
PAD	8B32	1484	1429	
PADA	A400	86	1215	1217 1224 1235 1294
PADBIT	A650	41	1484	
PAD1	8B35	1485	1487	
PARFIL	822E	382	405	
PARM	8220	377	239	
PARNR	A649	30	259	379 389 390 408
PBDA	A402	87	1216	1231 1271 1274 1292 1376 1382 1410 1432 1437
			1461 1481 1490 1518	
PCHR	A65A	56	134	162 474 576 593 596 608
PCLR	A659	55	132	159 473 574 610
PCR1	A00C	92	1503	
PHAKE	8ABC	1418	1419	
PM1	822B	381	392	
POR	8B4D	1502	****	
PRM10	820A	368	375	
PRVLOC	8555	761	756	
PSHOVE	8208	367	237	238 381 834 835
PTRIN	8872	1139	1131	
P1H	A64F	40	373	999 1111
P1L	A64E	39	372	876 980 997 1062 1078 1087 1108
P2H	A64D	38	371	433 804 865 1033 1112
P2L	A64C	37	370	435 799 869 875 913 1031 1109
P2SCR	829C	433	880	922 977 996 1086
P3H	A64B	36	369	398 431 438 457 688 792 803 806 847
			962	1021 1034 1119 1139
P3L	A64A	35	368	397 401 402 429 440 460 686 794 798
			802	810 829 843 958 1018 1032 1116 1141
P3SCR	82A7	438	705	730 864 1030
RAM	A620	8	1510	
RC	A63D	24	636	655 932 935 948
RDIG	A645	28	1308	1310 1329
REGZ	8395	562	****	

SYMBOL	VALUE	LINE	DEFINED	CROSS-REFERENCES
RESALL	81C4	326	925	1279 1298 1330 1371 1430 1534
REGET	8B4A	1500	1746	1764
RESTIV	8899	1157	1148	
RESXAF	81B8	316	411	1156 1163 1183 1364 1405
RESXF	81BE	321	462	544 635
ROBACK	8399	564	586	
RIN	887E	1145	1759	
RSTVEC	A67C	81	****	
SAVE	8A87	1394	1389	
SAVER	8188	289	377	455 529 621 921 1145 1168 1266 1284 1288
			1300	1348 1367 1373 1407 1527 1535
SAVINT	8064	152	125	131 139 179 193
SCAND	8906	1210	1758	
SCNVEC	A66F	70	1209	
SCPBUF	A600	7	1335	1336 1342
SCRA	A63A	20	1132	1134 1157 1159
SCRB	A63B	21	****	
SCRC	A63C	22	****	
SCRD	A63D	23	24	
SCRE	A63E	25	1178	1182
SCRF	A63F	26	1228	1247
SCRO	A630	10	****	
SCR1	A631	11	****	
SCR2	A632	12	****	
SCR3	A633	13	350	380 388 404 406
SCR4	A634	14	571	575
SCR5	A635	15	****	
SCR6	A636	16	466	467 504 507 663 951
SCR7	A637	17	469	508 659 907 950
SCR8	A638	18	532	533 540
SCR9	A639	19	531	534 542
SC1	890D	1213	1222	
SC2	891D	1219	1220	
SDBYT	A651	42	1447	1468 1470 1473 1542
SEEK	8B02	1461	1463	
SEGSM1	8C2B	1651	1318	
SENTRY	8E87	1717	1071	
SET	8B0D	1466	1467	
SPACE	8342	515	236	282 514 567 709 724 884 906 1106
SPCP3	8345	517	513	
SPC2	833F	514	592	
SPEXIT	86A8	925	945	947
SP2B	8698	918	912	
SP2C	86A3	923	954	
SP2D	86A8	926	924	
SP2E	86B8	931	928	
SP2F	86BA	932	930	
SR	A65B	57	175	606
STDVAL	8C69	1711	1472	
STD2	8619	862	****	
STOCOM	8120	235	251	
SVBRK	804A	137	1761	
SVBYTE	86F4	955	936	938 940 943
SVIRQ	8029	123	1762	
SUNMI	809B	177	1763	
SWITCH	8B69	1515	****	
SWLP	8B6C	1516	1519	

SYMBOL	VALUE	LINE	DEFINED	CROSS-REFERENCES
SWLP2	8B8C	1548	1551	
SYM	8BD6	1562	1249	
S1NG	87DE	1068	1080	
S13B	87CD	1059	993	
S13C	87D3	1062	1075	
S23B	87E6	1072	1060	
TABLE	8BD6	1563	****	
TAPERR	848E	667	630	638 644 658 662 665
TECHO	A653	45	1152	1358 1360 1368 1386
TEXT	8A06	1331	1305	
TIN	8A6A	1381	1399	
TLP1	8A83	1391	1392	
TOUT	8AA0	1406	1714	
TOUTFL	A654	47	1377	1383 1436 1543 1545
TRACON	80CD	196	189	
TRCOFF	80C0	191	1760	
TRCVEC	A674	75	195	
TRMTBL	8C6F	1713	1548	
TSTAT	8B3C	1489	1715	
TTY	8BA7	1540	1724	
TV	A656	49	181	528
TVNZ	80AF	185	182	
TXTM0V	8A0B	1335	1338	
UBRKV	A676	77	****	
UBRKVC	A676	76	77	
UIRQV	A678	79	****	
UIRQVC	A678	78	79	
URCVEC	A66C	69	271	698 1164
USRENT	8035	128	****	
VADDR	8646	882	897	
VALS	8BC6	1557	1293	1561
VALSP2	8BC8	1561	1291	
VECSW	8BB7	1546	1520	
VERZ	84B5	683	681	
VER1	8596	796	689	783
VER2	863C	878	807	874
VOCK	8664	895	****	
V1	866D	899	890	892 903
V2	864B	884	894	
WARM	8003	98	101	151 190 1526
WFR1B	85F7	841	838	
WRAP	82B8	446	452	
XR	A65E	60	153	615
YR	A65F	61	154	614
ZERCK	832E	506	625	881 957





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LINE #	LOC	CODE	LINE
0002	0000		; AUDIO CASSETTE INTERFACE
0003	0000		;*****
0004	0000		;***** COPYRIGHT 1978 SYNERTEK SYSTEMS CORPORATION
0005	0000		;*****
0006	0000		;
0007	0000		;VARIABLES
0008	0000		;
0009	0000		OLD = \$F9 ;REMEMBER PREV INPUT LEVEL IN LOA)
0010	0000		CHAR = \$FC ;CHAR ASSY AND DISASSY
0011	0000		MODE = \$FD ;BIT7=1 IS HS, 0 IS KIM
0012	0000		;
0013	0000		... BIT6=1 IS HS REC W/WRONG ID BEING READ
0014	0000		... OR NOT YET IN SYNC (NO FRAME ERR)
0015	0000		BUFADL = \$FE ;RUNNING BUFFER ADR
0016	0000		BUFADH = \$FF
0017	0000		CHKL = \$A636 ;SCR 6
0018	0000		CHKH = \$A637 ;SCR 7
0019	0000		TEMP1 = \$A638 ;SCR 8
0020	0000		TEMP2 = \$A639 ;SCR 9
0021	0000		; PARAMETER AREA
0022	A64A		* = \$A64A
0023	A64B		P3L * = * + 1 ;END ADDR + 1 (LO)
0024	A64C		P3H * = * + 1 ; (HI)
0025	A64D		P2L * = * + 1 ;START ADDR ; (LO)
0026	A64E		P2H * = * + 1 ; (HI)
0027	A64F		P1L * = * + 1 ; ID
0028	A64F		; CONSTANTS
0029	A64F		;
0030	A64F		EOT = \$04
0031	A64F		SYN = \$16
0032	A64F		TM1500 = 71 ;DELAY CONSTANT FOR OUTBTH
0033	A64F		C1500 = \$1F ;CLOCK LO LATCH FOR 1500 BAUD
0034	A64F		CKIM = \$AE ;CLOCK LO LATCH FOR KIM
0035	A64F		TPBIT = \$1000 ;BIT 3 IS ENABLE/DISABLE TO DECODE
0036	A64F		;
0037	A64F		;EQUATES
0038	A64F		;
0039	A64F		P2SCR = \$829C ;MOVE P2 TO \$FF,\$FE IN PAGE ZERO
0040	A64F		ZERCK = \$832E ;ZERO OUT CHECK SUM
0041	A64F		CONFIG = \$89A5
0042	A64F		;
0043	A64F		ID = P1L
0044	A64F		SAH = P2H
0045	A64F		SAL = P2L
0046	A64F		EAH = P3H
0047	A64F		EAL = P3L
0048	A64F		;
0049	A64F		FRAME = \$FF ;ERROR MSG # FOR FRAMING ERROR
0050	A64F		CHECK = \$CC ;ERROR # FOR CHECKSUM ERROR
0051	A64F		LSTCHR = \$2F ;LAST CHAR NOT '/'
0052	A64F		NONHEX = \$FF ;NON HEX CHAR IN KIM REC
0053	A64F		;
0054	A64F		;I/O TAPE ON/OFF IS CB2 ON VIA 1 (A000)
0055	A64F		; TAPE IN IS PB6 ON VIA 1 (A000)
0056	A64F		; TAPE OUT IS CODE 7 TO DISPLAY DECODER, THRU 6532:
			PB0-PB3 (A400)

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LINE #	LOC	CODE	LINE
0057	A64F		;
0058	A64F		VIAACR = \$A00B
0059	A64F		VIAPCR = \$A00C ;CONTROL CB2 TAPE ON/OFF, POR
0060	A64F		TPOUT = \$A402
0061	A64F		TAPOUT = TPOUT
0062	A64F		DDRROUT = \$A403
0063	A64F		TAPIN = \$A000
0064	A64F		DDRIN = \$A002
0065	A64F		CLOKHI = \$A005
0066	A64F		CLOKLO = \$A004
0067	A64F		LATCHL = \$A004
0068	A64F		DDRDIG = \$A401
0069	A64F		DIG = \$A400
0070	A64F		; LOADT ENTER W/ ADDR IN PARM 2, MODE IN ACC
0071	A64F		;
0072	A64F		* = \$8C78
0073	8C78	20 B6 8D	LOADT JSR START ;INITIALIZE
0074	8C7B	AD 02 A0	LDA DDRIN
0075	8C7E	29 BF	AND #\$BF ;BIT 6 = 0, INPUT IS PB6
0076	8C80	8D 02 A0	STA DDRIN
0077	8C83	A9 00	LDA #0
0078	8C85	8D 0B A0	STA VIAACR
0079	8C88	A9 AE	LDA #CKIM ; SET UP CLOCK FOR GETTR (KIM)
0080	8C8A	24 FD	BIT MODE
0081	8C8C	10 02	BPL LOADT1 ;KIM - GO AHEAD
0082	8C8E	A9 1F	LDA #C1500 ;HS - CHANGE GETTR VALUE
0083	8C90	8D 04 A0	LOADT1 STA LATCHL ;STORE GETTR VAL IN LO LATCH
0084	8C93	20 82 8D	LOADT2 JSR SYNC ;GET IN SYNC
0085	8C96	20 DE 8D	LOADT4 JSR RDCHTX
0086	8C99	C9 2A	CMP #'* ;START OF DATA?
0087	8C9B	F0 06	BEQ LOAD11
0088	8C9D	C9 16	CMP #SYN ;NO - SYN?
0089	8C9F	D0 F2	BNE LOADT2 ;IF NOT, RESTART SYNC SEARCH
0090	8CA1	F0 F3	BEQ LOADT4 ;IF YES, KEEP LOOKING FOR *
0091	8CA3		;
0092	8CA3	A5 FD	LOAD11 LDA MODE
0093	8CA5	29 BF	AND #\$BF ;CLEAR 'NOT IN SYNC' BIT
0094	8CA7	85 FD	STA MODE
0095	8CA9	20 28 8E	JSR RDBYTX ;READ ID BYTE ON TAPE
0096	8CAC	CD 4E A6	CMP ID ;COMPARE WITH REQUESTED ID
0097	8CAF	F0 35	BEQ LOADT5 ;LOAD IF EQUAL
0098	8CB1	AD 4E A6	LDA ID ;COMPARE WITH 0
0099	8CB4	C9 00	CMP #0
0100	8CB6	F0 2E	BEQ LOADT5 ;IF 0, LOAD ANYWAY
0101	8CB8	C9 FF	CMP #\$FF ;COMPARE WITH FF
0102	8CBA	F0 07	BEQ LOADT6 ;IF FF, USE REQUEST SA TO LOAD
0103	8CBC		;
0104	8CBC	24 FD	BIT MODE ;UNWANTED RECORD. KIM OR HS?
0105	8CBE	30 22	BMI HWRONG
0106	8CC0	4C 93 8C	JMP LOADT2 ;IF KIM, RESTART SEARCH
0107	8CC3		;
0108	8CC3		; SA (&EA IF USED) COME FROM REQUEST. DISCARD TAPE VALUE!
0109	8CC3		; (BUFAD ALREADY SET TO SA BY 'START')
0110	8CC3		;
0111	8CC3	20 28 8E	LOADT6 JSR RDBYTX ;GET SAL FROM TAPE

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LINE #	LOC	CODE	LINE	
0112	8CC6	20 78 8E	JSR CHKT	#INCLUDE IN CHECKSUM BUT IGNORE
0113	8CC9			
0114	8CC9	20 28 8E	JSR RDBYTX	#GET SAH FROM TAPE
0115	8CCC	20 78 8E	JSR CHKT	#INCLUDE IN CHECKSUM
0116	8CCF			
0117	8CCF	24 FD	BIT MODE	#HS OR KIM?
0118	8CD1	10 63	BPL LOADT7	#IF KIM, START READING DATA
0119	8CD3	20 E2 8D	JSR RDBYTH	#HS. GET EAH, EAL FROM ...
0120	8CD6	20 78 8E	JSR CHKT	# ... TAPE, INCLUDE IN CHECKSUM
0121	8CD9	20 E2 8D	JSR RDBYTH	# ... BUT IGNORE
0122	8CDC	20 78 8E	JSR CHKT	
0123	8CDF	4C 0C 8D	JMP LT7H	#START READING HS DATA
0124	8CE2			
0125	8CE2			# SA (& EA IF USED) COME FROM TAPE. SA REPLACES BUFAD
0126	8CE2			
0127	8CE2	A9 C0	HWRONG LDA ##C0	#READ THRU TO GET TO NEXT REC
0128	8CE4	85 FD	STA MODE	#BUT DON'T CHECK CKSUM, NO FRAME I
0129	8CE6			
0130	8CE6	20 28 8E	LOADT5 JSR RDBYTX	#GET SAL FROM TAPE
0131	8CE9	20 78 8E	JSR CHKT	
0132	8CEC	85 FE	STA BUFADL	#PUT IN BUF START L
0133	8CEE	20 28 8E	JSR RDBYTX	#SAME FOR SAH
0134	8CF1	20 78 8E	JSR CHKT	
0135	8CF4	85 FF	STA BUFADH	
0136	8CF6			#(SAL - H STILL HAVE REQUEST VALUE)
0137	8CF6	24 FD	BIT MODE	#HS OR KIM?
0138	8CF8	10 3C	BPL LOADT7	#IF KIM, START READING RECORD
0139	8CFA	20 E2 8D	JSR RDBYTH	#HS. GET & SAVE EAL, EAH
0140	8CFD	20 78 8E	JSR CHKT	
0141	8D00	8D 4A A6	STA EAL	
0142	8D03	20 E2 8D	JSR RDBYTH	
0143	8D06	20 78 8E	JSR CHKT	
0144	8D09	8D 4B A6	STA EAH	
0145	8D0C			
0146	8D0C			# READ HS DATA
0147	8D0C			
0148	8D0C	20 E2 8D	LT7H JSR RDBYTH	#GET NEXT BYTE
0149	8D0F	A6 FE	LDX BUFADL	#CHECK FOR END OF DATA + 1
0150	8D11	EC 4A A6	CPX EAL	
0151	8D14	D0 07	BNE LT7HA	
0152	8D16	A6 FF	LDX BUFADH	
0153	8D18	EC 4B A6	CPX EAH	
0154	8D1B	F0 13	BEQ LT7HB	
0155	8D1D	20 78 8E	LT7HA JSR CHKT	#NOT END. UPDATE CHECKSUM
0156	8D20	24 FD	BIT MODE	#WRONG RECORD?
0157	8D22	70 04	BVS LT7HC	#IF SO, DONT STORE BYTE
0158	8D24	A0 00	LDY #0	#STORE BYTE
0159	8D26	91 FE	STA (BUFADL),Y	
0160	8D28	E6 FE	LT7HC INC BUFADL	#BUMP BUFFER ADDR
0161	8D2A	D0 E0	BNE LT7H	
0162	8D2C	E6 FF	INC BUFADH	#CARRY
0163	8D2E	D0 DC	BNE LT7H	#ALWAYS
0164	8D30			
0165	8D30	C9 2F	LT7HB CMP #''	#EA, MUST BE ''
0166	8D32	D0 31	BNE LCERR	#LAST CHAR NOT ''

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LINE	#	LOC	CODE	LINE	
0167	8D34	F0 19		BEQ LOADT8	;(ALWAYS BRANCH)
0168	8D36			;	
0169	8D36			; READ KIM DATA	
0170	8D36			;	
0171	8D36	20 2C 8E		LOADT7 JSR RDBYTX	
0172	8D39	B0 2E		BCS NHERR	;(NONHEX CHAR?)
0173	8D3B	C9 2F		CMP #'/'	;(LAST ?)
0174	8D3D	F0 10		BEQ LOADT8	
0175	8D3F	20 78 8E		JSR CHKTX	;(UPDATE CHECKSUM (PACKED BYTE))
0176	8D42	A0 00		LDY #0	;(STORE BYTE)
0177	8D44	91 FE		STA (BUFADL),Y	
0178	8D46	E6 FE		INC BUFADL	;(BUMP BUFFER ADR)
0179	8D48	D0 EC		BNE LOADT7	;(CARRY?)
0180	8D4A	E6 FF		INC BUFADH	
0181	8D4C	4C 36 8D		JMP LOADT7	
0182	8D4F			;	
0183	8D4F			; TEST CHECKSUM & FINISH	
0184	8D4F			;	
0185	8D4F			LOADT8 =*	
0186	8D4F	20 28 8E		LT8A JSR RDBYTX	;(CHECK SUM)
0187	8D52	CD 36 A6		CMP CHKL	
0188	8D55	D0 16		BNE CKERR	
0189	8D57	20 28 8E		JSR RDBYTX	
0190	8D5A	CD 37 A6		CMP CHKH	
0191	8D5D	D0 0E		BNE CKERR	;(CHECK SUM ERROR)
0192	8D5F	F0 11		BEQ OKEXIT	;(ALWAYS)
0193	8D61			;	
0194	8D61	A9 FF		FRERR LDA #FRAME	;(FRAMING ERROR)
0195	8D63	D0 0A		BNE NGEXIT	;(ALWAYS)
0196	8D65	A9 2F		LCERR LDA #LSTCHR	;(LAST CHAR IS NOT '/')
0197	8D67	D0 06		BNE NGEXIT	;(ALWAYS)
0198	8D69			;	
0199	8D69	A9 FF		NHERR LDA #NONHEX	;(KIM ONLY, NON HEX CHAR READ)
0200	8D6B	D0 02		BNE NGEXIT	;(ALWAYS)
0201	8D6D			;	
0202	8D6D	A9 CC		CKERR LDA #CHECK	;(CHECKSUM ERROR)
0203	8D6F			;	
0204	8D6F	38		NGEXIT SEC	;(ERROR INDICATOR TO MONITOR IS CA)
0205	8D70	B0 01		BCS EXIT	;(ALWAYS)
0206	8D72			;	
0207	8D72	18		OKEXIT CLC	;(NO ERROR)
0208	8D73			;	
0209	8D73	24 FD		EXIT BIT MODE	
0210	8D75	50 05		BVC EX10	;(READING WRONG REC?)
0211	8D77	A0 80		LDY #80	
0212	8D79	4C 78 8C		JMP LOADT	;(RESTART SEARCH)
0213	8D7C	A2 CC		EX10 LDX #CC	
0214	8D7E	8E 0C A0		STX VIAPCR	;(STOP TAPE)
0215	8D81	60		RTS	
0216	8D82	A9 6D		SYNC LDA #6D	
0217	8D84	8D 00 A4		STA DIG	;(TURN ON OUT OF SYNC INDICATOR)
0218	8D87	A5 FD		LDA MODE	;(TURN ON OUT OF SYNC MODE)
0219	8D89	09 40		ORA #40	;(BIT6)
0220	8D8B	85 FD		STA MODE	
0221	8D8D	20 A8 8D		SYNCS JSR SYNBIT	;( SYNC TO TAPE)

LINE #	LOC	CODE	LINE
0222	8D90	66 FC	ROR CHAR
0223	8D92	A5 FC	LDA CHAR
0224	8D94	C9 16	CMP #SYN
0225	8D96	D0 F5	BNE SYNC5
0226	8D98	A2 0A	LDX #10
0227	8D9A	20 DE 8D	JSR RDCHTX
0228	8D9D	C9 16	CMP #SYN
0229	8D9F	D0 EC	BNE SYNC5
0230	8DA1	CA	DEX
0231	8DA2	D0 F6	BNE SYNC10+2
0232	8DA4	8E 00 A4	STX DIG
0233	8DA7	60	RTS
0234	8DA8		;SYNBIT GET BIT IN SYN SEARCH. IF HS, ENTER WITH
0235	8DA8		; TIMER STARTED BY PREV BIT. BIT RETURNED IN CARRY.
0236	8DA8		
0237	8DA8	24 FD	SYNBIT BIT MODE
0238	8DAA	10 63	BPL RDBITK
0239	8DAC	20 C9 8D	JSR GETTR
0240	8DAF	B0 01	BCC SYBONE
0241	8DB1	60	RTS
0242	8DB2	20 C9 8D	JSR GETTR
0243	8DB5	60	RTS
0244	8DB6		
0245	8DB6	84 FD	STY MODE
0246	8DB8	A9 09	LDA #9
0247	8DBA	20 A5 89	JSR JZCONF
0248	8DBD	20 2E 83	JSR ZERCK
0249	8DC0	20 9C 82	JSR P2SCR
0250	8DC3	A9 EC	LDA #SEC
0251	8DC5	8D 0C A0	STA VIAPCR
0252	8DC8	60	RTS
0253	8DC9		
0254	8DC9		; GETTR - GET TRANSITION TIME FROM 16 BIT CLOCK
0255	8DC9		; DESTROYS A,Y
0256	8DC9		; LO LATCH OF CLOCK MUST BE PRELOADED ACCORDING TO MODE
0257	8DC9		; SO THAT LSB OF HI BYTE OF CTR =BIT (HS)
0258	8DC9		; OR LSB OF HI BYTE IS 1/0 HF/LF (KIM)
0259	8DC9		; LSB OF HI CLOCK BYTE RETURNED IN CARRY
0260	8DC9		
0261	8DC9	A0 FF	LDY #FF
0262	8DCB	AD 00 A0	LDA TAPIN
0263	8DCE	29 40	AND #40
0264	8DD0	C5 F9	CMP OLD
0265	8DD2	F0 F7	BEQ GETTR+2
0266	8DD4	85 F9	STA OLD
0267	8DD6	AD 05 A0	LDA CLOKHI
0268	8DD9	8C 05 A0	STY CLOKHI
0269	8DDC	4A	LSR A
0270	8DDD	60	RTS
0271	8DDE		
0272	8DDE	24 FD	RDCHTX BIT MODE
0273	8DE0	10 7F A4	BPL RDCHT
0274	8DE2		
0275	8DE2		; RDBYTH - READ HS BYTE
0276	8DE2		; Y DESTROYED, BYTE RETURNED IN CHAR AND A

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LINE	LOC	CODE	LINE		
0387	8E82	EE 37 A6		INC CHKH	#BUMP HI BYTE
0388	8E85	98	CHKT10	TYA	#RESTORE A
0389	8E86	60		RTS	
0390	8E87	20 B6 8D	DUMPT	JSR START	#INIT VIA & CKSUM, SA TO BUFAD & :
0391	8E8A	A9 07		LDA #7	#CODE FOR TAPE OUT
0392	8E8C	8D 02 A4		STA TAPOUT	#BIT 3 USED FOR HI/LO
0393	8E8F	A0 80		LDY #80	
0394	8E91	24 FD		BIT MODE	
0395	8E93	10 13		BPL DUMPT1	#KIM - DO 128 SYNS
0396	8E95		#HS	WRITE 8 SEC	STEADY MARK
0397	8E95	EE 02 A4		INC TAPOUT	#DISABLE OUTPUT
0398	8E98	A2 08		LDX #8	#8 TIMES ...
0399	8E9A	A0 15	MARK8A	LDY #21	#... 1SEC
0400	8E9C	20 5D 8F	MARK8B	JSR OUTCHT	#BENIGN FAUSE
0401	8E9F	88		DEY	
0402	8EA0	D0 FA		BNE MARK8B	
0403	8EA2	CA		DEX	
0404	8EA3	D0 F5		BNE MARK8A	
0405	8EA5	CE 02 A4		DEC TAPOUT	#RESTORE OUTPUT
0406	8EA8				# AND DO 256 SYNS
0407	8EA8	A9 16	DUMPT1	LDA #SYN	
0408	8EAA	20 13 8F		JSR OUTCTX	#WRITE SYN
0409	8EAD	88		DEY	
0410	8EAE	D0 F8		BNE DUMPT1	
0411	8EB0				
0412	8EB0	A9 2A		LDA #*	#WRITE START
0413	8EB2	20 13 8F		JSR OUTCTX	
0414	8EB5				
0415	8EB5	AD 4E A6		LDA ID	#WRITE ID
0416	8EB8	20 46 8F		JSR OUTBTX	
0417	8EBB				
0418	8EBB	AD 4C A6		LDA SAL	#WRITE SA
0419	8EBE	20 43 8F		JSR OUTBCX	
0420	8EC1	AD 4D A6		LDA SAH	
0421	8EC4	20 43 8F		JSR OUTBCX	
0422	8EC7				
0423	8EC7				
0424	8EC7	24 FD		BIT MODE	#KIM OR HS?
0425	8EC9	10 0C		BPL DUMPT2	
0426	8ECB				
0427	8ECB	AD 4A A6		LDA EAL	#HS. WRITE EA
0428	8ECE	20 43 8F		JSR OUTBCX	
0429	8ED1	AD 4B A6		LDA EAH	
0430	8ED4	20 43 8F		JSR OUTBCX	
0431	8ED7				
0432	8ED7	A5 FE	DUMPT2	LDA BUFADL	#CHECK FOR LAST BYTE
0433	8ED9	CD 4A A6		CMP EAL	
0434	8EDC	D0 25		BNE DUMPT4	
0435	8EDE	A5 FF		LDA BUFADH	
0436	8EE0	CD 4B A6		CMP EAH	
0437	8EE3	D0 1E		BNE DUMPT4	
0438	8EE5				
0439	8EE5	A9 2F		LDA #'/	#LAST. WRITE '/
0440	8EE7	20 13 8F		JSR OUTCTX	
0441	8EEA	AD 36 A6		LDA CHKL	#WRITE CHECK SUM

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LINE	#	LOC	CODE	LINE
0442	8EED	20	46 8F	JSR OUTBTX
0443	8EF0	AD	37 A6	LDA CHKH
0444	8EF3	20	46 8F	JSR OUTBTX
0445	8EF6			
0446	8EF6	A9	04	LDA #EOT
0447	8EF8	20	46 8F	JSR OUTBTX
0448	8EFB	A9	04	LDA #EOT
0449	8EFD	20	46 8F	JSR OUTBTX
0450	8F00			
0451	8F00			DT3E = * (SET "OK" MARK)
0452	8F00	4C	72 8D	JMP OKEXIT
0453	8F03			
0454	8F03	A0	00	DUMPT4 LDY #0
0455	8F05	B1	FE	LDA (BUFADL),Y
0456	8F07	20	43 8F	JSR OUTBCX
0457	8F0A	E6	FE	INC BUFADL
0458	8F0C	D0	C9	BNE DUMPT2
0459	8F0E	E6	FF	INC BUFADH
0460	8F10	4C	D7 8E	JMP DUMPT2
0461	8F13	24	FD	OUTCTX BIT MODE
0462	8F15	10	46	BPL OUTCHT
0463	8F17			
0464	8F17			# OUTBTH - NO CLOCK
0465	8F17			# A,X DESTROYED
0466	8F17			# MUST RESIDE ON ONE PAGE - TIMING CRITICAL
0467	8F17	A2	09	OUTBTH LDX #9
0468	8F19	8C	39 A6	STY TEMP2
0469	8F1C	85	FC	STA CHAR
0470	8F1E	AD	02 A4	LDA TAPOUT
0471	8F21	46	FC	GETBIT LSR CHAR
0472	8F23	49	08	EOR #TPBIT
0473	8F25	8D	02 A4	STA TAPOUT
0474	8F28			# *** HERE STARTS FIRST 416 USEC PERIOD
0475	8F28	A0	47	LDY #TM1500
0476	8F2A	88		A416 DEY
0477	8F2B	D0	FD	BNE A416
0478	8F2D	90	11	BCC NOFLIP
0479	8F2F	49	08	EOR #TPBIT
0480	8F31	8D	02 A4	STA TAPOUT
0481	8F34			# *** END OF FIRST 416 USEC PERIOD
0482	8F34	A0	46	B416 LDY #TM1500-1
0483	8F36	88		B416B DEY
0484	8F37	D0	FD	BNE B416B
0485	8F39	CA		DEX
0486	8F3A	D0	E5	BNE GETBIT
0487	8F3C	AC	39 A6	LDY TEMP2
0488	8F3F	60		RTS
0489	8F40	EA		NOFLIP NOP
0490	8F41	90	F1	BCC B416
0491	8F43			
0492	8F43	20	78 8E	OUTBCX JSR CHKT
0493	8F46	24	FD	OUTBTX BIT MODE
0494	8F48	30	CD	BMI OUTBTH
0495	8F4A			
0496	8F4A			#OUTBTC - OUTPUT ONE KIM BYTE

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LINE	#	LOC	CODE	LINE	
0497		8F4A			
0498		8F4A		OUTBTC	=*
0499		8F4A	A8	OUTBT	TAY
0500		8F4B	4A		LSR A
0501		8F4C	4A		LSR A
0502		8F4D	4A		LSR A
0503		8F4E	4A		LSR A
0504		8F4F	20 52 8F	JSR	HEXOUT
0505		8F52			#MORE SIG DIGIT
0506		8F52			# FALL INTO HEXOUT
0507		8F52			#
0508		8F52			#CONVERT LSD OF A TO ASCII
0509		8F52	29 0F		#
0510		8F54	C9 0A	HEXOUT	AND #0F
0511		8F56	18		CMP #0A
0512		8F57	30 02		CLC
0513		8F59	69 07		BMI HEX1
0514		8F5B	69 30		ADC #07
0515		8F5D		HEX1	ADC #30
0516		8F5D			#
0517		8F5D			# OUTCHT - OUTPUT ASCII CHAR (KIM)
0518		8F5D			# CLOCK NOT USED
0519		8F5D			# X,Y PRESERVED
0520		8F5D			# MUST RESIDE ON ONE PAGE - TIMING CRITICAL
0521		8F5D	8E 38 A6		#
0522		8F60	8C 39 A6	OUTCHT	STX TEMP1
0523		8F63	85 FC		#PRESERVE X
0524		8F65	A9 FF	STY	TEMP2
0525		8F67	48		#DITTO Y
0526		8F68	AD 02 A4	STA	CHAR
0527		8F6B	46 FC	LDA	#FF
0528		8F6D	A2 12		#USE FF W/SHIFTS TO COUNT BITS
0529		8F6F	B0 02	KIMBIT	PHA
0530		8F71	A2 24		#SAVE BIT CTR
0531		8F73	A0 19	LDA	TPOUT
0532		8F75	49 08		#GET CURRENT OUTPUT LEVEL
0533		8F77	8D 02 A4	LSR	CHAR
0534		8F7A	88		#GET DATA BIT IN CARRY
0535		8F7B	D0 FD	LDX	#18
0536		8F7D	CA		#ASSUME 'ONE'
0537		8F7E	D0 F3	BCS	HF
0538		8F80	A2 18		#BIT IS ZERO
0539		8F82	B0 02	LDX	#36
0540		8F84	A2 0C		#
0541		8F86	A0 27	LDY	#25
0542		8F88	49 08	EOR	#TPBIT
0543		8F8A	8D 02 A4		#INVERT OUTPUT
0544		8F8D	88	STA	TPOUT
0545		8F8E	D0 FD		#
0546		8F90	CA	HFP1	DEY
0547		8F91	D0 F3		#PAUSE FOR 138 USEC
0548		8F93	68	BNE	HFP1
0549		8F94	0A	DEX	
0550		8F95	D0 D0		#COUNT HALF CYCS OF HF
0551		8F97	AE 38 A6	BNE	HF
				LDF	LDX #24
					#ASSUME BIT IS ONE
					#
					#BIT IS ZERO
					#
					#INVERT OUTPUT
					#
					#PAUSE FOR 208 USEC
					#
					#COUNT HALF CYCS
					#
					#RESTORE BIT CTR
					#DECREMENT IT
					#FF SHIFTED 8X = 00
					#



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LINE #	LOC	CODE	LINE
0552	8F9A	AC 39 A6	LDY TEMP2
0553	8F9D	98	TYA
0554	8F9E	60	RTS
0555	8F9F		
0556	8F9F		.END

#RESTORE DATA BYTE

ERRORS = 0000 <0000>



SYMBOL	VALUE	LINE	DEFINED	CROSS-REFERENCES
A208	8F2A	476	477	
BUFADH	00FF	15	135	152 162 180 435 459
BUFADL	00FE	14	132	149 159 160 177 178 432 455 457
B208	8F34	482	490	
B208B	8F36	483	484	
CHAR	00FC	10	222	223 290 293 331 352 355 369 373 469
			471	523 527
CHECK	00CC	49	202	
CHKH	A637	17	190	387 443
CHKL	A636	16	187	384 385 441
CHKT	8E78	382	112	115 120 122 131 134 140 143 155 175
			492	
CHKT10	8E85	388	386	
CKERR	8D6D	202	188	191
CKIM	00AE	33	79	
CLOKHI	A005	65	267	268
CLOKLO	A004	66	****	
CONFIG	89A5	40	247	
C1500	001F	32	82	
DDRDIG	A401	68	****	
DDRIN	A002	64	74	76
DDR0UT	A403	62	****	
DIG	A400	69	217	232
DT3E	8F00	451	****	
DUMPT	8E87	390	****	
DUMPT1	8EA8	407	395	410
DUMPT2	8ED7	432	425	458 460
DUMPT4	8F03	454	434	437
EAH	A64B	45	144	153 429 436
EAL	A64A	46	141	150 427 433
EOT	0004	29	446	448
EXIT	8D73	209	205	
EX10	8D7C	213	210	
FRAME	00FF	48	194	300
FRERR	8D61	194	****	
GETBIT	8F21	471	486	
GETTR	8DC9	261	239	242 265 282 286 288 307 308 314
HEX0UT	8F52	509	504	
HEX1	8F5B	514	512	
HF	8F73	531	529	537
HFCNT	8E1C	313	315	
HFP1	8F7A	534	535	
HWRONG	8CE2	127	105	
ID	A64E	42	96	98 415
KBITS	8E66	367	372	
KIMBIT	8F67	525	550	
LATCHL	A004	67	83	
LCERR	8D65	196	166	
LF	8F80	538	****	
LFP1	8F8D	544	545	
LF20	8F86	541	539	547
LOADT	8C78	73	212	
LOADT1	8C90	83	81	
LOADT2	8C93	84	89	106
SYMBOL	VALUE	LINE	DEFINED	CROSS-REFERENCES
LOADT4	8C96	85	90	
LOADT5	8CE6	130	97	100
LOADT6	8CC3	111	102	
LOADT7	8D36	171	118	138 179 181
LOADT8	8D4F	185	167	174
LOAD11	8CA3	92	87	
LSTCHR	002F	50	196	

SYMBOL	VALUE	LINE	DEFINED	CROSS-REFERENCES															
LT7H	8D0C	148	123	161	163														
LT7HA	8D1D	155	151																
LT7HB	8D30	165	154																
LT7HC	8D28	160	157																
LT8A	8D4F	186	****																
MARK8A	8E9A	399	404																
MARK8B	8E9C	400	402																
MODE	00FD	11	80	92	94	104	117	128	137	156	209	218							
			220	237	245	272	296	320	394	424	461	493							
NGEXIT	8D6F	204	195	197	200	301													
NHERR	8D69	199	172																
NOFLIP	8F40	489	478																
NONHEX	00FF	51	199																
OKEXIT	8D72	207	192	452															
OLD	00F9	9	264	266															
OUTBCX	8F43	492	419	421	428	430	456												
OUTBT	8F4A	499	****																
OUTBTC	8F4A	498	****																
OUTBTH	8F17	467	494																
OUTBTX	8F46	493	416	441	444	447	449												
OUTCHT	8F5D	521	400	462															
OUTCTX	8F13	461	408	413	440														
PACKT	8E3E	337	327																
PACKT1	8E4F	346	343																
PACKT2	8E55	351	354																
PACKT3	8E5F	358	318	338	340	342													
P1L	A64E	26	42																
P2H	A64D	25	43																
P2L	A64C	24	44																
P2SCR	829C	38	249																
P3H	A64B	23	45																
P3L	A64A	22	46																
RDASSY	8DF9	290	287																
RDBH10	8DEF	286	292																
RDBH90	8E04	296	285	289	297														
RDBITK	8E0F	306	238	368															
RDBYT	8E2C	324	171																
RDBYTH	8DE2	280	119	121	139	142	148	321											
RDBYTX	8E28	320	95	111	114	130	133	186	189										
RDCHT	8E61	365	273	324	330														
RDCHTX	8DDE	272	85	227															
RDRTN	8E5E	357	317	326	328														
SAH	A64D	43	420																
SAL	A64C	44	418																
START	8DB6	245	73	390															
SYBONE	8DB2	242	240																
SYB10	8DAC	239	****																
SYN	0016	30	88	224	228	407													
SYNBIT	8DA8	237	221																
SYNC	8D82	216	84																
SYNC10	8D98	226	231																
SYNC5	8D8D	221	225	229															
TAPIN	A000	63	262																
TAPOUT	A402	61	392	397	405	470	473	480											
TEMP1	A638	18	280	294	365	376	521	551											
TEMP2	A639	19	468	487	522	552													
TM1500	0047	31	475	482															
TPBIT	0008	34	472	479	532	542													
TPOUT	A402	60	61	526	533	543													
VIAACR	A00B	58	78																
VIAPCR	A00C	59	214	251															
WAITL0	8E14	308	309	311															
ZERCK	832E	39	248																

## NOTES



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SYNERTEK SYSTEMS CORPORATION

VIM REFERENCE MANUAL

MAY 1978